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WHEN IS A STOCHASTIC INTEGRAL A TIME CHANGE OF A DIFFUSION?

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Abstract

We give a necessary and sufficient condition (in terms of u, v, b, σ) that a time change of an n-dimensional Ito stochastic integral X_{+} on the form

 $dX_t = u(t, \omega)dt + v(t, \omega)dB_t$

has the same law as a diffusion Y_+ on the form

$$dY_t = b(Y_t)dt + \sigma(Y_t)dB_t.$$

As an application we prove a change of time formula for ndimensional Ito integrals. WHEN IS A STOCHASTIC INTEGRAL A TIME CHANGE OF A DIFFUSION?

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§1. The Main Result

In the following we will let $Y_t = Y_t^x$ denote an Ito diffusion, i.e. a (weak) solution in an open set $U \subset \mathbb{R}^n$ of the Ito stochastic differential equation

(1.1)
$$dY_{t} = b(Y_{t})dt + \sigma(Y_{t})dB_{t}, Y_{0} = x$$

where the functions b: $\mathbb{R}^n \to \mathbb{R}^n$ and $\sigma: \mathbb{R}^n \to \mathbb{R}^{n \times m}$ are continuous and $(B_t, \Omega, \mathcal{F}_t, P^X)$ denotes m-dimensional Brownian motion. And we will let $X_t = X_t^X$ denote an Ito stochastic integral

(1.2)
$$dX_{t} = u(t, \omega)dt + v(t, \omega)dB_{t}, X_{0} = x,$$

where $u(t,\omega) \in \mathbb{R}^n$, $v(t,\omega) \in \mathbb{R}^{n \times m}$ satisfy the usual conditions for existence of the stochastic integral: $u(t,\omega)$ and $v(t,\omega)$ are \mathcal{F}_t -adapted and

$$P^{O}\left\{\omega; \int_{0}^{t} |u(s,\omega)| + \sum_{ij=0}^{t} \int_{0}^{t} |v_{ij}(s,\omega)|^{2} ds^{\infty} \text{ for all } t\right\} = 1.$$

(See e.g. [4] or [7]). The time changes will consider are of the following form:

Let $c(t,\omega) \ge 0$ be an \mathcal{F}_t -adapted process. Define

(1.3)
$$\beta_{t} = \beta(t, \omega) = \int_{0}^{t} c(s, \omega) ds$$

We will say that β_t is a time change with time change rate $c(t,\omega)$. Note that β_t is also \mathcal{F}_t -adapted and for each ω the map $t \neq \beta_t$ is nondecreasing. Let $\alpha_t = \alpha(t,\omega)$ be the right continuous inverse of β_t :

$$(1.4) \qquad \alpha_t = \inf\{s; \beta_s > t\}$$

Then $\omega \rightarrow \alpha(t, \omega)$ is an $\{\mathcal{F}_s\}$ -stopping time for each t, since

$$\{\omega; \alpha(t,\omega) \leq s\} = \{\omega; t \leq \beta(s,\omega)\} \in \mathcal{F}_s.$$

We now ask the question: When does there exist a time change β_t as above such that $X_{\alpha_t} \sim Y_t$, i.e. X_{α_t} is identical in law to Y_t ? In β_t we give an answer to this question (Theorems 1-3) and in β_t we use this to prove a change of time formula for stochastic integrals.

Note that $\beta(\alpha_{+}) = t$ for all (t, ω) , so that

(1.5)
$$a'_t(\omega) = \frac{1}{c(\alpha_t, \omega)}$$
 for a.a $t \ge 0, \ \omega \in \Omega$.

Moreover,

$$\int_{0}^{t} c(\alpha_{r}, \omega) d\alpha_{r}^{\wedge} = \int_{0}^{\alpha} c(s, \omega) ds = \int_{0}^{t} dr$$

or

(1.6)
$$c(\alpha_t, \omega) d\hat{\alpha}_t = dt$$
, for each $\omega \in \Omega$,

where $d\alpha_t^{\Lambda}$ denotes the measure $d\alpha_t$ with the point masses corresponding to the discontinuities of α_+ taken out.

First we establish a useful measurability result. We let \mathcal{M}_t and \mathcal{N}_t denote the σ -algebras generated by $\{X_s; s \leq t\}$ and $\{Y_s; s \leq t\}$, respectively, and we define \mathcal{M}_{α_t} to be the σ -algebra in Ω generated by the functions $\omega \neq X_{\alpha_s}$; $s \leq t$.

We let $C_0^2(U)$ denote the twice continuously differentiable functions with compact support in U, and v^T denotes the transposed of the matrix v_{i} .

Lemma 1

Let $dX_t = u(t, \omega)dt + v(t, \omega)dB_t$, $c(t, \omega)$, α_t be as above. Then $(vv^T)(\alpha_t, \omega)a'_t$ is M_{α_+} -adapted

Proof.

By Ito's formula we have

$$X_{t}^{(i)}X_{t}^{(j)} = X_{0}^{(i)}X_{0}^{(j)} + \int_{0}^{t} X_{s}^{(i)}dX_{s}^{(j)} + \int_{0}^{t} X_{s}^{(j)}dX_{s}^{(i)} + \int_{0}^{t} (vv^{T})_{ij}(s,\omega)ds$$

Hence, if we put

$$H_{ij}(t,\omega) = X_{t}^{(i)} X_{t}^{(j)} - X_{0}^{(i)} X_{0}^{(j)} - \int_{0}^{t} X_{s}^{(i)} dX_{s}^{(j)} - \int_{0}^{t} X_{s}^{(j)} dX_{s}^{(j)}$$

then $H(t,\omega)$ is \mathcal{M}_t^{-} -adapted and we have

$$\int_{0}^{\alpha} t(vv^{T})(s,\omega)ds = H(\alpha_{t},\omega)$$

Therefore

$$(vv^{T})(\alpha_{t},\omega)\alpha_{t}' = \lim_{r \to 0} \frac{H(\alpha_{t},\omega)-H(\alpha_{t-r},\omega)}{r}$$

which shows that $(vv^T)(\alpha_t, \omega)\alpha'_t$ is \mathcal{M}_{α_t} -adapted.

Remarks

1) One may ask if it is also true that $u(\alpha_t, \omega)\alpha'_t$ is \mathcal{M}_{α_t} -adapted. However, the following example, which was pointed out to me by the referee, shows that this fails even in the case when $\alpha_+ = t$, v= 1, m = n = 1: Put.

$$u(t,\omega) = \begin{cases} \frac{B_1 - B_t}{1 - t} & \text{if } t < 1\\ 0 & \text{if } t \ge 1 \end{cases}$$

and define

$$\tilde{B}_{t} = -\int_{0}^{t} u(s,\omega)ds + B_{t}$$

Then \tilde{B}_{t} is a Brownian motion and

$$B_{t} = \int_{0}^{t} u(s, \omega) ds + \tilde{B}_{t},$$

but $u(t,\omega)$ is not \mathcal{F}_t -adapted.

