



Restoration of Well-Posedness of Infinite-Dimensional Singular ODE's via Noise

David Baños¹ · Martin Bauer² · Thilo Meyer-Brandis² · Frank Proske¹

Received: 26 October 2021 / Accepted: 8 February 2023
© The Author(s) 2023

Abstract

In this paper we aim at generalizing the results of A. K. Zvonkin (*That removes the drift*, 22, 129, 1974) and A. Y. Veretennikov (*Theory Probab. Appl.*, 24, 354, 1979) on the construction of unique strong solutions of stochastic differential equations with singular drift vector field and additive noise in the Euclidean space to the case of infinite-dimensional state spaces. The regularizing driving noise in our equation is chosen to be a locally non-Hölder continuous Hilbert space valued process of fractal nature, which does not allow for the use of classical construction techniques for strong solutions from PDE or semimartingale theory. Our approach, which does not resort to the Yamada-Watanabe principle for the verification of pathwise uniqueness of solutions, is based on Malliavin calculus.

Keywords Malliavin calculus · Fractional brownian motion · L^2 -compactness criterion · Strong solutions of SDEs · Irregular drift coefficient

Mathematics Subject Classification (2010) 60H10 · 60H15 · 60H50 · 35R15 · 35R60 · 34F05

The research is partially supported by the FINEWSTOCH (NFR-ISP) project.

✉ David Baños
davidru@math.uio.no

Martin Bauer
bauer@math.lmu.de

Thilo Meyer-Brandis
meyerbra@math.lmu.de

Frank Proske
proske@math.uio.no

¹ Department of Mathematics, University of Oslo,
Moltke Moes vei 35, P.O. Box 1053 Blindern, 0316 Oslo, Norway

² Department of Mathematics, LMU, Theresienstr. 39, D-80333, Munich, Germany

1 Introduction

The main objective of this paper is the construction of (unique) strong solutions of infinite-dimensional stochastic differential equations (SDEs) with a singular drift and additive noise. In fact, we want to derive our results from the perspective of a rather recently established theory of stochastic regularization (see [19] and the references therein) with respect to a new general method based on Malliavin calculus and another variational technique which can be applied to different types of SDEs and stochastic partial differential equations (SPDEs).

In order to explain the concept of stochastic regularization, let us consider the first-order ordinary differential equation (ODE)

$$\frac{d}{dt} X_t^x = b(t, X_t^x), \quad X_0 = x \in \mathcal{H}, \quad t \in [0, T] \quad (1)$$

for a vector field $b : [0, T] \times \mathcal{H} \rightarrow \mathcal{H}$, where \mathcal{H} is a separable Hilbert space with norm $\|\cdot\|_{\mathcal{H}}$.

Using Picard iteration, it is fairly straight forward to see that the ODE Eq. 1 has a unique (global) solution $(X_t^x)_{t \in [0, T]}$, if the driving vector field b satisfies a linear growth and Lipschitz condition, that is

$$\|b(t, x)\|_{\mathcal{H}} \leq C_1(1 + \|x\|_{\mathcal{H}})$$

and

$$\|b(t, x) - b(t, y)\|_{\mathcal{H}} \leq C_2 \|x - y\|_{\mathcal{H}}$$

for all t, x and y with constants $C_1, C_2 < \infty$.

However, well-posedness in the sense of existence and uniqueness of solutions may fail, if the vector field b lacks regularity, that is if e.g. b is not Lipschitz continuous. In this case, the ODE Eq. 1 may not even admit the existence of a solution in the case $\mathcal{H} = \mathbb{R}^d$.

On the other hand, the situation changes, if one integrates on both sides of the ODE (1) and adds a “regularizing” noise to the right hand side of the resulting integral equation.

More precisely, if $\mathcal{H} = \mathbb{R}^d$, well-posedness of the ODE Eq. 1 can be restored via regularization by a Brownian (additive) noise, that is by a perturbation of the ODE Eq. 1 given by the SDE

$$dX_t^x = b(t, X_t^x)dt + \varepsilon dB_t, \quad t \in [0, T], \quad X_0^x = x \in \mathbb{R}^d, \quad (2)$$

where $(B_t)_{t \in [0, T]}$ is a Brownian motion in \mathbb{R}^d and $\varepsilon > 0$.

If the vector field b is merely bounded and measurable, it turns out that the SDE Eq. 2 – regardless how small ε is – possesses a unique (global) strong solution, that is a solution $(X_t^x)_{t \in [0, T]}$, which as a process is a measurable functional of the driving noise $(B_t)_{t \in [0, T]}$. This surprising and remarkable result was first obtained by A. K. Zvonkin [41] in the one-dimensional case, whose proof, using PDE techniques, is based on a transformation (“Zvonkin-transformation”), that converts the SDE Eq. 2 into a SDE without drift part. Subsequently, this result was generalized by A. Y. Veretennikov [39] to the multi-dimensional case. Much later, that is 35 years later, Zvonkin’s and Veretennikov’s results were extended by G. Da Prato, F. Flandoli, E. Priola and M. Röckner [13] to the infinite-dimensional setting by using estimates of solutions of Kolmogorov’s equation on Hilbert spaces. In fact, the latter authors study mild solutions $(X_t)_{t \in [0, T]}$ to the SDE

$$dX_t = AX_t dt + b(X_t)dt + \sqrt{Q}dW_t, \quad t \in [0, T], \quad X_0 = x \in \mathcal{H},$$

where $(W_t)_{t \in [0, T]}$ is a cylindrical Brownian motion on \mathcal{H} , $A : D(A) \rightarrow \mathcal{H}$ a negative self-adjoint operator with compact resolvent, $Q : \mathcal{H} \rightarrow \mathcal{H}$ a non-negative definite self-adjoint

bounded operator and $b : \mathcal{H} \rightarrow \mathcal{H}$. Here, the authors prove for $b \in L^\infty(\mathcal{H}; \mathcal{H})$ under certain conditions on A and Q the existence of a unique mild solution, which is adapted to a completed filtration generated by $(W_t)_{t \in [0, T]}$. So restoration of well-posedness of the ODE Eq. 1 with a singular vector field is established via regularization by *both* the cylindrical Brownian noise $(W_t)_{t \in [0, T]}$ and A , which cannot be chosen to be the zero operator.

Other works in this direction in the infinite-dimensional setting based on different methods are e.g. A. S. Sznitman [38], A. Y. Pilipenko, M. V. Tantsyura [36] in connection with systems of McKean-Vlasov equations and G. Ritter, G. Leha [25] in the case of discontinuous drift vector fields of a rather specific form. We also refer to the references therein.

In this article, we aim at restoring well-posedness of singular ODE's by using a certain non-Hölder continuous additive noise of fractal nature. More specifically, we want to analyze solutions to the following type of SDE:

$$X_t^x = x + \int_0^t b(s, X_s^x) ds + \mathbb{B}_t, \quad t \in [0, T], \tag{3}$$

where the \mathcal{H} -valued regularizing noise $(\mathbb{B}_t)_{t \in [0, T]}$ is a stationary Gaussian process with locally non-Hölder continuous paths given by

$$\mathbb{B}_t = \sum_{k \geq 1} \lambda_k B_t^{H_k} e_k.$$

Here $\{\lambda_k\}_{k \geq 1} \subset \mathbb{R}$, $\{e_k\}_{k \geq 1}$ is an orthonormal basis of \mathcal{H} and $\{B^{H_k}\}_{k \geq 1}$ are independent one-dimensional fractional Brownian motions with Hurst parameters $H_k \in (0, \frac{1}{2})$, $k \geq 1$, such that

$$H_k \searrow 0$$

for $k \rightarrow \infty$.

Under certain (rather mild) growth conditions on the Fourier components b_k , $k \geq 1$, of the singular vector field $b : [0, T] \times \mathcal{H} \rightarrow \mathcal{H}$ (see Eqs. 22 and 23), which do not necessarily require that all b_k are equal (compare e.g. to [38]), we show in this paper the existence of a unique (global) strong solution to the SDE Eq. 3 driven by the non-Markovian process $(\mathbb{B}_t)_{t \in [0, T]}$.

Our approach for the construction of strong solutions to Eq. 3 relies on Malliavin calculus (see e.g. D. Nualart [32]) and another variational technique, which involves the use of spatial regularity of local time of finite-dimensional approximations of \mathbb{B}_t . In contrast to the above mentioned works (and most of other related works in the literature), the method in this paper is not based on PDE, Markov or semimartingale techniques. Furthermore, our technique corresponds to a construction principle, which is diametrically opposed to the commonly used Yamada-Watanabe principle (see e.g. [40]): Using the Yamada-Watanabe principle, one combines the existence of a weak solution to a SDE with pathwise uniqueness to obtain strong uniqueness of solutions. So

$$\boxed{\text{Weak existence}} + \boxed{\text{Pathwise uniqueness}} \Rightarrow \boxed{\text{Strong uniqueness}}.$$

This tool is in fact used by many authors in the literature. See e.g. the above mentioned authors or I. Gyöngy, T. Martinez [22], I. Gyöngy, N. V. Krylov [21], N. V. Krylov, M. Röckner [24] or S. Fang, T. S. Zhang [18], just to mention a few.

However, using our approach, verification of the existence of a strong solution, which is unique in law, provides strong uniqueness:

$$\boxed{\text{Strong existence}} + \boxed{\text{Uniqueness in law}} \Rightarrow \boxed{\text{Strong uniqueness}}.$$

See also H. J. Engelbert [17] in the finite-dimensional Brownian case regarding the latter construction principle.

In order to briefly explain our method in the case of time-homogeneous vector fields, we mention that we apply an infinite-dimensional generalization of a compactness criterion for square integrable Brownian functionals in $L^2(\Omega)$, which is originally due to G. Da Prato, P. Malliavin, and D. Nualart [32], to a double-sequence of strong solutions $\{(X_t^{d,\varepsilon})_{t \in [0, T]}\}_{d \geq 1, \varepsilon > 0}$ associated with the following SDE's

$$X_t^{d,\varepsilon} = x + \int_0^t b^{d,\varepsilon}(X_s^{d,\varepsilon}) ds + \mathbb{B}_t, \quad t \in [0, T]. \tag{4}$$

Here $\{b^{d,\varepsilon}\}_{d \in \mathbb{N}, \varepsilon > 0}$ is an approximating double-sequence of vector fields of the singular drift b , which are smooth and live on d -dimensional subspaces of \mathcal{H} .

The application of the above mentioned compactness criterion (for each fixed t), however, requires certain (uniform) estimates with respect to the Malliavin derivative D_t of $X_t^{d,\varepsilon}$ in the direction of a cylindrical Brownian motion. For this purpose, the Malliavin derivative $D : \mathbb{D}^{1,2}(\mathcal{H}) \rightarrow L^2([0, T] \times \Omega) \otimes \mathcal{L}_{HS}(\mathcal{H}, \mathcal{H})$ ($\mathbb{D}^{1,2}(\mathcal{H})$ is the space of \mathcal{H} -valued Malliavin differentiable random variables and $\mathcal{L}_{HS}(\mathcal{H}, \mathcal{H})$ is the space of Hilbert-Schmidt operators from \mathcal{H} to \mathcal{H}) in connection with a chain rule is applied to both sides of (4) and one obtains the following linear equation:

$$D_s X_t^{d,\varepsilon} = \int_s^t (b^{d,\varepsilon})'(X_u^{d,\varepsilon}) D_s X_u^{d,\varepsilon} du + \sum_{n \geq 1} \lambda_n K_{H_n}(t, s) \langle e_n, \cdot \rangle_{\mathcal{H}} e_n, \quad s < t, \tag{5}$$

where $(b^{d,\varepsilon})'$ is the derivative of $b^{d,\varepsilon}$, $\langle \cdot, \cdot \rangle_{\mathcal{H}}$ the inner product and K_H a certain kernel function defined for Hurst parameters $H_n \in (0, \frac{1}{2})$.