2) The next example shows that it need <u>not</u> be the case that $v(\alpha_t, \omega)\alpha'_t$ is \mathcal{M}_{α_t} -adapted, even if $\alpha_t = t$: Choose $v(t, \omega)$ non-constant with the values ± 1 and independent of $\{B_t\}_{t \ge 0}$ (m=n=1). Define

$$d\tilde{B}_t = v(t, \omega) dB_t$$

Then \tilde{B}_t is a Brownian motion (see McKean [4], §2.9 and also Corollary 1 later in this article). Hence we have

$$dB_t = v(t, \omega) d\tilde{B}_t$$

but $v(t,\omega)$ is not \mathcal{F}_t -adapted.

Let \mathfrak{B} denote the Borel σ -algebra of subsets of $[0,\infty)$. For t>0 we define a measure Q_{α_+} on $\mathfrak{B} \times \mathfrak{F}$ by setting

$$Q_{\alpha_{t}}(f) = E^{x} \begin{bmatrix} \int f(s, \omega) ds \end{bmatrix}$$

if $f(s,\omega)$ is bounded and $\mathscr{B} \times \mathscr{F}$ -measurable. Let \mathscr{X} denote the σ -algebra in $[0,\infty) \times \Omega$ generated by the function $(s,\omega) \to X_s(\omega)$ and

let $\mathbb{E}_{\alpha_{t}}[g|\chi] = \mathbb{E}_{\alpha_{t}}[g|\chi]$ denote the conditional expectation of $g(s,\omega)$ wrt. \mathcal{X} and wrt. the measure $Q_{\alpha_{t}}$.

We can now state and prove the main result. First we consider the case when

(1.9)
$$\beta_{\infty} = \infty$$
 a.s. (i.e. $\alpha_{+} < \infty$ for all $t < \infty$ a.s.)

The general case will considered later in this section (Theorem 2).

Theorem 1.

Assume that (1.9) holds. Then the following 3 statements, (I), (II) and (III), are equivalent:

(I) (i)
$$\mathbb{E}_{\alpha_{t}}[u|X] = b(X)\mathbb{E}_{\alpha_{t}}[c|X]$$
 for all $t \ge 0$ and
(ii) $(vv^{T})(t,\omega) = c(t,\omega)(\sigma\sigma^{T})(X_{t})$ for a.a. $t\in(0,\alpha_{\omega}), \omega\in\Omega$.

(II) (i) $E_{\alpha_{t}}[u|X] = b(X)E_{\alpha_{t}}[c|X]$ for all $t \ge 0$ and (iii) $E_{\alpha_{t}}[vv^{T}|X] = \sigma\sigma^{T}(X)E_{\alpha_{t}}[c|X]$ for all $t \ge 0$

(III) $X_{\alpha_t} \sim Y_t$

Proof.

(1.10) $E^{x} \begin{bmatrix} \alpha \\ \beta \\ \omega(s,\omega)g(X_{s})ds \end{bmatrix} = E^{x} \begin{bmatrix} \alpha \\ \beta \\ \omega(s,\omega)g(X_{s})ds \end{bmatrix} = and$

(1.11)
$$E^{x}\left[\int_{0}^{\alpha} (vv^{T})(s,\omega)g(X_{s})ds\right] = E^{x}\left[\int_{0}^{\alpha} (\sigma\sigma^{T})(X_{s})g(X_{s})c(s,\omega)ds\right]$$

for all bounded functions g.

$(II) \implies (III):$

For $0 \le t \le \infty$ we define a bounded linear functional W_t on $C_b(U)$ (the bounded real continuous functions on U equipped with the sup norm) by

$$W_t f = E^X [f(X_{\alpha_t})]; f \in C_b(U).$$

Since α_t is a stopping time we have by Ito's formula (see e.g. [7], Lemma 7.8) if $f \in C_0^2(U)$:

$$W_{t}f = E^{x}[f(X_{0})] + E^{x}\left[\int_{0}^{\alpha} \left\{\sum_{i=1}^{u} u_{i}(s,\omega) \frac{\partial f}{\partial x_{i}}(X_{s}) + \frac{1}{2}\sum_{i,j}^{v} (vv^{T})_{ij}(s,\omega) \frac{d^{2}f}{\partial x_{i}\partial x_{j}}(X_{s})\right]ds$$

So if (II) holds we obtain, using (1.10), (1.11) and (1.6)

$$W_{t}f = f(x) + E^{x} \begin{bmatrix} \alpha \\ j \\ 0 \end{bmatrix} \begin{bmatrix} \alpha \\ i \end{bmatrix} b_{i}(x_{s}) \cdot \frac{\partial f}{\partial x_{i}}(x_{s}) + \frac{1}{2} \sum_{i,j} (\sigma\sigma^{T})_{ij}(x_{s}) \cdot \frac{\partial f}{\partial x_{i}}(x_{s}) + \frac{1}{2} \sum_{i,j} (\sigma\sigma^{T})_{ij}(x_{s}) + E^{x} \begin{bmatrix} \alpha \\ j \\ 0 \end{bmatrix} b_{i}(x_{\alpha}) \cdot \frac{\partial f}{\partial x_{i}}(x_{\alpha}) + \frac{1}{2} \sum_{i,j} (\sigma\sigma^{T})_{ij}(x_{\alpha}) \cdot \frac{\partial^{2} f}{\partial x_{i}\partial x_{j}}(x_{\alpha}) dr \end{bmatrix} = f(x) + E^{x} \begin{bmatrix} \alpha \\ j \\ 0 \end{bmatrix} b_{i}(x_{\alpha}) + E^{x} \begin{bmatrix} \alpha \\ j \\ 0 \end{bmatrix} b_{i}(x_{\alpha}) dr \end{bmatrix}$$

where $A = \sum_{i} b_{i}(\partial/\partial x_{i}) + \frac{1}{2} \sum_{ij} (\sigma\sigma^{T})_{ij}(\partial^{2}/\partial x_{i}\partial x_{j})$ is the generator of Y_{t} . Therefore

(1.12)
$$\frac{d}{dt} W_t f = W_t (Af) ; t > 0$$
$$W_0 f = f(x)$$

for all $f \in C_0^2(U)$. Similarly we obtain, if we put

$$V_{t}f = E^{X}[f(Y_{t})] , t \ge 0$$

that

(1.13)
$$\frac{d}{dt} V_t f = V_t (A_f) , t \ge 0$$
$$V_0 f = f(x)$$

for all $f \in C_0^2(U)$. Since the solution of the equations (1.12) and (1.13) is unique (see [6], Lemma 2.5) we conclude that

$$W_{+}f = V_{+}f$$
 for all $t \ge 0$, $f \in C_{0}^{2}(U)$.