We remark here that this type of linearization based on a stochastic derivative D_t actually corresponds to the Nash-Moser principle, which is used for the construction of solutions of (non-linear) PDE's by means of linearization of equations via classical derivatives. See e.g. J. Moser [31].

In a next step we then can derive a representation of $D_s X_t^{d,\varepsilon}$ (under a Girsanov change of measure) in Eq. 5 which is not based on derivatives of $b^{d,\varepsilon}$ by using Picard iteration and the following variational argument:

$$\begin{aligned} \int_{t < s_1 < \dots < s_n < u} \kappa(s) D^\alpha f(\mathbb{B}_s^d) ds &= \int_{\mathbb{R}^{dn}} D^\alpha f(z) L_\kappa^n(t, z) dz \\ &= (-1)^{|\alpha|} \int_{\mathbb{R}^{dn}} f(z) D^\alpha L_\kappa^n(t, z) dz, \end{aligned}$$

where $\mathbb{B}_s^d := (B_{s_1}^{H_1}, \dots, B_{s_1}^{H_d}, \dots, B_{s_n}^{H_1}, \dots, B_{s_n}^{H_d})$ and $f : \mathbb{R}^{dn} \rightarrow \mathbb{R}$ is a smooth function with compact support. Here D^α stands for a partial derivative of order $|\alpha|$ with respect a multi-index α . Further, $L_\kappa^n(t, z)$ is a spatially differentiable local time of \mathbb{B}^d on a simplex scaled by non-negative integrable function $\kappa(s) = \kappa_1(s) \dots \kappa_n(s)$.

Then, using the latter we can verify the required estimates for the Malliavin derivative of the approximating solutions in connection with the above mentioned compactness criterion and we finally obtain (under some additional arguments) that for each fixed t

$$X_t^{d,\varepsilon} \rightarrow X_t \text{ in } L^2(\Omega)$$

for $\varepsilon \searrow 0, d \rightarrow \infty$, where $(X_t)_{t \in [0, T]}$ is the unique strong solution to Eq. 3.

Finally, let us also mention a series of papers, from which our construction method gradually evolved: We refer to the works [27–30] in the case of finite-dimensional Brownian

noise. See [20] in the Hilbert space setting in connection with Hölder continuous drift vector fields. In the case of SDEs driven by Lévy processes we mention [23]. Other results can be found in [1, 6] with respect to SDEs driven by fractional Brownian motion and related noise. See also [7] in the case of “skew fractional Brownian motion”, [5] with respect to singular delay equations and [8] in the case of Brownian motion driven mean-field equations.

We shall also point to the work of R. Catellier and M. Gubinelli [11], who prove existence and *path by path* uniqueness (in the sense of A. M. Davie [15]) of strong solutions of fractional Brownian motion driven SDEs with respect to (distributional) drift vector fields belonging to the Besov-Hölder space $B_{\infty,\infty}^\alpha$, $\alpha \in \mathbb{R}$. The approach of the authors is based inter alia on the theorem of Arzela-Ascoli and a comparison principle based on an average translation operator. In the distributional case, that is $\alpha < 0$, the drift part of the SDE is given by a generalized non-linear Young integral defined via the topology of $B_{\infty,\infty}^\alpha$. See also D. Nualart, Y. Ouknine [33] in the one-dimensional case.

The structure of our article is as follows: In Section 2 we introduce the mathematical framework of this paper. Further, in Section 3 we discuss some properties of the process \mathbb{B} . and weak solutions of the SDE Eq. 3. Section 4 is devoted to the construction of unique strong solutions to the SDE Eq. 3. In Section 5, examples of singular vector fields for which strong solutions exist are given. Finally, Appendices A, B and C contain, respectively, a compactness criterion, an integration by parts formula and some technical lemmas and estimates that will be used throughout the article.

Notation For the sake of readability we assume throughout the paper that $1 \leq T < \infty$ is a finite time horizon. We define \mathcal{H} to be an infinite-dimensional separable real-valued Hilbert space with scalar product $\langle \cdot, \cdot \rangle_{\mathcal{H}}$ and orthonormal basis $\{e_k\}_{k \geq 1}$. Denote by $\|\cdot\|_{\mathcal{H}}$ the induced norm on \mathcal{H} defined by $\|x\|_{\mathcal{H}} := \langle x, x \rangle_{\mathcal{H}}^{\frac{1}{2}}$, $x \in \mathcal{H}$. For every $x \in \mathcal{H}$ and $k \geq 1$ we denote by $x^{(k)} := \langle x, e_k \rangle_{\mathcal{H}}$ the projection onto the subspace spanned by e_k , $k \geq 1$. Loosely speaking we are referring to the subspace spanned by e_k , $k \geq 1$, as the k -th dimension. In line with this notation we denote the projection of the SDE Eq. 3 on the subspace spanned by e_k , $k \geq 1$, by $X^{(k)} := \langle X, e_k \rangle_{\mathcal{H}}$. Moreover we can write the SDE Eq. 3 as an infinite dimensional system of real-valued stochastic differential equations, namely

$$X_t^{(k)} = x^{(k)} + \int_0^t b_k(s, X_s) ds + \mathbb{B}_t^{(k)}, \quad t \in [0, T], \quad k \geq 1,$$

where b_k and $\mathbb{B}^{(k)}$ are the projections on the subspace spanned by e_k , $k \geq 1$, of b and \mathbb{B} , respectively. Note here that the function $b_k : [0, T] \times \mathcal{H} \rightarrow \mathbb{R}$ has still domain $[0, T] \times \mathcal{H}$. Furthermore, we define the truncation operator π_d , $d \geq 1$, which maps an element $x \in \mathcal{H}$ onto the first d dimensions, by

$$\pi_d x := \sum_{k=1}^d x^{(k)} e_k. \tag{6}$$

The truncated space $\pi_d \mathcal{H}$ is denoted by \mathcal{H}_d . We define the change of basis operator $\tau : \mathcal{H} \rightarrow \ell^2$ by

$$\tau x = \tau \sum_{k \geq 1} x^{(k)} e_k = \sum_{k \geq 1} x^{(k)} \tilde{e}_k, \tag{7}$$

where $\{\tilde{e}_k\}_{k \geq 1}$ is an orthonormal basis of ℓ^2 . It is easily seen that the operator τ is a bijection and we denote its inverse by $\tau^{-1} : \ell^2 \rightarrow \mathcal{H}$.

Further frequently used notation:

- Let $(\mathcal{X}, \mathcal{A}, \mu)$ denote a measurable space and $(\mathcal{Y}, \|\cdot\|_{\mathcal{Y}})$ a normed space. Then $L^2(\mathcal{X}; \mathcal{Y})$ denotes the space of square integrable functions X over \mathcal{X} taking values in \mathcal{Y} and is endowed with the norm

$$\|X\|_{L^2(\mathcal{X}; \mathcal{Y})}^2 = \int_{\mathcal{X}} \|X(\omega)\|_{\mathcal{Y}}^2 \mu(d\omega).$$

- The space $L^2(\Omega, \mathcal{F})$ denotes the space of square integrable random variables on the sample space Ω measurable with respect to the σ -algebra \mathcal{F} .
- We define $\mathbb{B}^x := x + \mathbb{B}$.
- For any vector u we denote its transposed by u^\top .
- We denote by Id the identity operator.
- The Jacobian of a differentiable function is denoted by ∇ .
- For any multi-index α of length d and any d -dimensional vector u we define $u^\alpha := \prod_{i=1}^d u_i^{\alpha_i}$.
- For two mathematical expressions $E_1(\theta), E_2(\theta)$ depending on some parameter θ we write $E_1(\theta) \lesssim E_2(\theta)$, if there exists a constant $C > 0$ not depending on θ such that $E_1(\theta) \leq CE_2(\theta)$.
- Let A be some countable set. Then we denote by $\#A$ its cardinality.

2 Preliminaries

2.1 Shuffles

Let m and n be two integers. We denote by $\mathcal{S}(m, n)$ the set of *shuffle permutations*, i.e. the set of permutations $\sigma : \{1, \dots, m+n\} \rightarrow \{1, \dots, m+n\}$ such that $\sigma(1) < \dots < \sigma(m)$ and $\sigma(m+1) < \dots < \sigma(m+n)$. Equivalently we denote for integers k and n by $\mathcal{S}(k; n)$ the set of shuffle permutations of k sets of size n , i.e. the set of permutations $\sigma : \{1, \dots, k \cdot n\} \rightarrow \{1, \dots, k \cdot n\}$ such that $\sigma(m \cdot n + 1) < \dots < \sigma((m+1) \cdot n)$ for all $m = 0, \dots, k-1$. Furthermore the n -dimensional simplex Δ^n of the interval (s, t) is defined by

$$\Delta_{s,t}^n := \{(u_1, \dots, u_n) \in [0, T]^n : s < u_1 < \dots < u_n < t\}.$$

Note that the product of two simplices can be written as

$$\Delta_{s,t}^m \times \Delta_{s,t}^n = \bigcup_{\sigma \in \mathcal{S}(m,n)} \{(w_1, \dots, w_{m+n}) \in [0, T]^{m+n} : w_\sigma \in \Delta_{s,t}^{m+n}\} \cup \mathfrak{N}, \tag{8}$$

where the set \mathfrak{N} has Lebesgue measure zero and w_σ denotes the shuffled vector $(w_{\sigma(1)}, \dots, w_{\sigma(m+n)})$. For the sake of readability we denote throughout the paper the integral over the simplex $\Delta_{s,t}^n$ of the product of integrable functions $f_i : [0, T] \rightarrow \mathbb{R}$, $i = 1, \dots, n$, by

$$\int_{\Delta_{s,t}^n} \prod_{j=1}^n f_j(u_j) du := \int_s^t \int_{u_1}^t \dots \int_{u_{n-1}}^t \prod_{j=1}^n f_j(u_j) du_n \dots du_2 du_1.$$

Due to Eq. 8, we get for integrable functions $f_i : [0, T] \rightarrow \mathbb{R}$, $i = 1, \dots, m+n$, that

$$\int_{\Delta_{s,t}^m} \prod_{j=1}^m f_j(u_j) du \int_{\Delta_{s,t}^n} \prod_{j=m+1}^{m+n} f_j(u_j) du = \sum_{\sigma \in \mathcal{S}(m,n)} \int_{\Delta_{s,t}^{m+n}} \prod_{j=1}^{m+n} f_{\sigma(j)}(w_j) dw. \tag{9}$$

For a proof of a more general result we refer the reader to [6, Lemma 2.1].

2.2 Fractional Calculus

In the following we give some basic definitions and properties on fractional calculus. For more insights on the general theory we refer the reader to [34] and [37].

Let $a, b \in \mathbb{R}$ with $a < b$, $f, g \in L^p([a, b])$ with $p \geq 1$ and $\alpha > 0$. We define the *left- and right-sided Riemann-Liouville fractional integrals* by

$$I_{a^+}^\alpha f(x) = \frac{1}{\Gamma(\alpha)} \int_a^x (x - y)^{\alpha-1} f(y) dy,$$

and

$$I_{b^-}^\alpha g(x) = \frac{1}{\Gamma(\alpha)} \int_x^b (y - x)^{\alpha-1} g(y) dy,$$

for almost all $x \in [a, b]$. Here Γ denotes the gamma function.

Furthermore, for any given integer $p \geq 1$, let $I_{a^+}^\alpha(L^p)$ and $I_{b^-}^\alpha(L^p)$ denote the images of $L^p([a, b])$ by the operator $I_{a^+}^\alpha$ and $I_{b^-}^\alpha$, respectively. If $0 < \alpha < 1$ as well as $f \in I_{a^+}^\alpha(L^p)$ and $g \in I_{b^-}^\alpha(L^p)$, we define the *left- and right-sided Riemann-Liouville fractional derivatives* by

$$D_{a^+}^\alpha f(x) = \frac{1}{\Gamma(1 - \alpha)} \frac{d}{dx} \int_a^x \frac{f(y)}{(x - y)^\alpha} dy, \tag{10}$$

and

$$D_{b^-}^\alpha g(x) = \frac{1}{\Gamma(1 - \alpha)} \frac{d}{dx} \int_x^b \frac{g(y)}{(y - x)^\alpha} dy, \tag{11}$$

respectively. The left- and right-sided derivatives of f and g defined in Eqs. 10 and 11 admit moreover the representations

$$D_{a^+}^\alpha f(x) = \frac{1}{\Gamma(1 - \alpha)} \left(\frac{f(x)}{(x - a)^\alpha} + \alpha \int_a^x \frac{f(x) - f(y)}{(x - y)^{\alpha+1}} dy \right),$$

and

$$D_{b^-}^\alpha g(x) = \frac{1}{\Gamma(1 - \alpha)} \left(\frac{g(x)}{(b - x)^\alpha} + \alpha \int_x^b \frac{g(x) - g(y)}{(y - x)^{\alpha+1}} dy \right).$$

Last, we get by construction that similar to the fundamental theorem of calculus

$$I_{a^+}^\alpha (D_{a^+}^\alpha f) = f, \tag{12}$$

for all $f \in I_{a^+}^\alpha(L^p)$, and

$$D_{a^+}^\alpha (I_{a^+}^\alpha g) = g, \tag{13}$$

for all $g \in L^p([a, b])$. Equivalent results hold for $I_{b^-}^\alpha$ and $D_{b^-}^\alpha$.

2.3 Fractional Brownian Motion

The one-dimensional *fractional Brownian motion*, in short fBm, $B^H = (B_t^H)_{t \in [0, T]}$ with Hurst parameter $H \in (0, \frac{1}{2})$ on a complete probability space $(\Omega, \mathcal{F}, \mathbb{P})$ is defined as a centered Gaussian process with covariance function

$$R_H(t, s) := \mathbb{E} [B_t^H B_s^H] = \frac{1}{2} (t^{2H} + s^{2H} - |t - s|^{2H}).$$

Note that $\mathbb{E}\left[|B_t^H - B_s^H|^2\right] = |t - s|^{2H}$ and hence B^H has stationary increments and almost surely Hölder continuous paths of order $H - \varepsilon$ for all $\varepsilon \in (0, H)$. However, the increments of B^H , $H \in (0, \frac{1}{2})$, are not independent and B^H is not a semimartingale, see e.g. [32, Proposition 5.1.1].

Subsequently we give a brief outline of how a fractional Brownian motion can be constructed from a standard Brownian motion. For more details we refer the reader to [32].

Recall the following result (see [32, Proposition 5.1.3]) which gives the kernel of a fractional Brownian motion and an integral representation of $R_H(t, s)$ in the case of $H < \frac{1}{2}$.

Proposition 2.1 *Let $H < \frac{1}{2}$. The kernel*

$$K_H(t, s) := c_H \left[\left(\frac{t}{s}\right)^{H-\frac{1}{2}} (t-s)^{H-\frac{1}{2}} + \left(\frac{1}{2} - H\right) s^{\frac{1}{2}-H} \int_s^t u^{H-\frac{3}{2}} (u-s)^{H-\frac{1}{2}} du \right], \tag{14}$$

where $c_H = \sqrt{\frac{2H}{(1-2H)\beta(1-2H, H+\frac{1}{2})}}$ and β is the beta function, satisfies

$$R_H(t, s) = \int_0^{t \wedge s} K_H(t, u) K_H(s, u) du. \tag{15}$$

Subsequently, we denote by W a standard Brownian motion on the complete filtered probability space $(\Omega, \mathcal{F}, \mathbb{F}^W, \mathbb{P})$, where $\mathbb{F}^W := (\mathcal{F}_t^W)_{t \in [0, T]}$ is the natural filtration of W augmented by all \mathbb{P} -null sets. Using the kernel given in Eq. 14 it is well known that the fractional Brownian motion B^H has a representation

$$B_t^H = \int_0^t K_H(t, s) dW_s, \quad H \in \left(0, \frac{1}{2}\right). \tag{16}$$

Note that due to representation Eq. 16 the natural filtration generated by B^H is identical to \mathbb{F}^W . Furthermore, equivalent to the case of a standard Brownian motion, it exists a version of Girsanov’s theorem for fractional Brownian motion which is due to [16, Theorem 4.9]. In the following we state the version given in [33, Theorem 3.1].

But first let us define the isomorphism K_H from $L^2([0, T])$ onto $I_{0+}^{H+\frac{1}{2}}(L^2)$ (see [16, Theorem 2.1]) given by

$$(K_H \varphi)(s) = I_{0+}^{2H} s^{\frac{1}{2}-H} I_{0+}^{\frac{1}{2}-H} s^{H-\frac{1}{2}} \varphi, \quad \varphi \in L^2([0, T]). \tag{17}$$

From Eq. 17 and the properties of the Riemann-Liouville fractional integrals and derivatives Eqs. 12 and 13, the inverse of K_H is given by

$$(K_H^{-1} \varphi)(s) = s^{\frac{1}{2}-H} D_{0+}^{\frac{1}{2}-H} s^{H-\frac{1}{2}} D_{0+}^{2H} \varphi(s), \quad \varphi \in I_{0+}^{H+\frac{1}{2}}(L^2).$$

It can be shown (see [33]) that if φ is absolutely continuous

$$(K_H^{-1} \varphi)(s) = s^{H-\frac{1}{2}} I_{0+}^{\frac{1}{2}-H} s^{\frac{1}{2}-H} \varphi'(s), \tag{18}$$

where φ' denotes the weak derivative of φ .

Theorem 2.2 (Girsanov’s theorem for fBm) *Let $u = (u_t)_{t \in [0, T]}$ be a process with integrable trajectories and set $\tilde{B}_t^H = B_t^H + \int_0^t u_s ds$, $t \in [0, T]$. Assume that*

- (i) $\int_0^t u_s ds \in I_{0+}^{H+\frac{1}{2}}(L^2([0, T]), \mathbb{P}\text{-a.s.})$, and

(ii) $\mathbb{E}[\mathcal{E}_T] = 1$, where

$$\mathcal{E}_T := \exp \left\{ -\int_0^T K_H^{-1} \left(\int_0^\cdot u_r dr \right) (s) dW_s - \frac{1}{2} \int_0^T K_H^{-1} \left(\int_0^\cdot u_r dr \right)^2 (s) ds \right\}.$$

Then the shifted process \tilde{B}^H is an \mathbb{F}^W -fractional Brownian motion with Hurst parameter H under the new probability measure $\tilde{\mathbb{P}}$ defined by $\frac{d\tilde{\mathbb{P}}}{d\mathbb{P}} = \mathcal{E}_T$.

Remark 2.3 Theorem 2.2 can be extended to the multi- and infinite-dimensional cases, which will be considered in this paper primarily. Indeed, note first that the measure change in Girsanov’s theorem acts dimension-wise. In particular, consider the two dimensional shifted process

$$\begin{aligned} X_t^{(1)} &= B_t^{H_1} + \int_0^t u_s^{(1)} ds, \\ X_t^{(2)} &= B_t^{H_2} + \int_0^t u_s^{(2)} ds, \quad t \in [0, T], \end{aligned}$$

where B^{H_1} and B^{H_2} are two fractional Brownian motions with Hurst parameters H_1 and H_2 generated by the independent standard Brownian motions $W^{(1)}$ and $W^{(2)}$, respectively, and $u^{(1)}$ and $u^{(2)}$ are two shifts fulfilling the conditions of Theorem 2.2. Then the measure change with respect to the stochastic exponential

$$\mathcal{E}_T^{(1)} := \exp \left\{ -\int_0^T K_{H_1}^{-1} \left(\int_0^\cdot u_r^{(1)} dr \right) (s) dW_s^{(1)} - \frac{1}{2} \int_0^T K_{H_1}^{-1} \left(\int_0^\cdot u_r^{(1)} dr \right)^2 (s) ds \right\}$$

yields the two dimensional process

$$\begin{aligned} X_t^{(1)} &= \tilde{B}_t^{H_1}, \\ X_t^{(2)} &= B_t^{H_2} + \int_0^t u_s^{(2)} ds, \quad t \in [0, T]. \end{aligned}$$

Here, \tilde{B}^{H_1} is a fractional Brownian motions with respect to the measure $\tilde{\mathbb{P}}$ defined by $\frac{d\tilde{\mathbb{P}}}{d\mathbb{P}} = \mathcal{E}_T^{(1)}$. Note that B^{H_2} is still a fractional Brownian motion under $\tilde{\mathbb{P}}$, since $W^{(1)}$ and $W^{(2)}$ are independent. Applying Girsanov’s theorem again with respect to the stochastic exponential

$$\mathcal{E}_T^{(2)} := \exp \left\{ -\int_0^T K_{H_2}^{-1} \left(\int_0^\cdot u_r^{(2)} dr \right) (s) dW_s^{(2)} - \frac{1}{2} \int_0^T K_{H_2}^{-1} \left(\int_0^\cdot u_r^{(2)} dr \right)^2 (s) ds \right\},$$

yields the two dimensional process

$$\begin{aligned} X_t^{(1)} &= \tilde{B}_t^{H_1}, \\ X_t^{(2)} &= \tilde{B}_t^{H_2}, \quad t \in [0, T], \end{aligned}$$

where \tilde{B}^{H_1} and \tilde{B}^{H_2} are independent fractional Brownian motions with respect to the measure $\hat{\mathbb{P}}$ defined by

$$\frac{d\hat{\mathbb{P}}}{d\mathbb{P}} = \frac{d\hat{\mathbb{P}}}{d\tilde{\mathbb{P}}} \frac{d\tilde{\mathbb{P}}}{d\mathbb{P}} = \mathcal{E}_T^{(2)} \mathcal{E}_T^{(1)}.$$

Repeating iteratively yields the stochastic exponential – if well-defined –

$$\mathcal{E}_T := \prod_{k \geq 1} \mathcal{E}_T^{(k)}$$

acting on infinite dimensions.

Finally, we give the property of strong local non-determinism of the fractional Brownian motion B^H with Hurst parameter $H \in (0, \frac{1}{2})$ which was proven in [35, Lemma 7.1]. This property will essentially help us to overcome the limitations of not having independent increments of the underlying noise.