Similarly we prove by induction on k that

$$E^{x}[f(X_{\alpha_{t}})g_{1}(X_{\alpha_{t}}) \dots g_{k}(X_{\alpha_{t_{k}}})] = E^{x}[f(Y_{t})g_{1}(Y_{t_{1}}) \dots g_{k}(Y_{t_{k}})]$$

for all t, $t_1, \ldots, t_k \ge 0$ and f, $g_1, \ldots; g_k \in C_0^2(U)$ by applying the above argument to the n(k+1) - dimensional processes

$$(X_{\alpha_t}, X_{\alpha_{t_1}}, \dots, X_{\alpha_{t_k}})$$
 and (Y_t, Y_t, \dots, Y_t) .

 $(III) \Rightarrow (I). Suppose X_{\alpha_t} \sim Y_t. Since Y_t is a Markov process wrt.$ $<math>\mathcal{N}_t$ it follows that X_{\alpha_t} is a Markov process wrt. \mathcal{M}_{α_t} and with generator A. Therefore, using Dynkin's formula (see e.g. [7], Th. 7.10) and (1.6) we have, for $f \in C_0^2(U)$:

$$(1.14) \quad E^{X}[f(X_{\alpha_{t}+h}) \mid \alpha_{t}] = E^{X_{\alpha_{t}}}[f(X_{\alpha_{h}})] = f(X_{\alpha_{t}}) + \\E^{X_{\alpha_{t}}}[\int_{0}^{h} \{\sum_{i} b_{i}(X_{\alpha_{t}}) \cdot \frac{\partial f}{\partial x_{i}}(X_{\alpha_{t}}) + \frac{1}{2}\sum_{i,j} (\sigma\sigma^{T})_{ij}(X_{\alpha_{t}}) \cdot \frac{d^{2}f}{\partial x_{i}\partial x_{j}}(X_{\alpha_{t}}) \}dr]$$
$$= f(X_{\alpha_{t}}) + E^{X_{\alpha_{t}}}[\int_{0}^{\alpha_{h}} \{\sum_{i} b_{i}(X_{s}) \cdot \frac{\partial f}{\partial x_{i}}(X_{s}) + \\\frac{1}{2}\sum_{i,j} (\sigma\sigma^{T})_{ij}(X_{s}) \cdot \frac{d^{2}f}{\partial x_{i}\partial x_{j}}(X_{s}) \}c(s,\omega)ds]$$

On the other hand, from Ito's formula we get as before

$$(1.15) \quad E^{X}[f(X_{\alpha_{t+h}})|\mathcal{M}_{\alpha_{t}}] = f(X_{\alpha_{t}}) + E^{X}[f(X_{\alpha_{t+h}}) - f(X_{\alpha_{t}})|\mathcal{M}_{\alpha_{t}}]$$
$$= f(X_{\alpha_{t}}) + E^{X}\begin{bmatrix}\alpha_{t+h}\\j\\\alpha_{t}\end{bmatrix} \{\sum_{i=1}^{n} u_{i}(s,\omega) \cdot \frac{\partial f}{\partial x_{i}}(X_{s}) + \frac{1}{2}\sum_{i,j} (vv^{T})_{ij}(s,\omega) \frac{\partial^{2} f}{\partial x_{i}\partial x_{j}}(X_{s})\}ds[\mathcal{M}_{\alpha_{t}}],$$

and a similar formula, denoted by (1.15), if we replace α_t by 0. Comparing (1.14) and (1.15) for $f(x_1, \ldots, x_n) = \exp(i(\lambda_1 x_1 + \ldots + \lambda_n x_n))$ (where $i = \sqrt{-1}$) we see that (1.10) and (1.11) holds by putting t=0. Thus it remains to prove property (ii).

From (1.14) and (1.15) we conclude that if we fix i,j and put

$$F_{t}(\omega) = \int_{0}^{\alpha} (vv^{T})_{ij}(s,\omega) ds$$

then .

$$(\sigma\sigma^{T})_{ij}(X_{\alpha_{t}}) = \lim_{h \to 0} \frac{1}{h} E^{X_{\alpha_{t}}} [\int_{0}^{h} (\sigma\sigma^{T})_{ij}(X_{\alpha_{r}})dr]$$

(1.16)
$$= \lim_{h \to 0} \frac{1}{h} E^{X} [F_{t+h} - F_{t} | \mathcal{M}_{\alpha_{t}}] \text{ for all } t, \omega.$$

Choose a t>0 such that F'_t exists a.s. Let N be an integer. Define, for h>0,

$$G_{h}(\omega) = \frac{1}{h} (F_{t+h}(\omega) - F_{t}(\omega))$$

$$H_{h}(\omega) = \begin{cases} G_{h}(\omega) & \text{if } |G_{h}(\omega)| \leq N \\ -N & \text{if } G_{h}(\omega) < -N \\ N & \text{if } G_{h}(\omega) > N \end{cases}$$

and put

$$H_{0}(\omega) = \begin{cases} F'_{h}(\omega) & \text{if } |F'_{h}(\omega)| \leq N \\ -N & \text{if } F'_{h}(\omega) \leq -N \\ N & \text{if } F'_{h}(\omega) \geq N, \end{cases}$$

Then H_0 is measurable wrt. \mathfrak{M}_{α} by Lemma 1. By bounded convergence we have

(1.17)
$$\lim_{h \to 0} E^{x} [H_{h} | \mathcal{M}_{\alpha}] = E^{x} [\lim_{h \to 0} H_{h} | \mathcal{M}_{\alpha}] = H_{0} \quad \text{a.s.}$$

Put $W = \{\omega; |F_{t}(\omega)| \leq \frac{1}{2}N\} \in \mathcal{M}_{\alpha_{t}}$

Choose $\omega \in W$. Then there exists $h(\omega) > 0$ such that

$$h < h(\omega) \Rightarrow |G_h(\omega)| \leq N$$
 i.e. $G_h(\omega) = H_h(\omega)$.

.

We want to conclude that

(1.18)
$$\lim_{h \to 0} \mathbb{E}^{X}[G_{h}|\mathcal{M}_{\alpha_{t}}] = \lim_{h \to 0} \mathbb{E}^{X}[H_{h}|\mathcal{M}_{\alpha_{t}}]$$

for a.a $\omega \in W$.

To obtain this write

$$E^{X}[f|M_{\alpha_{t}}](\omega) = \int f(\eta)dQ_{\omega}(\eta)$$
, for a.a. $\omega \in \Omega$.

where Ω_{ω} is a conditional probability distribution of P given \mathcal{M}_{α_t} . (See Stroock and Varadhan [8], Theorem 1.16) Let

$$V(\omega) = \bigcap \{ V \in \mathcal{M}_{\alpha}; \omega \in V \} \in \mathcal{M}_{\alpha}_{t}$$

be the $\mathcal{M}_{\alpha}^{\alpha}$ -atom containing ω .

Since

$$Q_{\omega}(V(\omega)) = 1$$
 for a.a. ω

([8], Theorem 1.18) and $V(\omega) \subset W$ for all $\omega \in W$ (since $W \in \mathcal{M}_{\alpha}$), we have for a.a. $\omega \in W$ and $h < h(\omega)$

$$E^{\mathbf{X}}[G_{\mathbf{h}}|\mathcal{M}_{\alpha_{t}}](\omega) = \int_{W} G_{\mathbf{h}} d\Omega_{\omega} = \int_{W} H_{\mathbf{h}}(\omega) d\Omega_{\omega} = E^{\mathbf{X}}[H_{\mathbf{h}}|\mathcal{M}_{\alpha_{t}}]$$

and (1.18) follows.

Combining (1.17) and (1.18) we obtain that

$$\lim_{h \to 0} E^{X}[G_{h}|\mathcal{M}_{\alpha_{t}}] = F_{t} \qquad \text{a.s. in } W$$

And since N was arbitrary we conclude from (1.16)

(1.19)
$$(\sigma\sigma^{T})_{ij}(X_{\alpha_{t}}) = (vv^{T})_{ij}(\alpha_{t},\omega)\alpha_{t}$$
 for a.a. t, ω

or

(1.20)
$$(vv^{T})_{ij}(\alpha_{t},\omega) = c(\alpha_{t},\omega)(\sigma\sigma^{T})_{ij}(X_{\alpha_{t}})$$
 for a.a. t,ω .

Moreover, if we define

(1.21)
$$F_{t}(\omega) = \lim_{h \to 0} \frac{1}{h} (F_{t+h} - F_{t})$$
 for all t, ω ,

then using (1.15) and Fatou's lemma we get

$$F_{t}(\omega) = E^{X}[F_{t}|\mathcal{M}_{\alpha_{t}}] \leq \frac{\lim h}{h \neq 0} \frac{1}{h} E^{X}[F_{t+h}-F_{t}|\mathcal{M}_{\alpha_{t}}]$$

(1.22) =
$$(\sigma\sigma^{T})_{ij}(X_{\alpha_{t}}) < \infty$$
 for all t, ω

Thus $t \neq F_t(\omega)$ is absolutely continuous for each ω . Therefore $(vv^T)_{ij}(s,\omega) = 0$ a.e. on each s-interval where $s \neq \beta(s,\omega)$ is constant i.e. where $s \neq c(s,\omega)$ is 0 a.e. and, by (1.6)

$$(vv^{T})_{ij}(\alpha_{r},\omega)d\alpha_{r} = (\sigma\sigma^{T})_{ij}(x_{\alpha_{r}})dr = (\sigma\sigma^{T})_{ij}(x_{\alpha_{r}})c(\alpha_{r},\omega)d\alpha_{r}$$

This is equivalent to saying that.

$$\int_{0}^{\alpha} t (vv^{T})_{ij}(s,\omega) ds = \int_{0}^{\alpha} (\sigma\sigma^{T})_{ij}(x_{s})c(s,\omega) ds$$

for all t, ω . Thus (ii) holds and the proof of Theorem 1 is complete.

<u>Remark</u>. Consider the more general situation when Y_t is not ssumed to be a diffusion, but just a stochastic integral of the same type as X_+ :

(1.1)
$$dY_{+} = e(t, \omega)dt + f(t, \omega)dB_{+}, \quad Y_{0} = x.$$

It is natural to ask if one can find conditions on the coefficients in order that $X_{\alpha_{+}} \sim Y_{t}$ in case.

We end this section by considering the case when we do not assume that (1.9) holds, i.e. we allow $\beta_{\infty} < \infty$. This case will be a special case of the following situation: Let

$$X_{t} = X_{t}^{x}(\omega) = x + \int_{0}^{t} u(s,\omega)ds + \int_{0}^{t} v(s,\omega)dB_{t}; \quad 0 < t < \tau$$

be a stochastic integral in an open set $W \subset U \subset \mathbb{R}^n$, where τ is an \mathfrak{F}_t -stopping time such that $\tau < \tau_W$, the first exit time from W of X_t . The probability law of X_t starting at x, \overline{P}^x , is defined by

$$\bar{P}^{x}[X_{t_{1}\wedge\tau}\in F_{1},\ldots,X_{t_{k}\wedge\tau}\in F_{k}] = P^{0}[X_{t_{1}\wedge\tau}^{x}\in F_{1},\ldots,X_{t_{k}\wedge\tau}^{x}\in F_{k}],$$

and \overline{E}^{X} denotes integration wrt. \overline{P}^{X} . Suppose Y_{t} is as before and let $\overset{A}{P}^{X}$ denote the probability law of X_{t} starting at x. Then we say that X_{t} is a time change of Y_{t} (with time change rate $c(t,\omega)$) if the process Z_{t} defined by

(1.23)
$$Z_{t} = \begin{cases} X_{\alpha_{t}} & ; & 0 \leq t < \beta_{\tau} \\ Y_{t-\beta_{\tau}} & ; & t > \beta_{\tau} \end{cases}$$

with probability law $\tilde{P}^{\mathbf{X}}$ defined by

 $\tilde{\mathbf{E}}^{\mathbf{X}}[\mathbf{f}_{1}(\mathbf{Z}_{t_{1}})\cdots \mathbf{f}_{k}(\mathbf{Z}_{t_{k}})\cdot \boldsymbol{\chi}_{\{t_{j}\leq\beta_{\tau}\leq t_{j+1}\}}] = \mathbf{E}^{\mathbf{X}}[\mathbf{f}_{1}(\mathbf{X}_{\alpha_{t_{1}}}^{\mathbf{X}})\cdots \mathbf{f}_{j}(\mathbf{X}_{\alpha_{t_{j}}}^{\mathbf{X}})\cdot$

(1.24)
$$f_{j+1}(Y_{t_{j+1}-\beta_{\tau}}^{\chi_{\tau}})\cdots f_{k}(Y_{t_{k}-\beta_{\tau}}^{\chi_{\tau}}) \cdot \chi_{\{t_{j}<\beta_{\tau}< t_{j+1}\}}$$

coincide in law with Y_t for every $x \in W$. (For simplicity we suppress the superscript x in what follows) Then question when X_t is a time change of Y_t can now by given an answer similar to Theorem 1, except that in this case the measure Q_{α} must be modified to the measure $Q_{\alpha} t^{\Lambda \tau}$ defined by

$$Q_{\alpha_{t}^{\wedge \tau}}(f) = E^{x} \begin{bmatrix} \alpha_{t}^{\wedge \tau} \\ \int f(s, \omega) ds \end{bmatrix}$$

if $f \ge 0$ is $\mathscr{B} \times \mathfrak{F}$ -measurable. The corresponding conditional expectation is denoted by $\mathbb{E}_{\alpha_{\perp} \wedge \tau}[\mid]$.

Theorem 2. The following are equivalent:

(A) $\begin{array}{l} E_{\alpha_{t}\wedge\tau}[u|X] = b(X)E_{\alpha_{t}\wedge\tau}[c|X] \quad \text{for all } t \ge 0 \quad \text{and} \\ (vv^{T})(t,\omega) = c(t,\omega)(\sigma\sigma^{T})(X_{t}) \quad \text{for a.a. } t, \omega_{\tau} \text{such that } t < \beta_{\tau}. \end{array}$ (B) X_{t} is a time change of Y_{t} , with time change rate $c(t,\omega)$.