Lemma 2.4 *Let B^H be a fractional Brownian motion with Hurst parameter $H \in (0, \frac{1}{2})$. Then there exists a constant \mathfrak{K}_H dependent merely on H such that for every $t \in [0, T]$ and $0 < r \leq t$*

$$\text{Var}\left(B_t^H \mid B_s^H : |t - s| \geq r\right) \geq \mathfrak{K}_H r^{2H}.$$

3 Cylindrical Fractional Brownian Motion and Weak Solutions

We start this section by defining the driving noise $(\mathbb{B}_t)_{t \in [0, T]}$ in SDE Eq. 3. Let $\{W^{(k)}\}_{k \geq 1}$ be a sequence of independent one-dimensional standard Brownian motions on a joint complete probability space $(\Omega, \mathcal{F}, \mathbb{P})$. We define the cylindrical Brownian motion W taking values in \mathcal{H} by

$$W_t := \sum_{k \geq 1} W_t^{(k)} e_k, \quad t \in [0, T],$$

and denote by $\mathbb{F}^W := (\mathcal{F}_t^W)_{t \in [0, T]}$ its natural filtration augmented by the \mathbb{P} -null sets. Moreover, we define a sequence of Hurst parameters $H := \{H_k\}_{k \geq 1} \subset (0, \frac{1}{2})$ with the following properties:

- (i) $\sum_{k \geq 1} H_k < \frac{1}{6}$
- (ii) $\sup_{k \geq 1} H_k < \frac{1}{12}$

Using H we construct the sequence of fractional Brownian motions $\{B^{H_k}\}_{k \geq 1}$ associated to $\{W^{(k)}\}_{k \geq 1}$ by

$$B_t^{H_k} := \int_0^t K_{H_k}(t, s) dW_s^{(k)}, \quad t \in [0, T], \quad k \geq 1,$$

where the kernel $K_{H_k}(\cdot, \cdot)$ is defined as in Eq. 14. Note that the fractional Brownian motions $\{B^{H_k}\}_{k \geq 1}$ are independent by construction. Consequently, we define the cylindrical fractional Brownian motion B^H with associated sequence of Hurst parameters H by

$$B_t^H := \sum_{k \geq 1} B_t^{H_k} e_k, \quad t \in [0, T]. \tag{19}$$

Nevertheless, the cylindrical fractional Brownian motion B^H is not in the space $L^2(\Omega; \mathcal{H})$. That is why we consider the operator $Q : \mathcal{H} \rightarrow \mathcal{H}$ defined by

$$Qx = \sum_{k \geq 1} \lambda_k^2 x^{(k)} e_k,$$

for a given sequence of non-negative real numbers $\lambda := \{\lambda_k\}_{k \geq 1} \in \ell^2$ such that $\frac{\lambda}{\sqrt{H}} := \left\{ \frac{\lambda_k}{\sqrt{H_k}} \right\}_{k \geq 1} \in \ell^1$. In particular, Q is a self-adjoint operator and we have that the *weighted cylindrical fractional Brownian motion*

$$\mathbb{B}_t := \sqrt{Q}B_t^H = \sum_{k \geq 1} \lambda_k B_t^{H_k} e_k, \tag{20}$$

lies in $L^2(\Omega; \mathcal{H})$ for every $t \in [0, T]$. Due to the following lemma the stochastic process $(\mathbb{B}_t)_{t \in [0, T]}$ is continuous in time.

Lemma 3.1 *The stochastic process $(\mathbb{B}_t)_{t \in [0, T]}$ defined in Eq. 20 has almost surely continuous sample paths on $[0, T]$.*

Proof Note first that due to [10][Theorem 1] for any fractional Brownian motion B^H with Hurst parameter $H \in (0, \frac{1}{2})$ there exists a constant $C > 0$ independent of H such that

$$\mathbb{E} \left[\sup_{t \in [0, T]} |B_t^H| \right] \leq \frac{C}{\sqrt{H}}. \tag{21}$$

Using monotone convergence and Eq. 21 we have that

$$\begin{aligned} \mathbb{E} \left[\sup_{t \in [0, T]} \|\mathbb{B}_t\|_{\mathcal{H}} \right] &\leq \mathbb{E} \left[\sup_{t \in [0, T]} \sum_{k \geq 1} |\lambda_k| |B_t^{H_k}| \right] \leq \sum_{k \geq 1} \lambda_k \mathbb{E} \left[\sup_{t \in [0, T]} |B_t^{H_k}| \right] \\ &\leq \sum_{k \geq 1} \lambda_k \frac{C}{\sqrt{H_k}} < \infty. \end{aligned}$$

Thus, $(\sqrt{Q}B_t^H)_{t \in [0, T]}$ is almost surely finite and $\{(\pi_d \sqrt{Q}B_t^H)_{t \in [0, T]}\}_{d \geq 1}$ is a Cauchy sequence in $L^1(\Omega; \mathcal{C}([0, T]; \mathcal{H}))$ which converges almost surely to $(\sqrt{Q}B_t^H)_{t \in [0, T]}$. \square

Before we come to the next result, let us recall the notion of a weak solution and uniqueness in law.

Definition 3.2 The sextuple $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P}, \mathbb{B}, X)$ is called a weak solution of stochastic differential Eq. 3, if

- (i) $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P})$ is a complete filtered probability space, where $\mathbb{F} = \{\mathcal{F}_t\}_{t \in [0, T]}$ satisfies the usual conditions of right-continuity and completeness,
- (ii) $\mathbb{B} = (\mathbb{B}_t)_{t \in [0, T]}$ is a weighted cylindrical fractional (\mathbb{F}, \mathbb{P}) -Brownian motion as defined in Eq. 20, and
- (iii) $X = (X_t)_{t \in [0, T]}$ is a continuous, \mathbb{F} -adapted, \mathcal{H} -valued process satisfying \mathbb{P} -a.s.

$$X_t = x + \int_0^t b(s, X_s) ds + \mathbb{B}_t, \quad t \in [0, T].$$

Remark 3.3 For notational simplicity we refer solely to the process X as a weak solution (or later on as a strong solution) in the case of an unambiguous stochastic basis $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P}, B)$.

Definition 3.4 We say a weak solution X^1 with respect to the stochastic basis $(\Omega^1, \mathcal{F}^1, \mathbb{F}^1, \mathbb{P}^1, \mathbb{B}^1)$ of the SDE Eq. 3 is *weakly unique* or *unique in law*, if for any other

weak solution X^2 of Eq. 3 on a potential other stochastic basis $(\Omega^2, \mathcal{F}^2, \mathbb{F}^2, \mathbb{P}^2, \mathbb{B}^2)$ it holds that

$$\mathbb{P}_{X^1}^1 = \mathbb{P}_{X^2}^2,$$

whenever $\mathbb{P}_{X_0^1}^1 = \mathbb{P}_{X_0^2}^2$.

Proposition 3.5 *Let $b : [0, T] \times \mathcal{H} \rightarrow \mathcal{H}$ be a measurable and bounded function with $\|b_k\|_\infty \leq C_k \lambda_k < \infty$ for every $k \geq 1$ where $C := \{C_k\}_{k \geq 1} \in \ell^1$. Then SDE Eq. 3 has a weak solution $(X_t)_{t \in [0, T]}$ such that*

$$\mathbb{E} \left[\sup_{t \in [0, T]} \|X_t\|_{\mathcal{H}}^2 \right] < \infty.$$

Moreover, the solution is unique in law.

Proof Let $\{W^{(k)}\}_{k \geq 1}$ be a sequence of independent standard Brownian motions on the filtered probability space $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{Q})$. Consider the cylindrical fractional Brownian motion \widehat{B}^H generated by $\{W^{(k)}\}_{k \geq 1}$ as defined in Eq. 19 with associated sequence of Hurst parameters H . We define the stochastic exponential \mathcal{E} by

$$\begin{aligned} \mathcal{E}_t := \exp & \left\{ \sum_{k \geq 1} \left(\int_0^t K_{H_k}^{-1} \left(\int_0^\cdot b_k(u, x + \sqrt{Q} \widehat{B}_u^H) \lambda_k^{-1} du \right) (s) dW_s^{(k)} \right. \right. \\ & \left. \left. - \frac{1}{2} \int_0^t K_{H_k}^{-1} \left(\int_0^\cdot b_k(u, x + \sqrt{Q} \widehat{B}_u^H) \lambda_k^{-1} du \right)^2 (s) ds \right) \right\}. \end{aligned}$$

In order to show that the stochastic exponential \mathcal{E} is well-defined we first have to verify that for every $k \geq 1$

$$\int_0^\cdot b_k(u, x + \sqrt{Q} \widehat{B}_u^H) \lambda_k^{-1} du \in I_{0+}^{H_k + \frac{1}{2}} \left(L^2([0, T]) \right), \mathbb{P} - \text{a.s.}$$

Due to Eq. 18 this property is fulfilled, if for all $k \geq 1$

$$\int_0^T \left(b_k(u, x + \sqrt{Q} \widehat{B}_u^H) \lambda_k^{-1} \right)^2 du < \infty,$$

which holds since $\|b_k\|_\infty \leq C_k \lambda_k$. Furthermore, we can find a constant $C > 0$ such that

$$\begin{aligned} \exp & \left\{ \frac{1}{2} \sum_{k \geq 1} \int_0^T K_{H_k}^{-1} \left(\int_0^\cdot b_k(u, x + \sqrt{Q} \widehat{B}_u^H) \lambda_k^{-1} du \right)^2 (s) ds \right\} \\ & \leq \exp \left\{ CT^2 \sum_{k \geq 1} C_k^2 \right\} < \infty. \end{aligned}$$

Hence, by Novikov’s criterion \mathcal{E}_t is a martingale, in particular $\mathbb{E}[\mathcal{E}_t] = 1$ for all $t \in [0, T]$. Consequently, under the probability measure \mathbb{P} , defined by $\frac{d\mathbb{P}}{d\mathbb{Q}} := \mathcal{E}_T$, the process $B_t^H := \widehat{B}_t^H - \int_0^t \sqrt{Q}^{-1} b(u, x + \sqrt{Q} \widehat{B}_u^H) du, t \in [0, T]$, is a cylindrical fractional Brownian motion due to Theorem 2.2 and Remark 2.3. Therefore, $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P}, \sqrt{Q} B^H, X)$, where $X_t := x + \sqrt{Q} \widehat{B}_t^H$, is a weak solution of SDE Eq. 3. Since the probability measures $\mathbb{Q} \approx \mathbb{P}$ are equivalent, the solution is unique in law. \square

4 Strong Solutions and Malliavin Derivative

After establishing the existence of a weak solution, we investigate under which conditions SDE Eq. 3 has a strong solution. Therefore, let us first recall the notion of a strong solution and moreover the notion of pathwise uniqueness.

Definition 4.1 A weak solution $(\Omega, \mathcal{F}, \mathbb{F}^{\mathbb{B}}, \mathbb{P}, \mathbb{B}, X^x)$ of the stochastic differential Eq. 3 is called *strong solution*, if $\mathbb{F}^{\mathbb{B}}$ is the filtration generated by the driving noise \mathbb{B} and augmented with the \mathbb{P} -null sets.

Definition 4.2 We say a weak solution $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P}, \mathbb{B}, X^1)$ of Eq. 3 is *pathwise unique*, if for any other weak solution $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P}, \mathbb{B}, X^2)$ on the same stochastic basis,

$$\mathbb{P} \left(\omega \in \Omega : X_t^1(\omega) = X_t^2(\omega) \forall t \geq 0 \right) = 1.$$

The cause of this paper is to establish the existence of strong solutions of stochastic differential Eq. 3 for *singular* drift coefficients b . More precisely, we define the class $\mathfrak{B}([0, T] \times \mathcal{H}; \mathcal{H})$ of measurable functions $b : [0, T] \times \mathcal{H} \rightarrow \mathcal{H}$ for which there exist sequences $C \in \ell^1$ and $D \in \ell^1$ such that for every $k \geq 1$

$$\begin{aligned} \sup_{y \in \mathcal{H}} \sup_{t \in [0, T]} |b_k(t, y)| &\leq C_k \lambda_k, \text{ and} \\ \sup_{d \geq 1} \int_{\mathbb{R}^d} \sup_{t \in [0, T]} |b_k \left(t, \sqrt{Q} \sqrt{\mathcal{K}} \tau^{-1} y \right)| dy &\leq D_k \lambda_k, \end{aligned} \tag{22}$$

where $y = (y_1, \dots, y_d)$ and $\mathcal{K} : \mathcal{H} \rightarrow \mathcal{H}$ is the defined by

$$\mathcal{K}x = \sum_{k \geq 1} \mathfrak{K}_{H_k} x^{(k)} e_k, \quad x \in \mathcal{H}, \tag{23}$$

for $\{\mathfrak{K}_{H_k}\}_{k \geq 1}$ being the local non-determinism constant of $\{B^{H_k}\}_{k \geq 1}$ as given in Lemma 2.4.