<u>Proof.</u> (A) => (B): We proceed as in the proof of (II) => (III) in Theorem 1, except that now we put

$$W_{t}f = \tilde{E}[f(Z_{t})]; \quad f \in C_{0}^{2}(U), t \ge 0.$$

Then by Ito's formula we get

$$\tilde{E}[f(Z_{t}) \cdot \chi_{\{t < \beta_{\tau}\}}] = \tilde{E}[f(x) \cdot \chi_{\{t < \beta_{\tau}\}}] + \tilde{E}[\int_{0}^{\alpha_{t}} (\nabla f)^{T}(X_{s}) \vee (s, \omega) dB_{s} \cdot \chi_{\{t < \beta_{\tau}\}}] + \\ \tilde{E}[\int_{0}^{\alpha_{t}} \{\sum_{i} u_{i}(s, \omega) \frac{\partial f}{\partial x_{i}}(X_{s}) + \sum_{i,j} (\nabla v^{T})_{ij}(s, \omega) \frac{\partial^{2} f}{\partial x_{i} \partial x_{j}}(X_{s}) ds \cdot \chi_{\{t < \beta_{\tau}\}}]$$

Similarly

$$\widetilde{E}[f(Z_{t}) \circ \chi_{\{t \ge \beta_{\tau}\}}] = E[f(Y_{t-\beta_{\tau}}^{\chi_{\tau}}) \circ \chi_{\{t \ge \beta_{\tau}\}}]$$

$$= E[f(X_{\tau}) \circ \chi_{\{t \ge \beta_{\tau}\}}] + E[\int_{0}^{t-\beta_{\tau}} (Af)(Y_{u}^{\chi_{\tau}})du \circ \chi_{\{t \ge \beta_{\tau}\}}]$$

$$(1.26) = E[f(X_{\tau}) \circ \chi_{\{t \ge \beta_{\tau}\}}] + E[\int_{\beta_{\tau}}^{t} (Af)(Y_{u-\beta_{\tau}}^{\chi_{\tau}})dv \circ \chi_{\{t \ge \beta_{\tau}\}}]$$

By Ito's formula we get

$$\mathbb{E}[f(X_{\tau}) \circ \chi_{\{t \geq \beta_{\tau}\}}] = \mathbb{E}[f(x) \circ \chi_{\{t \geq \beta_{\tau}\}}] + \mathbb{E}[\int_{0}^{\tau} (\nabla f)^{T}(X_{s}) \vee (s, \omega) dB_{s} \circ \chi_{\{t \geq \beta_{t}\}}]$$

(1.27)

+
$$E\left[\int_{0}^{\tau} \left\{\sum_{i} u_{i}(s,\omega) \cdot \frac{\partial f}{\partial x_{i}}(x_{s}) + \sum_{i,j} (vv^{T})_{ij}(s,\omega) \cdot \frac{\partial^{2} f}{\partial x_{i} \partial x_{j}}(x_{s})\right\} ds \cdot \chi \{t \ge \beta_{\tau}\}\right]$$

so by adding (1.26) and (1.27) we obtain

$$\tilde{E}[f(Z_{t})] = f(x) + E\begin{bmatrix} \alpha_{t}^{\wedge \tau} & (\nabla f)^{T}(X_{s}) \vee (s, \omega) dB_{s} \end{bmatrix} + E\begin{bmatrix} \alpha_{t}^{\wedge \tau} & (\nabla f)^{T}(X_{s}) \vee (s, \omega) \cdot \frac{\partial^{2} f}{\partial x_{i} \partial x_{j}} (X_{s}) + \sum_{i,j} (\nabla V^{T})_{ij}(s, \omega) \cdot \frac{\partial^{2} f}{\partial x_{i} \partial x_{j}} (X_{s}) \} ds (1.28) + E\begin{bmatrix} t & X_{\tau} & (X_{\tau}) & (Y_{v-\beta_{\tau}}) dv \cdot \chi_{\{t>\beta_{\tau}\}} \end{bmatrix}.$$

Since $\alpha_t \wedge \tau$ is a stopping time the second term on the right of (1.28) is 0 and by (A) the third term is the same as

$$E\begin{bmatrix} \alpha_{\tau}^{\wedge\tau} \\ Af \end{pmatrix} (X_{s})c(s,\omega)ds] = E\begin{bmatrix} \alpha_{t} \\ Af \end{pmatrix} (X_{s})c(s,\omega)ds \cdot \chi \{t < \beta_{\tau}\}]$$

+
$$E\begin{bmatrix} \tau \\ (Af)(X_{s})c(s,\omega)ds \cdot \chi \{t > \beta_{\tau}\}]$$

(1.29)
$$= E\begin{bmatrix} t \\ (Af)(X_{\alpha})dr \cdot \chi \{t < \beta_{\tau}\}] + E\begin{bmatrix} \beta \\ \tau \\ (Af)(X_{\alpha})dr \cdot \chi \{t > \beta_{\tau}\}]$$

(Note that

(1.30)
$$\int_{0}^{\tau} (Af)(X_{s})c(s,\omega)ds = \int_{0}^{\alpha_{\beta_{\tau}}} (Af)(X_{s})c(s,\omega)ds,$$

since $c(s,\omega) = 0$ for a.a. $s \in (\tau, \alpha_{\beta_{\tau}})$. Substituting (1.29) in (1.28) and comparing with (1.24) we conclude that

$$\tilde{E}[f(Z_t)] = f(x) + \tilde{E}[\int_{0}^{t} (Af)(Z_s) ds].$$

Thus we have obtained (1.11) and the rest of the proof of (i) => (ii) follows the proof of (II) => (III) in Theorem 1.

<u>(B) => (A)</u>: We reverse the argument just given. If Z_t is a Markov process with generator A we get by the Dynkin formula

$$\widetilde{E}(f(Z_{t})] = f(x) + \widetilde{E}[\int_{0}^{t} (Af)(Z_{s})ds]$$

$$= f(x) + \widetilde{E}[\int_{0}^{t\wedge\beta\tau} (Af)(Z_{s})ds] + \widetilde{E}[\int_{t\wedge\beta\tau}^{t} (Af)(Z_{v})dv]$$

$$= f(x) + E[\int_{0}^{t\wedge\beta\tau} (Af)(X_{\alpha})dr] + \widetilde{E}[(\int_{\beta\tau}^{t} (Af)(Z_{v})dv)\chi_{\{t>\beta\tau\}}]$$

$$= f(x) + E[\int_{0}^{\alpha} (Af)(X_{s})c(s,\omega)ds] + E[(\int_{\beta\tau}^{t} (Af)(Y_{v-\beta\tau})dv)\cdot\chi_{\{t>\beta\tau\}}]$$

$$(1.31) = f(x) + E[\int_{0}^{\alpha} (Af)(X_{s})c(s,\omega)ds] + E[(\int_{\beta\tau}^{t} (Af)(Y_{v-\beta\tau})dv)\cdot\chi_{\{t>\beta\tau\}}]$$

Comparing (1.28) and (1.31) we conclude that

$$E\begin{bmatrix} \sigma_{t}^{\Lambda\tau} & \sigma_{t}^{\Lambda\tau} \\ \int u(s,\omega)g(X_{s})ds \end{bmatrix} = E\begin{bmatrix} \int b(X_{s})c(s,\omega)g(X_{s})ds \end{bmatrix}$$

and

$$E\begin{bmatrix}\alpha_{t}^{\wedge\tau} (vv^{T})(s,\omega)g(X_{s})ds] = E\begin{bmatrix}\alpha_{t}^{\wedge\tau} (\sigma\sigma^{T})(X_{s})c(s,\omega)g(X_{s})ds\end{bmatrix}$$

for all bounded functions g.