In order to prove the existence of a strong solution for drift coefficients of class $\mathfrak{B}([0, T] \times \mathcal{H}; \mathcal{H})$ we proceed in the following way:

- 1) We define an approximating double-sequence $\{b^{d,\varepsilon}\}_{d \geq 1, \varepsilon > 0}$ for drift coefficients of type Eq. 22 which merely act on d dimensions and are sufficiently smooth
- 2) For every $d \geq 1$ and $\varepsilon > 0$, we prove that the SDE

$$X_t^{d,\varepsilon} = x + \int_0^t b^{d,\varepsilon}(s, X_s^{d,\varepsilon}) ds + \mathbb{B}_t, \quad t \in [0, T], \tag{24}$$

has a unique strong solution which is Malliavin differentiable

- 3) We show that the double-sequence of strong solutions $X_t^{d,\varepsilon}$ converges weakly to $\mathbb{E} [X_t | \mathcal{F}_t^W]$, where X_t is the unique weak solution of SDE Eq. 3
- 4) Applying a compactness criterion based on Malliavin calculus, we prove that the double-sequence is relatively compact in $L^2(\Omega, \mathcal{F}_t^W)$
- 5) Last, we show that X_t is adapted to the filtration $\mathbb{F}^{\mathbb{B}}$ and thus is a strong solution of SDE Eq. 3

4.1 Approximating Double-Sequence

Recall the truncation operator $\pi_d, d \geq 1$, defined in Eq. 6 and the change of basis operator τ defined in Eq. 7. We define the operator $\tilde{\pi}_d : \mathcal{H} \rightarrow \mathbb{R}^d$ as $\tilde{\pi}_d := \tau \circ \pi_d$. For every $k \geq 1$ let the function $\tilde{b}^d : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^d$ be defined by

$$\tilde{b}^d(t, z) = \tilde{\pi}_d b(t, \tau^{-1}z). \tag{25}$$

Let $\varphi_\varepsilon, \varepsilon > 0$, be a mollifier on \mathbb{R}^d such that for any locally integrable function $f : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^d$ and for every $t \in [0, T]$ the convolution $f(t, \cdot) * \varphi_\varepsilon$ is smooth and

$$f(t, \cdot) * \varphi_\varepsilon \rightarrow f(t, \cdot), \varepsilon \rightarrow 0,$$

almost everywhere with respect to the Lebesgue measure. Finally, we define for every $d \geq 1$ and $\varepsilon > 0$ the double-sequence $b^{d,\varepsilon} : [0, T] \times \mathcal{H} \rightarrow \mathcal{H}$ by

$$b^{d,\varepsilon}(t, y) := \tau^{-1} \left(\tilde{b}^d(t, \tilde{\pi}_d y) * \varphi_\varepsilon(\tilde{\pi}_d y) \right). \tag{26}$$

Analogously to Eq. 25, we define for $t \in [0, T]$ and $z \in \mathbb{R}^d$

$$\tilde{b}^{d,\varepsilon}(t, z) := \tau b^{d,\varepsilon}(t, \tau^{-1}z) = \tilde{b}^d(t, z) * \varphi_\varepsilon(z). \tag{27}$$

Due to the definition of the mollifier φ_ε we have that for every $d \geq 1$

$$b^{d,\varepsilon}(t, \tau^{-1}z) = \tau^{-1} \left(\tilde{b}^d(t, z) * \varphi_\varepsilon(z) \right) \xrightarrow{\varepsilon \rightarrow 0} \tau^{-1} \tilde{b}^d(t, z) = b^d(t, \tau^{-1}z) \tag{28}$$

for almost every $(t, z) \in [0, T] \times \mathbb{R}^d$ with respect to the Lebesgue measure. Thus, due to Eq. 28 and the canonical properties of the truncation operator we have that

$$b^{d,\varepsilon}(t, y) \xrightarrow{\varepsilon \rightarrow 0} b^d(t, y) \xrightarrow{d \rightarrow \infty} b(t, y)$$

pointwise in $[0, T] \times \mathcal{H}$, where $b^d := \pi_d b$. Due to the assumptions on b we further get for every $p \geq 2$ using dominated convergence that

$$\lim_{d \rightarrow \infty} \lim_{\varepsilon \rightarrow 0} \mathbb{E} \left[\int_0^T \left\| b^{d,\varepsilon}(t, \mathbb{B}_t^x) - b(t, \mathbb{B}_t^x) \right\|_{\mathcal{H}}^p dt \right]^{\frac{1}{p}} = 0.$$

Hence, we can speak of an approximating double-sequence $\{b^{d,\varepsilon}\}_{d \geq 1, \varepsilon > 0}$ of the drift coefficient b . In line with the previously used notation we define

$$\begin{aligned} b_k^{d,\varepsilon}(t, y) &:= \langle b^{d,\varepsilon}(t, y), e_k \rangle_{\mathcal{H}} = \langle \tilde{b}^{d,\varepsilon}(t, \tau y), \tilde{e}_k \rangle =: \tilde{b}_k^{d,\varepsilon}(t, \tau y), \\ b_k^d(t, y) &:= \langle b^d(t, y), e_k \rangle_{\mathcal{H}} = \langle \tilde{b}^d(t, \tau y), \tilde{e}_k \rangle =: \tilde{b}_k^d(t, \tau y). \end{aligned}$$

Moreover, note that $b^{d,\varepsilon}, b^d \in \mathfrak{B}([0, T] \times \mathcal{H}; \mathcal{H})$.

Remark 4.3 Note that we needed to truncate and shift the domain of the function b to \mathbb{R}^d merely in order to apply mollification.

4.2 Malliavin Differentiable Strong Solutions for Regular Drifts

In the following proposition we establish the existence of a unique strong solution for a class of drift coefficients which contains the approximating sequence $\{b^{d,\varepsilon}\}_{d \geq 1, \varepsilon > 0}$. More specifically, we consider drift coefficients $b \in \mathfrak{B}([0, T] \times \mathcal{H}; \mathcal{H})$ such that for all $k \geq 1$ and all $t \in [0, T]$

$$b_k(t, \cdot) \in \text{Lip}_{L_k}(\mathcal{H}; \mathbb{R}),$$

where $L \in \ell^2$. We denote the space of such functions by $\mathfrak{L}([0, T] \times \mathcal{H}; \mathcal{H})$.

Proposition 4.4 *Let $b \in \mathfrak{L}([0, T] \times \mathcal{H}; \mathcal{H})$. Then SDE Eq. 3 has a pathwise unique strong solution.*

Proof In order to prove the existence of a strong solution we use Picard iteration and proceed similar to the well-known case of finite dimensional SDEs. More precisely, we define inductively the sequence $Y^0 := x + \mathbb{B}$ and for all $n \geq 1$

$$Y_t^n = x + \int_0^t b\left(s, Y_s^{n-1}\right) ds + \mathbb{B}_t, \quad t \in [0, T]. \tag{29}$$

We show next that $\{Y^n\}_{n \geq 0}$ is a Cauchy sequence in $L^2([0, T] \times \Omega)$. Indeed, due to monotone convergence we get for every $n \geq 1$ and $t \in [0, T]$

$$\begin{aligned} \mathbb{E} \left[\left\| Y_t^{n+1} - Y_t^n \right\|_{\mathcal{H}}^2 \right]^{\frac{1}{2}} &= \mathbb{E} \left[\left\| \int_0^t b(s, Y_s^n) - b(s, Y_s^{n-1}) ds \right\|_{\mathcal{H}}^2 \right]^{\frac{1}{2}} \\ &\leq \int_0^t \left(\sum_{k \geq 1} \mathbb{E} \left[\left| b_k(s, Y_s^n) - b_k(s, Y_s^{n-1}) \right|^2 \right] \right)^{\frac{1}{2}} ds \\ &\leq \|L\|_{\ell^2} \int_0^t \mathbb{E} \left[\left\| Y_s^n - Y_s^{n-1} \right\|_{\mathcal{H}}^2 \right]^{\frac{1}{2}} ds, \end{aligned} \tag{30}$$

and

$$\mathbb{E} \left[\left\| Y_t^1 - Y_t^0 \right\|_{\mathcal{H}}^2 \right]^{\frac{1}{2}} = \mathbb{E} \left[\left\| \int_0^t b(s, x + \mathbb{B}_s) ds \right\|_{\mathcal{H}}^2 \right]^{\frac{1}{2}} \leq t \|C\lambda\|_{\ell^2}.$$

By induction we obtain for every $n \geq 0$ a constant A depending on C, λ and L such that

$$\mathbb{E} \left[\left\| Y_t^{n+1} - Y_t^n \right\|_{\mathcal{H}}^2 \right]^{\frac{1}{2}} \leq \frac{A^{n+1}}{(n+1)!} t^{n+1}.$$

Hence, for every $m, n \geq 0$

$$\begin{aligned} \|Y^m - Y^n\|_{L^2([0, T] \times \Omega; \mathcal{H})} &\leq \sum_{k=n}^{m-1} \|Y^{k+1} - Y^k\|_{L^2([0, T] \times \Omega; \mathcal{H})} \\ &= \sum_{k=n}^{m-1} \mathbb{E} \left[\int_0^T \left\| Y_t^{k+1} - Y_t^k \right\|_{\mathcal{H}}^2 dt \right]^{\frac{1}{2}} \\ &\leq \sum_{k=n}^{m-1} \frac{A^{k+1}}{(k+1)!} T^{k+\frac{3}{2}} =: B(n, m). \end{aligned}$$

Since $B(n, m)$ is bounded by $T^{\frac{1}{2}} e^{AT}$, the series converges and

$$B(n, m) \xrightarrow{n, m \rightarrow \infty} 0.$$

Therefore $\{Y^n\}_{n \geq 0}$ is a Cauchy sequence in $L^2([0, T] \times \Omega; \mathcal{H})$. Define

$$X_t := \lim_{n \rightarrow \infty} Y_t^n$$

as the $L^2([0, T] \times \Omega; \mathcal{H})$ limit of $\{Y^n\}_{n \geq 0}$. Then X_t is $\mathcal{F}_t^{\mathbb{B}}$ adapted for all $t \in [0, T]$ since this holds for all $Y_t^n, n \geq 0$. We prove that X_t solves SDE Eq. 3:

We have for all $n \geq 0$ and $t \in [0, T]$ that

$$Y_t^{n+1} = x + \int_0^t b(s, Y_s^n) ds + \mathbb{B}_t.$$

Using the Lipschitz continuity of b , we get

$$\begin{aligned} \mathbb{E} \left[\left\| \int_0^t b(s, Y_s^n) - b(s, X_s) ds \right\|_{\mathcal{H}}^2 \right]^{\frac{1}{2}} &\leq \int_0^t \left(\sum_{k \geq 1} \mathbb{E} \left[|b_k(s, Y_s^n) - b_k(s, X_s)|^2 \right] \right)^{\frac{1}{2}} ds \\ &\leq \|L\|_{\ell^2} \int_0^t \mathbb{E} \left[\|Y_s^n - X_s\|_{\mathcal{H}}^2 \right]^{\frac{1}{2}} ds \xrightarrow{n \rightarrow \infty} 0. \end{aligned}$$

Hence, $(X_t)_{t \in [0, T]}$ is a strong solution of SDE Eq. 3.

In order to show pathwise uniqueness, let X and Y be two strong solutions on the same stochastic basis $(\Omega, \mathcal{F}, \mathbb{P}, \mathbb{B})$ with the same initial condition. Then for all $t \in [0, T]$ we get similar to Eq. 30 that

$$\mathbb{E} \left[\|X_t - Y_t\|_{\mathcal{H}}^2 \right]^{\frac{1}{2}} \leq \|L\|_{\ell^2} \int_0^t \mathbb{E} \left[\|X_s - Y_s\|_{\mathcal{H}}^2 \right]^{\frac{1}{2}} ds.$$

Using Grönwall’s inequality yields that $\mathbb{E} \left[\|X_t - Y_t\|_{\mathcal{H}}^2 \right] = 0$ for all $t \in [0, T]$, and therefore $X_t = Y_t$ \mathbb{P} -a.s. for all $t \in [0, T]$. But since X and Y are almost surely continuous we get

$$\mathbb{P} \left(\omega \in \Omega : X_t^1(\omega) = X_t^2(\omega) \forall t \geq 0 \right) = 1.$$

□

Next we investigate under which conditions the unique strong solution is Malliavin differentiable. But let us start with a definition of Malliavin differentiability of a random variable in the space \mathcal{H} .