This proves the first identity in (A). To obtain the second identity we proceed as in the proof of (III) => (I) in Theorem 1: Let $\tilde{m_t}$ denote the σ -algebra generated by {Z_s; s<t}. Then by the strong Markov property we have for all t, ω

(1.32)
$$\lim_{h \to 0} \frac{1}{h} \tilde{E}[f(z_{t+h}) - f(z_t) | \tilde{m}_t] = \lim_{h \to 0} \frac{1}{h} \tilde{E}^t[f(z_h) - f(z_0)] = (Af)(z_t)$$

On the other hand, from the general calculation in (1.28) we get $\lim_{h \to 0} \frac{1}{h} \tilde{E}[f(Z_{t+h}) - f(Z_{t}) | \tilde{m}_{t}] =$ $\lim_{h \to 0} \frac{1}{h} \tilde{E}[\int_{\alpha_{t} \wedge \tau}^{\alpha_{t} + h^{\wedge \tau}} \{\sum_{i} u_{i}(s, w) \cdot \frac{\partial f}{\partial x_{i}}(x_{s}) + \sum_{ij} (vv^{T})_{ij}(s, \omega) \cdot \frac{\partial^{2} f}{\partial x_{i} \partial x_{j}}(x_{s}) \} ds | \tilde{m}_{t}]$ $\lim_{h \to 0} \frac{1}{h} \tilde{E}[\int_{t}^{t+h} (Af) (X_{v-\beta_{\tau}}) dv \cdot \chi_{\{t > \beta_{\tau}\}} | \tilde{m}_{t}] \qquad (1.33)$

Applying this to the function $f(x_1, \dots, x_n) = x_1 x_1$, we get by combining (1.32) and (1.33):

$$(\sigma\sigma^{T})_{ij}(z_{t}) = \lim_{h \to 0} \frac{1}{h} E \left[\int_{\alpha_{t}}^{\alpha_{t}+h} (vv^{T})_{ij}(s,\omega) ds \cdot \chi_{\{t < \beta_{\tau}\}} | \tilde{\mathcal{M}}_{t} \right]$$

+
$$\lim_{h \to 0} \frac{1}{h} \tilde{E} \left[\int_{t}^{t+h} (\sigma\sigma^{T}_{ij})(z_{v}) dv \cdot \chi_{\{t > \beta_{\tau}\}} | \tilde{\mathcal{M}}_{t} \right]$$

=
$$(vv^{T})_{ij}(\alpha_{t},\omega) \alpha_{t}' E \left[\chi_{\{t > \beta_{\tau}\}} | \tilde{\mathcal{M}}_{t} \right] + (\sigma\sigma^{T})_{ij}(z_{t}) \cdot E \left[\chi_{\{t > \beta_{\tau}\}} | \tilde{\mathcal{M}}_{t} \right],$$

by the same argument as in the proof of (1.19).

Hence

$$(1.34) \quad (\sigma\sigma^{T})_{ij}(z_{t}) \mathbb{E}[\chi_{\{t < \beta_{\tau}\}} | \tilde{\mathcal{M}}_{t}] = (vv^{T})_{ij} \alpha_{t}^{'} \mathbb{E}[\chi_{\{t > \beta_{\tau}\}} | \tilde{\mathcal{M}}_{t}]$$

Put $B = \{\omega; t < \beta_{\tau}\}$ and let

$$A_0 = \{\omega; E[\chi_B | \tilde{\mathcal{M}}_t] = 0\} \in \tilde{\mathcal{M}}_t.$$

Then

$$P(B\cap A_0) = \int_{A_0} \chi_B \circ dP = \int_{A_0} E[\chi_B | \widetilde{m}_t] dP = 0,$$

so

$$E[\chi_{B}|\tilde{\mathcal{M}}_{t}] > 0$$
 a.s. on B

Therefore we can conclude from (1.34) that for all t>0

$$(vv^{T})_{ij}(\alpha_{t}, \omega) = c(\alpha_{t}, \omega)(\sigma\sigma^{T})_{ij}(x_{\alpha_{t}})$$

for a.a. ω s.t. $t < \beta_{\tau}(\omega)$.

Thus we obtain the same conclusion (I) as in Theorem 1, except that it is only valid for a.a. t,ω such that $t < \beta_{\tau}(\omega)$. That completes the proof of Theorem 2.

Corollary 1. Suppose

$$u(t,\omega) = c(t,\omega)b(X_t)$$
 and $(vv^T)(t,\omega) = c(t,\omega)(\sigma\sigma^T)(X_t)$

for a.a. t, ω sucht that $t < \beta_{\tau}$. Then X_t is a time change of Y_t , with time change rate $c(t, \omega)$. Theorem 2 allows us to extend the characterization of Markovian path-preserving functions given in Csink and Øksendal [1] to the case when the time change β_t is not necessarily strictly increasing: - 17 -

<u>Theorem 3</u>. Let $dS_t = a(S_t)dt + \gamma(S_t)dB_t$ and $dY_t = b(Y_t)dt + \sigma(Y_t)dB_t$ be Ito diffusions on open sets $G \subset \mathbb{R}^p$ and $U \subset \mathbb{R}^n$, respectively. Denote the generators of S_t and Y_t by \overline{A} and A, respectively. Let $\phi: G \neq U$ be a C^2 function. Then the following are equivalent:

(1) There exists a continuous function $\lambda \ge 0$ on G such that

(1.35) $\overline{A}[fo\phi] = \lambda A[f] \circ \phi$ for all $f \in C^2(U)$

(2) For each open set D with $\overline{D} \subset G$ the stochastic integral $\phi(S_t)$, $t \leq \tau$ is a time change of X_t , with time change rate $\lambda(S_t)$ (in the sense of (1.23)-(1.24)).

<u>Proof</u>. By the Ito formula we have that $X_{t} = \phi(S_{t})$, $t < \tau_{W}$, satisfies

$$dx_{t}^{(k)} = (A\phi_{k})(S_{t})dt + \nabla\phi_{k}^{T}(S_{t})\gamma(S_{t})dB_{t}, \quad k=1,\ldots,m ,$$

where $X_t^{(k)}$ is component no. k of X_t . Therefore by Theorem 2 (2) holds if and only if

(1.36)
$$E_{\alpha_{t} \wedge \tau} [A\phi_{k}(S_{t}) | X] = b_{k}(X) E_{\alpha_{t} \wedge \tau} [\lambda(S_{t}) | X]$$

and

$$(1.37) \qquad (\nabla \phi_{k}^{T} \gamma \gamma^{T} \nabla \phi_{l})(S_{t}) = \lambda(S_{t})(\sigma \sigma^{T})_{kl}(X_{t}) \quad ; \quad l \leq k, \quad l \leq m,$$

for a.a. t, ω such that t < β . Letting t+0 we se that equation (1.37) is equivalent to

$$(1.38) \qquad \nabla \phi_{k}^{T} \gamma \gamma^{T} \nabla \phi_{\ell}(x) = \lambda(x) (\sigma \sigma^{T})_{k\ell}(\phi(x)), \quad 1 \leq k, \quad \ell \leq m$$

for all x∈G.

Similarly we claim that (1.36) is equivalent to

$$(1.39) \qquad A\phi_{k}(x) = \lambda(x)b_{k}(\phi(x)) \qquad ; 1 \leq k \leq m, x \in G.$$

It is clear that (1.39) implies (1.36). Conversely, if (1.36) holds we consider two cases:

<u>Case 1</u>: x belongs to the S-fine interior D of N = {z; $\lambda(z)=0$ }; i.e. $\tau_N = \inf\{t>0; S_t \notin N\} > 0$ a.s. Since $\alpha_{t=0} = \lim_{t \neq 0} \alpha_t = \tau_N$ we then get from (1.36) that

$$K(x) = E^{x} \begin{bmatrix} \tau_{N}^{\wedge \tau} \\ (A\phi_{k})(S_{t}) dt \end{bmatrix} = 0 \quad \text{for all } x \in D.$$

Applying the characteristic operator \mathcal{M} of S_t to the function K we get (se [7], p.138)

$$0 = \mathcal{O}(K(x) = (A\phi_k)(x) \qquad \text{for all } x \in D,$$

so (1.39) holds in this case.

Case 2: $\tau_N = 0$ a.s. Then we have $\alpha_0 = 0$ a.s. and therefore from (1.36)

$$A\phi_{k}(x) = \lim_{t \neq 0} \frac{1}{E^{x}[\alpha_{t} \wedge \tau]} E^{x} [\int_{0}^{\alpha_{t} \wedge \tau} (A\phi_{k})(s_{r})dr]$$

$$= \lim_{t \neq 0} \frac{1}{E^{x}[\alpha_{t} \wedge \tau]} \cdot E^{x} \begin{bmatrix} \alpha_{t} \wedge \tau \\ 0 \end{bmatrix} \cdot \sum_{k=1}^{\alpha_{t} \wedge \tau} b_{k}(\phi(s_{r}))dr = \lambda(x)b_{k}(\phi(x)),$$

as claimed.

We now note that (1.38) and (1.39) are equivalent to requiring that

$$A[f \circ \phi] = \lambda A[f] \circ \phi$$

for all polynomials

$$f(x_1, \dots, x_n) = \sum_{i} c_i x_i + \sum_{i,j} d_{ij} x_i x_j$$

of degree < 2, and hence that (1.35) holds for all $f \in C^2(U)$.

<u>Remark</u>. It is natural to ask what happens if we allow a more general time change rate $c(t,\omega)$ (not necessarily of the form $\lambda(S_t)$) which makes $\phi(S_t)$ a time change of X_t . However, the argument above gives that if such a $c(t,\omega)$ exists, then as in (1.37)

$$(\nabla \phi_{k}^{T} \gamma \gamma^{T} \nabla \phi_{\ell})(S_{t}) = c(t, \omega)(\sigma \sigma^{T})_{k\ell}(X_{t}) \quad \text{for } l \leq k, \ \ell \leq m,$$

and so

$$c(t, \omega) = \lambda(S_t)$$

with

$$\lambda(\mathbf{x}) = \frac{(\nabla \phi_{\mathbf{k}}^{\mathrm{T}} \gamma \gamma^{\mathrm{T}} \nabla \phi_{\ell})(\mathbf{x})}{(\sigma \sigma_{\mathbf{k}\ell}^{\mathrm{T}})(\phi(\mathbf{x}))}$$

i.e. we have a time change of the type discussed in Theorem 3.

$\$. A TIME CHANGE FORMULA FOR ITO INTEGRALS

As an illustration we first use Theorem 1 to characterize the stochastic integrals which are time changes of Brownian motion. If u=0 the corresponding result without time change (and with time change if n=1) was first proved by McKean ([4], §2.9). The sufficiency of condition (2.1) has been proved by F. Knight [3] (in a martingale setting).

<u>Corollary 2</u>. Let X_t be the n-dimensional stochastic integral in (1.2). Then there exists a time change α_t as above with time change rate $c(t,\omega) > 0$ such that

 $X_{\alpha} \sim B_{t}$ (n-dimensional Brownian motion) if and only if

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(2.1)
$$E_{\alpha}[u|X] = 0 \text{ for all } t \text{ and } (vv^{T})(t,\omega) = c(t,\omega)I_{n}$$
for all a.a $t \ge 0$, a.a. $\omega \in \Omega$

where I_n is the n×n identity matrix.

Example 1. If X_{+} is a 2-dimensional process the form

$$dX_{+} = v(t, \omega) dB_{+}$$

where $v \in R^{2 \times 2}$ and B_t is 2-dimensional Brownian motion, then X_t is a conformal martingale if and only if

 $(vv^{T})(t,\omega) = \eta(t,\omega)I_{2}$ for some $\eta(t,\omega) > 0$.

(See [2]). Thus it follows from Corollary 2 that a conformal martingale is a change of time of Brownian motion (in \mathbb{R}^2). This was proved by Getoor and Sharpe ([2]), p. 292-293) and it follows from the result by Knight in [3].

A special case of Corollary 2 is the following:

<u>Corollary 3</u>. Let $c(t, \omega) \ge 0$ be given and let α_t correspond to c as before. Put

$$X_{t} = \int_{0}^{t} \sqrt{c(s,\omega)} dB_{s}$$

where B is n-dimensional Brownian motion. Then X is also an α t n-dimensional Brownian motion.