Definition 4.5 Let X be an \mathcal{H} -valued square integrable functional of the cylindrical Brownian motion $(W_t)_{t \in [0, T]}$. We define the operator $D^m, m \geq 1$, such that

$$D^m X = \sum_{k \geq 1} D^m X^{(k)} e_k,$$

as the Malliavin derivative in the direction of the m -th Brownian motion $W^{(m)}$. Here, $D^m X^{(k)}, m, k \geq 1$, is the (standard) Malliavin derivative with respect to the Brownian motion $W^{(m)}$ of the square integrable random variable $X^{(k)}$ taking values in \mathbb{R} . We say a random variable X with values in \mathcal{H} is in the space $\mathbb{D}^{1,2}(\mathcal{H})$ of Malliavin differentiable functions in $L^2(\Omega)$ if and only if

$$\|X\|_{\mathbb{D}^{1,2}(\mathcal{H})}^2 := \sum_{m \geq 1} \int_0^T \mathbb{E} \left[\|D_s^m X\|_{\mathcal{H}}^2 \right] ds < \infty.$$

Moreover, a stochastic process $(X_t)_{t \in [0, T]}$ with values in \mathcal{H} is said to be in the space $\mathbb{D}^{1,2}([0, T] \times \mathcal{H})$ if and only if for every $t \in [0, T]$

$$\|X_t\|_{\mathbb{D}^{1,2}(\mathcal{H})}^2 := \sum_{m \geq 1} \int_0^T \mathbb{E} \left[\|D_s^m X_t\|_{\mathcal{H}}^2 \right] ds < \infty.$$

By means of Definition 4.5 we extend the well-known chain rule in Malliavin Calculus, cf. [32, Proposition 1.2.4], to Malliavin differentiable random variables taking values in \mathcal{H} . But first we define the class $\mathcal{L}_0(\mathcal{H})$ of Lipschitz continuous functions on \mathcal{H} with vanishing Lipschitz constants.

We say a function $f : \mathcal{H} \rightarrow \mathcal{H}$ is in the space $\mathcal{L}_0(\mathcal{H})$ if there exist sequences of constants $L, M \in \ell^2$ such that for all $k \geq 1$ and $x, y \in \mathcal{H}$

$$|(f(x) - f(y), e_k)_{\mathcal{H}}| \leq L_k \sum_{i \geq 1} M_i |(x - y, e_i)_{\mathcal{H}}|. \tag{31}$$

Lemma 4.6 *Let $f \in \mathcal{L}_0(\mathcal{H})$ with associated Lipschitz sequences $L, M \in \ell^2$ and $Y \in \mathbb{D}^{1,2}(\mathcal{H})$. Then, $f(Y) \in \mathbb{D}^{1,2}(\mathcal{H})$ and there exists a double-sequence $\{G_i^{(k)}\}_{k,i \geq 1}$ of random variables with $G_i^{(k)} \leq L_k \cdot M_i$ \mathbb{P} -a.s. for all $k, i \geq 1$ such that for every $m \geq 1$*

$$D^m f(Y) = \sum_{k \geq 1} \sum_{i \geq 1} G_i^{(k)} D^m \langle Y, e_i \rangle_{\mathcal{H}} e_k. \tag{32}$$

Moreover,

$$\|f(Y)\|_{\mathbb{D}^{1,2}(\mathcal{H})} \leq \|L\|_{\ell^2} \cdot \|M\|_{\ell^2} \cdot \|Y\|_{\mathbb{D}^{1,2}(\mathcal{H})}.$$

Proof First, consider the case $f : \mathbb{R}^d \rightarrow \mathbb{R}^d$ for some $d \geq 1$, where Y is taking values in \mathbb{R}^d . Using the chain rule, see [32, Proposition 1.2.4], and the notion of Malliavin Differentiability in Definition 4.5, there exists a double-sequence $\{G_i^{(k)}\}_{1 \leq k, i \leq d}$ of random variables with $G_i^{(k)} \leq L_k \cdot M_i$ \mathbb{P} -a.s. for all $1 \leq k, i \leq d$ such that for every $m \geq 1$

$$D^m f(Y) = \sum_{k=1}^d D^m f_k(Y) \tilde{e}_k = \sum_{k=1}^d \sum_{i=1}^d G_i^{(k)} D^m \langle Y, \tilde{e}_i \rangle \tilde{e}_k. \tag{33}$$

Recall the change of basis operator $\tau : \mathcal{H} \rightarrow \ell^2$ defined in Eq. 7. Let now $f : \mathcal{H}_d \rightarrow \mathcal{H}_d$, where Y is taking values in \mathcal{H}_d . Define $g : \mathbb{R}^d \rightarrow \mathbb{R}^d$ by $g := \tau \circ f \circ \tau^{-1}$. Then g is Lipschitz continuous in the sense of Eq. 31 with associated Lipschitz sequences $L, M \in \ell^2$ and due to equality Eq. 33 we get the identity

$$\begin{aligned} \tau D^m f(Y) &= \tau \sum_{k=1}^d D^m f_k(Y) e_k = \sum_{k=1}^d D^m g_k(\tau Y) \tilde{e}_k \\ &= \sum_{k=1}^d \sum_{i=1}^d G_i^{(k)} D^m \langle \tau Y, \tilde{e}_i \rangle \tilde{e}_k = \sum_{k=1}^d \sum_{i=1}^d G_i^{(k)} D^m \langle Y, e_i \rangle_{\mathcal{H}} \tilde{e}_k \\ &= \tau \sum_{k=1}^d \sum_{i=1}^d G_i^{(k)} D^m \langle Y, e_i \rangle_{\mathcal{H}} e_k. \end{aligned}$$

Thus, Eq. 32 holds for $f : \mathcal{H}_d \rightarrow \mathcal{H}_d$. Let finally $f : \mathcal{H} \rightarrow \mathcal{H}$, where Y is taking values in \mathcal{H} . Recall the truncation operator $\pi_d : \mathcal{H} \rightarrow \mathcal{H}_d$ defined in Eq. 6. Since f is Lipschitz

continuous, $f(\pi_d Y)$ converges to $f(Y)$ in $L^2(\Omega)$. Furthermore, we have for every $d \geq 1$ that

$$\begin{aligned} \|\pi_d f(\pi_d Y)\|_{\mathbb{D}^{1,2}(\mathcal{H})}^2 &= \sum_{m \geq 1} \int_0^T \mathbb{E} \left[\|D_s^m(\pi_d f(\pi_d Y))\|_{\mathcal{H}}^2 \right] ds \tag{34} \\ &= \sum_{m \geq 1} \sum_{k=1}^d \int_0^T \mathbb{E} \left[\left| \sum_{i=1}^d G_i^{d,(k)} D_s^m \langle Y, e_i \rangle_{\mathcal{H}} \right|^2 \right] ds \\ &\leq \|L\|_{\ell^2}^2 \sum_{m \geq 1} \int_0^T \mathbb{E} \left[\left| \sum_{i=1}^d M_i D_s^m \langle Y, e_i \rangle_{\mathcal{H}} \right|^2 \right] ds \\ &\leq \|L\|_{\ell^2}^2 \cdot \|M\|_{\ell^2}^2 \sum_{m \geq 1} \int_0^T \mathbb{E} \left[\|D_s^m Y\|_{\mathcal{H}}^2 \right] ds \\ &= \|L\|_{\ell^2}^2 \cdot \|M\|_{\ell^2}^2 \cdot \|Y\|_{\mathbb{D}^{1,2}(\mathcal{H})}^2 < \infty. \end{aligned}$$

Note that the double-sequence $\{G_i^{d,(k)}\}_{i \geq 1, k \geq 1}$ depends on $d \geq 1$. Nevertheless, $\|\pi_d f(\pi_d Y)\|_{\mathbb{D}^{1,2}(\mathcal{H})}$ is uniformly bounded in $d \geq 1$. Thus, due to [32, Lemma 1.2.3] and dominated convergence we have $f(Y) \in \mathbb{D}^{1,2}(\mathcal{H})$ and $D^m(\pi_d f(\pi_d Y))$ converges weakly to $D^m f(Y)$ for every $m \geq 1$. Moreover, the sequence $\{G_i^{d,(k)}\}_{d \geq 1}$ is bounded by $L_k \cdot M_i$ for every $k, i \geq 1$. Hence, for every $k, i \geq 1$ there exists a subsequence $\{G_i^{d_n,(k)}\}_{n \geq 1}$ which converges weakly to some random variable $\tilde{G}_i^{(k)}$ which is bounded by $L_k \cdot M_i$. Summarizing we get that in $L^2([0, T] \times \Omega; \mathcal{H})$

$$\begin{aligned} D^m f(Y) &= \lim_{n \rightarrow \infty} \pi_{d_n} D^m f(\pi_{d_n} Y) = \lim_{n \rightarrow \infty} \sum_{k=1}^{d_n} \sum_{i=1}^{d_n} G_i^{d_n,(k)} D^m \langle Y, e_i \rangle_{\mathcal{H}} e_k \\ &= \sum_{k \geq 1} \sum_{i \geq 1} \tilde{G}_i^{(k)} D^m \langle Y, e_i \rangle_{\mathcal{H}} e_k, \end{aligned}$$

where the last equality holds due to Eq. 34 and dominated convergence. □

Define the class $\mathfrak{L}_0([0, T] \times \mathcal{H}; \mathcal{H})$ by

$$\begin{aligned} \mathfrak{L}_0([0, T] \times \mathcal{H}; \mathcal{H}) &= \\ \{f \in \mathfrak{B}([0, T] \times \mathcal{H}; \mathcal{H}) : f(t, \cdot) \in \mathcal{L}_0(\mathcal{H}) \text{ uniformly in } t \in [0, T]\}, \end{aligned}$$

and note that $f(t, \cdot) \in \mathcal{L}_0(\mathcal{H})$ uniformly in $t \in [0, T]$ implies $f_k(t, \cdot) \in \text{Lip}_{L_k}(\mathcal{H}; \mathbb{R})$, $k \geq 1$, uniformly in $t \in [0, T]$ for some sequence $L \in \ell^2$. Thus, $\mathfrak{L}_0([0, T] \times \mathcal{H}; \mathcal{H}) \subset \mathfrak{L}([0, T] \times \mathcal{H}; \mathcal{H})$.

Proposition 4.7 *Let $b \in \mathfrak{L}_0([0, T] \times \mathcal{H}; \mathcal{H})$. Then the unique strong solution $(X_t)_{t \in [0, T]}$ of Eq. 3 is Malliavin differentiable.*

Proof Recall the Picard iteration defined in Eq. 29

$$Y_t^n = x + \int_0^t b(s, Y_s^{n-1}) ds + \mathbb{B}_t, \quad t \in [0, T], \quad n \geq 1, \tag{35}$$

and $Y^0 = x + \mathbb{B}$. We denote the k -th dimension of the infinite dimensional system Eq. 35 by $Y^{n,(k)} := \langle Y^n, e_k \rangle_{\mathcal{H}}$.

Using the Picard iteration Eq. 35, we show that for every step $n \geq 0$ the process Y^n is Malliavin differentiable. We prove this using induction. For $n = 0$ we have that for all $t \in [0, T]$ using Eq. 15

$$\begin{aligned} \|Y_t^0\|_{\mathbb{D}^{1,2}(\mathcal{H})}^2 &= \sum_{m \geq 1} \int_0^T \mathbb{E} \left[\|D_s^m Y_t^0\|_{\mathcal{H}}^2 \right] ds \\ &= \sum_{m \geq 1} \int_0^T \mathbb{E} \left[\left\| \sum_{k \geq 1} \lambda_k D_s^m B_t^{H_k} e_k \right\|_{\mathcal{H}}^2 \right] ds \\ &= \sum_{m \geq 1} \int_0^T \mathbb{E} \left[\|\lambda_m D_s^m B_t^{H_m} e_m\|_{\mathcal{H}}^2 \right] ds \\ &= \sum_{m \geq 1} \int_0^T \lambda_m^2 K_{H_m}^2(t, s) ds \\ &= \sum_{m \geq 1} \lambda_m^2 R_{H_m}(t, t) = \sum_{m \geq 1} \lambda_m^2 t^{2H_m} < \infty. \end{aligned}$$

Now suppose that $\|Y_t^n\|_{\mathbb{D}^{1,2}(\mathcal{H})} < \infty$ for $n \geq 0$. Due to Lemma 4.6 $b(t, Y_t^n)$ is in $\mathbb{D}^{1,2}(\mathcal{H})$ and we have for every $t \in [0, T]$ that

$$\|b(t, Y_t^n)\|_{\mathbb{D}^{1,2}(\mathcal{H})} \leq \|L\|_{\ell^2} \cdot \|M\|_{\ell^2} \cdot \|Y_t^n\|_{\mathbb{D}^{1,2}(\mathcal{H})} < \infty,$$

for some $L, M \in \ell^2$ independent of $n \geq 0$. Moreover, $\int_0^T b(r, Y_r^n) dr$ is Malliavin differentiable admitting for all $0 \leq s \leq T$ the representation

$$D_s^m \left(\int_0^T b(r, Y_r^n) dr \right) = \int_s^T D_s^m b(r, Y_r^n) dr.$$

Thus, we get for Y^{n+1} that

$$\begin{aligned} \|Y_t^{n+1}\|_{\mathbb{D}^{1,2}(\mathcal{H})} &= \left\| \left(\int_0^T b(s, Y_s^n) ds + Y_t^0 \right) \right\|_{\mathbb{D}^{1,2}(\mathcal{H})} \\ &\leq \int_0^T \|b(s, Y_s^n)\|_{\mathbb{D}^{1,2}(\mathcal{H})} ds + \|Y_t^0\|_{\mathbb{D}^{1,2}(\mathcal{H})} \\ &\leq \|L\|_{\ell^2} \cdot \|M\|_{\ell^2} \cdot \int_0^T \|Y_s^n\|_{\mathbb{D}^{1,2}(\mathcal{H})} ds + \|Y_t^0\|_{\mathbb{D}^{1,2}(\mathcal{H})} < \infty. \end{aligned}$$

Hence, Y^{n+1} is Malliavin differentiable in the sense of Definition 4.5. Moreover, we can find a positive constant A depending on L, M, λ and T such that

$$\|Y_t^n\|_{\mathbb{D}^{1,2}(\mathcal{H})} \leq \sum_{k=0}^n \frac{A^{k+1}}{k!} t^k \leq A \cdot e^{At}.$$

Consequently, $\|Y_t^n\|_{\mathbb{D}^{1,2}(\mathcal{H})}^2$ is uniformly bounded in $n \geq 0$ and therefore, since $Y^n \rightarrow X$ in $L^2([0, T] \times \Omega)$ and the Malliavin derivative is a closable operator, also X is Malliavin differentiable in the sense of Definition 4.5. □

Let us finally put the previous results together and show that SDE Eq. 24 has a unique Malliavin differentiable strong solution.

Corollary 4.8 *Let $b^{d,\varepsilon} : [0, T] \times \mathcal{H} \rightarrow \mathcal{H}$ be defined as in Eq. 26. Then, SDE Eq. 24 has a unique strong solution $(X_t^{d,\varepsilon})_{t \in [0, T]}$ which is Malliavin differentiable. Furthermore, the Malliavin derivative $D_s^m X_t^{d,\varepsilon}$ has for $0 \leq s < t \leq T$ a.s. the representation*

$$D_s^m X_t^{d,\varepsilon} = \lambda_m K_{H_m}(t, s) e_m + \lambda_m \sum_{n \geq 1} \int_{\Delta_{s,t}^n} K_{H_m}(u_1, s) \sum_{\eta_0, \dots, \eta_{n-1}=1}^d \left(\prod_{j=1}^n \partial_{\eta_j} \tilde{b}_{\eta_{j-1}}^{d,\varepsilon} \left(u_j, \tau X_{u_j}^{d,\varepsilon} \right) \right) e_{\eta_0} du, \tag{36}$$

where $\eta_n = m$ and $\tilde{b}^{d,\varepsilon} : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^d$ is defined as in Eq. 27.

Proof If the drift function $b^{d,\varepsilon}$ is in the class $\mathcal{L}_0([0, T] \times \mathcal{H}, \mathcal{H})$, then SDE Eq. 24 has a unique Malliavin differentiable strong solution by Propositions 4.4 and 4.7. Thus we merely need to show that $b^{d,\varepsilon}(t, \cdot) \in \mathcal{L}_0(\mathcal{H})$ uniformly in $t \in [0, T]$. Let $t \in [0, T]$ and $y, z \in \mathcal{H}$. Then, using the triangular inequality and the mean-value theorem we get for all $1 \leq k \leq d$ that

$$\begin{aligned} \left| \left\langle b^{d,\varepsilon}(t, y) - b^{d,\varepsilon}(t, z), e_k \right\rangle_{\mathcal{H}} \right| &= \left| b_k^{d,\varepsilon}(t, y) - b_k^{d,\varepsilon}(t, z) \right| = \left| \tilde{b}_k^{d,\varepsilon}(t, \tau^{-1}y) - \tilde{b}_k^{d,\varepsilon}(t, \tau^{-1}z) \right| \\ &\leq \sum_{i=1}^d \left| \tilde{b}_k^{d,\varepsilon} \left(t, \sum_{j=1}^{i-1} z_j \tilde{e}_j + \sum_{j=i}^d y_j \tilde{e}_j \right) - \tilde{b}_k^{d,\varepsilon} \left(t, \sum_{j=1}^i z_j \tilde{e}_j + \sum_{j=i+1}^d y_j \tilde{e}_j \right) \right| \\ &\leq \sum_{i=1}^d \sup_{\xi \in \mathbb{R}^d} |\partial_i \tilde{b}_k^{d,\varepsilon}(t, \xi)| |y_i - z_i| = \sum_{i=1}^d \sup_{\xi \in \mathbb{R}^d} |\partial_i \tilde{b}_k^{d,\varepsilon}(t, \xi)| |y - z, e_i|. \end{aligned}$$

Note that we can find sequences $\{L_k\}_{1 \leq k \leq d}$ and $\{M_i\}_{1 \leq i \leq d}$ such that for all $1 \leq k, i \leq d$ we have $\sup_{\xi \in \mathbb{R}^d} |\partial_i \tilde{b}_k^{d,\varepsilon}(t, \xi)| \leq L_k \cdot M_i$. Hence, $b^{d,\varepsilon} \in \mathcal{L}_0([0, T] \times \mathcal{H}; \mathcal{H})$.

It is left to show that representation Eq. 36 holds. First note that due to the definition of the Malliavin derivative of a random variable Y with values in \mathcal{H} , see Definition 4.5, we have that $D^m(\tau Y) = \tau D^m Y$, for all $m \geq 1$. Consequently, we get for $0 \leq s < t \leq T$ using Lemma 4.6 that the Malliavin derivative $D_s^m X_t^{d,\varepsilon}$ can be written as

$$D_s^m X_t^{d,\varepsilon} = \tau^{-1} D_s^m \tilde{X}_t^{d,\varepsilon} = \int_s^t \nabla \tilde{b}^{d,\varepsilon} \left(u, \tilde{X}_u^{d,\varepsilon} \right) D_s^m X_u^{d,\varepsilon} du + D_s^m \mathbb{B}_t.$$

Iterating this step yields

$$D_s^m X_t^{d,\varepsilon} = \sum_{n \geq 1} \int_{\Delta_{s,t}^n} \left(\prod_{j=1}^n \nabla \tilde{b}^{d,\varepsilon} \left(u_j, \tilde{X}_{u_j}^{d,\varepsilon} \right) \right) \lambda_m K_{H_m}(u_1, s) e_m du + \lambda_m K_{H_m}(t, s) e_m.$$

Further note that

$$\nabla \tilde{b}^{d,\varepsilon} \left(u_j, \tilde{X}_{u_j}^{d,\varepsilon} \right) = \nabla \left(\sum_{k=1}^d \tilde{b}_k^{d,\varepsilon} \left(u_j, \tilde{X}_{u_j}^{d,\varepsilon} \right) e_k \right) = \sum_{l=1}^d \sum_{k=1}^d \partial_l \tilde{b}_k^{d,\varepsilon} \left(u_j, \tilde{X}_{u_j}^{d,\varepsilon} \right) e_k e_l^\top.$$

Thus, we get for every $n \geq 1$

$$\prod_{j=1}^n \nabla \tilde{b}^{d,\varepsilon} \left(u_j, \tilde{X}_{u_j}^{d,\varepsilon} \right) = \sum_{l=1}^d \sum_{k=1}^d \left(\sum_{\eta_1, \dots, \eta_{n-1}=1}^d \prod_{j=1}^n \partial_{\eta_j} \tilde{b}_{\eta_{j-1}}^{d,\varepsilon} \left(u_j, \tilde{X}_{u_j}^{d,\varepsilon} \right) \right) e_k e_l^\top, \tag{37}$$

where $\eta_0 = k$ and $\eta_n = l$ and consequently, representation Eq. 36 holds. □

4.3 Weak Convergence

In this step we show that the sequence of unique strong solutions $\{X^{d,\varepsilon}\}_{d \geq 1, \varepsilon > 0}$ of the approximating SDEs Eq. 24 converge weakly to the weak solution of Eq. 3 where $b \in \mathfrak{B}([0, T] \times \mathcal{H}; \mathcal{H})$.

Lemma 4.9 *Let $b \in \mathfrak{B}([0, T] \times \mathcal{H}; \mathcal{H})$. Furthermore, let $(X_t)_{t \in [0, T]}$ be the weak solution of Eq. 3. Consider the approximating sequence of strong solutions $\{(X_t^{d,\varepsilon})_{t \in [0, T]}\}_{d \geq 1, \varepsilon > 0}$ of SDEs Eq. 24, where $b^{d,\varepsilon} : [0, T] \times \mathcal{H} \rightarrow \mathcal{H}$ is defined as in Eq. 26. Then, for every $t \in [0, T]$ and for any bounded continuous function $\phi : \mathcal{H} \rightarrow \mathbb{R}$*

$$\phi(X_t^{d,\varepsilon}) \xrightarrow{d \rightarrow \infty, \varepsilon \rightarrow 0} \mathbb{E} \left[\phi(X_t) | \mathcal{F}_t^W \right],$$

weakly in $L^2(\Omega, \mathcal{F}^W)$.