We now use this to prove that a time change of a stochastic integral is again a stochastic integral, but driven by a different Brownian motion \tilde{B}_t . First we construct \tilde{B}_t :

Lemma 2. Suppose $t \Rightarrow \alpha(t, \omega)$ is continuous, $\alpha(0, \omega) = 0$ for a.a

 ω . Fix t>0. For k = 1, 2,... put

$$t_{j} = \begin{cases} j \cdot 2^{-k} & \text{if } j \cdot 2^{-k} \leq t \\ t & \text{if } j \cdot 2^{-k} > t \end{cases}$$

and choose r_j such that $\alpha_{r_j} = t_j$. Suppose $f(s,\omega) \ge 0$ is \mathcal{F}_s -adapted and satisfies $P^0 \begin{bmatrix} t \\ 0 \end{bmatrix} f(s,\omega)^2 ds < \infty \end{bmatrix} = 1$

Then

(2.2)
$$\lim_{k \to \infty} \sum_{j}^{\alpha} f(\alpha_{j}, \omega) \Delta B = \int_{\alpha}^{\alpha} f(s, \omega) dB \qquad \text{a.s.,}$$

where $\alpha_j = \alpha_r$, $\Delta B_{\alpha} = B_{\alpha} - B_{\alpha}$ and the limit is in $L^2(\Omega, P^0)$.

Proof. For all k we hve

$$E[(\sum_{j} f(\alpha_{j}, \omega) \Delta B_{\alpha_{j}} - \int f(s, \omega) dB_{s})^{2}]$$

$$= \sum_{j} E[(\int_{\alpha_{j}}^{\alpha_{j}+1} (f(\alpha_{j}, \omega) - f(s, \omega)) dB_{s})^{2}]$$

$$= \sum_{j} E[\int_{\alpha_{j}}^{\alpha_{j}+1} (f(\alpha_{j}, \omega) - f(s, \omega))^{2} ds] = E[\int_{0}^{\alpha_{j}} (f(-f_{k})^{2} ds],$$

where $f_k(s,\omega) = \sum_j f(t_j,\omega)\chi[t_j,t_{j+1})$ (s) is the elementary approximation to f. (See [7], Ch. III). This implies (2.2) in the case when f is bounded and $t \neq f(t,\omega)$ is continuous, for a.a. ω . The proof in the general case follows by approximation in the usual way. (See Ch. III, Steps 1-3 in [7]).

The following result extends a 1-dimensional time change formula proved by Mckean ([4], §2.8).

Theorem 4. (Time change formula for Ito integrals)

Let (B_s, \mathcal{F}_s) be m-dimensional Brownian motion and $v(t, \omega) \in \mathbb{R}^{n \times m}$ as before. Suppose α_t satisfies the conditions in Lemma 2. Define

(2.3)
$$\tilde{B}_{t} = \lim_{k \to \infty} \sum_{j} \sqrt{c(a_{j}, \omega)} \Delta B_{\alpha j} = \int_{0}^{\alpha t} \sqrt{c(s, \omega)} dB_{s}$$

Then \tilde{B}_t is an (m-dimensional) $\mathcal{F}_{\alpha t}$ -Brownian motion (i.e \tilde{B}_t is a Brownian motion and \tilde{B}_t is a martingale wrt. $\mathcal{F}_{\alpha t}$) and

(2.4)
$$\int_{0}^{\alpha} t v(s,\omega) dB_{s} = \int_{0}^{t} v(\alpha_{r}, \omega) \cdot \sqrt{\alpha_{r}} d\tilde{B}_{r}, \text{ a.s. } P^{0}.$$

where $\alpha'_{r}(\omega)$ is the derivative of α_{r} wrt. r, so that

(2.5)
$$\alpha'_r(\omega) = \frac{1}{c(\alpha_r, \omega)}$$
 for a.a $r \ge 0$, $\omega \in \Omega$.

<u>Proof</u>. The existence of the limit in (2.3) and the second identity in (2.3) follows by applying Lemma 2 to the function

$$f(s,\omega) = \sqrt{c(s,\omega)}.$$

Then by Corollary 2 we have that \tilde{B}_t is an \mathcal{F}_{α} -Brownian motion. It remains to prove (2.4):

$$\int_{0}^{\alpha} v(s,\omega) dB_{s} = \lim_{k \to \infty} \sum_{j}^{c} v(\alpha_{j},\omega) \Delta B_{\alpha_{j}}$$
$$= \lim_{k \to \infty} \sum_{j}^{c} v(\alpha_{j},\omega) \sqrt{\frac{1}{c(\alpha_{j},\omega)}} \sqrt{\frac{1}{c(\alpha_{j},\omega)}} \Delta B_{\alpha_{j}}$$
$$= \lim_{k \to \infty} \sum_{j}^{c} v(\alpha_{j},\omega) \sqrt{\frac{1}{c(\alpha_{j},\omega)}} \Delta \tilde{B}_{j}$$

$$= \int_{0}^{t} v(\alpha_{r}, \omega) \sqrt{\frac{1}{c(\alpha_{r}, \omega)}} \Delta \tilde{B}_{r},$$

and the proof is complete.

We now apply Theorem 4 to the case when the stochastic integral X_t is an Ito diffusion

(2.6)
$$dX_{+} = a(X_{+})dt + \gamma(X_{+})dB_{+}$$

where a: $\mathbb{R}^n \to \mathbb{R}^n$, $\gamma: \mathbb{R}^n \to \mathbb{R}^{n \times m}$ are continuous.

<u>Corollary 4</u>. Let X_t be the Ito diffusion given by (2.6) and let $t \Rightarrow \alpha(t, \omega)$ be absolutely continuous, $\alpha(0, \omega) = 0$ for a.a. ω . Then X_{α} is a Markov process wrt. \mathcal{M}_{α} if and only if there exists a α_t function q: $\mathbb{R}^n \Rightarrow [0, \infty)$ such that

$$(2.7) \qquad c(t,\omega) = q(X_{+}(\omega))$$

for a.a. t < α_{ω} , $\omega \in \Omega$, and in that case

(2.8)
$$d(X_{\alpha_{t}}) = \frac{a(X_{\alpha_{t}})}{q(X_{\alpha_{t}})} dt + \frac{\gamma(X_{\alpha_{t}})}{q(X_{\alpha_{t}})} d\tilde{B}_{t}$$

where \tilde{B}_t is the f_{α}_t -Brownian motion from Theorem 4.

<u>Proof</u>. If (2.7) holds then (2.8) follows from Theorem 4. Hence χ_{α_t} is a weak solution of the stochastic differential equation (2.8) and therefore χ_{α_t} is a Markov process. Conversely, if χ_{α_t} is a Mar- α_t kov process wrt. \mathcal{M}_{α_t} then by the proof of (III)=>(I)(ii) in Theorem 1 we obtain

for a.a.
$$t < \alpha$$
 , $\omega \in \Omega$

i.e.

$$c(t,\omega) = q(X_{+})$$

 $(\gamma \gamma^{\mathrm{T}})(\mathrm{X}_{+}) = \mathrm{c(t, \omega)}(\sigma \sigma^{\mathrm{T}})(\mathrm{X}_{+})$

with

$$q(x) = \frac{(\gamma \gamma^{T})(x)}{(\sigma \sigma^{T})(x)} .$$

<u>Remark</u>. The last part of this proof does not require that α is absolutely continuous.

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