Proof Using the Wiener transform

$$\mathcal{W}(Z)(f) := \mathbb{E} \left[Z \mathcal{E} \left(\int_0^T \langle f(s), dW_s \rangle_{\mathcal{H}} \right) \right],$$

of some random variable $Z \in L^2(\Omega, \mathcal{F}_T^W)$ in $f \in L^2([0, T]; \mathcal{H})$, it suffices to show for any arbitrary $f \in L^2([0, T]; \mathcal{H})$ that

$$\mathcal{W}(\phi(X_t^{d,\varepsilon}))(f) \xrightarrow{d \rightarrow \infty, \varepsilon \rightarrow 0} \mathcal{W} \left(\mathbb{E} \left[\phi(X_t) | \mathcal{F}_t^W \right] \right) (f).$$

So, let $f \in L^2([0, T]; \mathcal{H})$ be arbitrary, then by using Girsanov's theorem we get

$$\begin{aligned} & \left| \mathcal{W}(\phi(X_t^{d,\varepsilon}))(f) - \mathcal{W} \left(\mathbb{E} \left[\phi(X_t) | \mathcal{F}_t^W \right] \right) (f) \right| \\ &= \left| \mathbb{E} \left[\phi(\mathbb{B}_t^x) \mathcal{E} \left(\int_0^T \left\langle f(s) + \left(\sum_{k=1}^d K_{H_k}^{-1} \left(\int_0^\cdot b_k^{d,\varepsilon}(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) e_k \right), dW_s \right\rangle_{\mathcal{H}} \right) \right] \right. \\ & \quad \left. - \mathbb{E} \left[\phi(\mathbb{B}_t^x) \mathcal{E} \left(\int_0^T \left\langle f(s) + \left(\sum_{k \geq 1} K_{H_k}^{-1} \left(\int_0^\cdot b_k(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) e_k \right), dW_s \right\rangle_{\mathcal{H}} \right) \right] \right| \\ & \lesssim \mathbb{E} \left[\left| \mathcal{E} \left(\int_0^T \left\langle f(s) + \left(\sum_{k=1}^d K_{H_k}^{-1} \left(\int_0^\cdot b_k^{d,\varepsilon}(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) e_k \right), dW_s \right\rangle_{\mathcal{H}} \right) \right. \right. \right. \\ & \quad \left. \left. - \mathcal{E} \left(\int_0^T \left\langle f(s) + \left(\sum_{k \geq 1} K_{H_k}^{-1} \left(\int_0^\cdot b_k(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) e_k \right), dW_s \right\rangle_{\mathcal{H}} \right) \right| \right]. \end{aligned}$$

Using the inequality

$$|e^x - e^y| \leq |x - y| (e^x + e^y) \quad \forall x, y \in \mathbb{R},$$

we get

$$\begin{aligned}
 & \left| \mathcal{W}(\phi(X_t^{d,\varepsilon}))(f) - \mathcal{W}\left(\mathbb{E}\left[\phi(X_t) | \mathcal{F}_t^W\right]\right)(f) \right| \\
 & \leq \mathbb{E} \left[\int_0^T \left\langle f(s) + \left(\sum_{k=1}^d K_{H_k}^{-1} \left(\int_0^\cdot b_k^{d,\varepsilon}(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) e_k \right), dW_s \right\rangle_{\mathcal{H}} \right. \\
 & \quad \left. - \int_0^T \left\langle f(s) + \left(\sum_{k \geq 1} K_{H_k}^{-1} \left(\int_0^\cdot b_k(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) e_k \right), dW_s \right\rangle_{\mathcal{H}} \right] \\
 & \quad + \mathbb{E} \left[\int_0^T \left\langle \left(f(s) + \left(\sum_{k=1}^d K_{H_k}^{-1} \left(\int_0^\cdot b_k^{d,\varepsilon}(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) e_k \right) \right)^2, ds \right\rangle_{\mathcal{H}} \right. \\
 & \quad \left. - \int_0^T \left\langle \left(f(s) + \left(\sum_{k \geq 1} K_{H_k}^{-1} \left(\int_0^\cdot b_k(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) e_k \right) \right)^2, ds \right\rangle_{\mathcal{H}} \right] \\
 & \leq \mathbb{E} \left[\sum_{k=1}^d \int_0^T K_{H_k}^{-1} \left(\int_0^\cdot b_k^{d,\varepsilon}(u, \mathbb{B}_u^x) \lambda_k^{-1} - b_k(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) dW_s^{(k)} \right. \\
 & \quad \left. - \sum_{k \geq d+1} \int_0^T K_{H_k}^{-1} \left(\int_0^\cdot b_k(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) dW_s^{(k)} \right] \\
 & \quad + A_{d,\varepsilon}(f),
 \end{aligned}$$

where

$$\begin{aligned}
 A_{d,\varepsilon}(f) := & \mathbb{E} \left[\int_0^T \left\langle \left(f(s) + \left(\sum_{k=1}^d K_{H_k}^{-1} \left(\int_0^\cdot b_k^{d,\varepsilon}(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) e_k \right) \right)^2, ds \right\rangle_{\mathcal{H}} \right. \\
 & \left. - \int_0^T \left\langle \left(f(s) + \left(\sum_{k \geq 1} K_{H_k}^{-1} \left(\int_0^\cdot b_k(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) e_k \right) \right)^2, ds \right\rangle_{\mathcal{H}} \right].
 \end{aligned}$$

For every $k \geq 1$, we get with representation Eq. 18 that

$$\begin{aligned}
 \mathcal{K}_{H_k}^{-1}(d, \varepsilon, s) & := K_{H_k}^{-1} \left(\int_0^\cdot b_k^{d,\varepsilon}(u, \mathbb{B}_u^x) \lambda_k^{-1} - b_k(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) \\
 & = s^{H_k - \frac{1}{2}} I_{0+}^{\frac{1}{2} - H_k} s^{\frac{1}{2} - H_k} \left(b_k^{d,\varepsilon}(s, \mathbb{B}_s^x) - b_k(s, \mathbb{B}_s^x) \right) \lambda_k^{-1} \\
 & = \frac{\lambda_k^{-1}}{\Gamma\left(\frac{1}{2} - H_k\right)} \int_0^s \left(\frac{u}{s}\right)^{\frac{1}{2} - H_k} (s - u)^{-\frac{1}{2} - H_k} \left(b_k^{d,\varepsilon}(u, \mathbb{B}_u^x) - b_k(u, \mathbb{B}_u^x) \right) du,
 \end{aligned}$$

which is bounded by

$$\begin{aligned}
 \left| \mathcal{K}_{H_k}^{-1}(d, \varepsilon, s) \right| & \leq 2 \frac{C_k}{\Gamma\left(\frac{1}{2} - H_k\right)} \int_0^s \left(\frac{u}{s}\right)^{\frac{1}{2} - H_k} (s - u)^{-\frac{1}{2} - H_k} du \\
 & = 2 \frac{C_k}{\Gamma\left(\frac{1}{2} - H_k\right)} s^{\frac{1}{2} - H_k} \beta\left(\frac{3}{2} - H_k, \frac{1}{2} - H_k\right) \lesssim C_k.
 \end{aligned}$$

Consequently, we get for every $d \geq 1$ using the Burkholder-Davis-Gundy inequality that

$$\mathbb{E} \left[\left| \sum_{k=1}^d \int_0^T \mathcal{K}_{H_k}^{-1}(d, \varepsilon, s) dW_s^{(k)} \right|^2 \right] \leq \sum_{k=1}^d \mathbb{E} \left[\int_0^T \left| \mathcal{K}_{H_k}^{-1}(d, \varepsilon, s) \right|^2 ds \right] \lesssim \sum_{k \geq 1} C_k < \infty.$$

Hence, by dominated convergence

$$\lim_{d \rightarrow \infty} \lim_{\varepsilon \rightarrow 0} \mathbb{E} \left[\left| \sum_{k=1}^d \int_0^T \mathcal{K}_{H_k}^{-1}(d, \varepsilon, s) dW_s^{(k)} \right|^2 \right] = 0.$$

Equivalently, we have

$$\mathbb{E} \left[\left| \int_0^T \sum_{k \geq d+1} K_{H_k}^{-1} \left(\int_0^\cdot b_k(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) dW_s^{(k)} \right|^2 \right] \lesssim \sum_{k \geq 1} C_k < \infty.$$

Thus, again by dominated convergence

$$\lim_{d \rightarrow \infty} \lim_{\varepsilon \rightarrow 0} \mathbb{E} \left[\left| \int_0^T \sum_{k \geq d+1} K_{H_k}^{-1} \left(\int_0^\cdot b_k(u, \mathbb{B}_u^x) \lambda_k^{-1} du \right) (s) dW_s^{(k)} \right|^2 \right] = 0.$$

Similarly, one can show that $A_{d,\varepsilon}(f)$ vanishes for every $f \in L^2([0, T]; \mathcal{H})$ as $\varepsilon \rightarrow 0$ and $d \rightarrow \infty$. Consequently, $\phi(X_t^{d,\varepsilon}) \xrightarrow{d \rightarrow \infty, \varepsilon \rightarrow 0} \mathbb{E}[\phi(X_t) | \mathcal{F}_t^W]$ weakly in $L^2(\Omega, \mathcal{F}_t^W)$. \square

4.4 Application of the Compactness Criterion

Theorem 4.10 *The double-sequence $\{X_t^{d,\varepsilon}\}_{d \geq 1, \varepsilon > 0}$ of strong solutions of SDE Eq. 24 is relatively compact in $L^2(\Omega, \mathcal{F}_t^W)$.*

Proof We are aiming at applying the compactness criterion given in Theorem A.3. Therefore, let $0 < \alpha_m < \beta_m < \frac{1}{2}$ and $\gamma_m > 0$ for all $m \geq 1$ and define the sequence $\mu_{s,m} = 2^{-i\alpha_m} \gamma_m$, if $s = 2^i + j$, $i \geq 0$, $0 \leq j \leq 2^i$, $m \geq 1$ where $\mu_{s,m} \rightarrow 0$ for $s, m \rightarrow \infty$. We have to check that there exists a uniform constant C such that for all $\{X_t^{d,\varepsilon}\}_{d \geq 1, \varepsilon > 0}$

$$\|X_t^{d,\varepsilon}\|_{L^2(\Omega; \mathcal{H})} \leq C, \tag{38}$$

$$\sum_{m \geq 1} \gamma_m^{-2} \|D^m X_t^{d,\varepsilon}\|_{L^2(\Omega; L^2([0,T]; \mathcal{H}))}^2 \leq C,$$

and

$$\sum_{m \geq 1} \frac{1}{(1 - 2^{-2(\beta_m - \alpha_m)}) \gamma_m^2} \int_0^T \int_0^T \frac{\|D_s^m X_t^{d,\varepsilon} - D_u^m X_t^{d,\varepsilon}\|_{L^2(\Omega; \mathcal{H})}^2}{|s - u|^{1+2\beta_m}} ds du \leq C. \tag{39}$$

Note first that Eq. 38 is fulfilled due to the uniform boundedness of $\{b^{d,\varepsilon}\}_{d \geq 1, \varepsilon > 0}$ and the definition of the process $(\mathbb{B}_t)_{t \in [0, T]}$, see Eq. 20.

Next we show uniform boundedness of Eq. 39. Note first that under the assumption $u \leq s$ we have

$$\begin{aligned} D_s^m X_t^{d,\varepsilon} - D_u^m X_t^{d,\varepsilon} &= \lambda_m (K_{H_m}(t, s) - K_{H_m}(t, u)) e_m \\ &+ \int_s^t \nabla \tilde{b}^{d,\varepsilon}(v, \tilde{X}_v^{d,\varepsilon}) D_s^m X_v^{d,\varepsilon} dv - \int_u^t \nabla \tilde{b}^{d,\varepsilon}(v, \tilde{X}_v^{d,\varepsilon}) D_u^m X_v^{d,\varepsilon} dv \\ &= \lambda_m (K_{H_m}(t, s) - K_{H_m}(t, u)) e_m - \int_u^s \nabla \tilde{b}^{d,\varepsilon}(v, \tilde{X}_v^{d,\varepsilon}) D_u^m X_v^{d,\varepsilon} dv \\ &+ \int_s^t \nabla \tilde{b}^{d,\varepsilon}(v, \tilde{X}_v^{d,\varepsilon}) (D_s^m X_v^{d,\varepsilon} - D_u^m X_v^{d,\varepsilon}) dv \\ &= \lambda_m (K_{H_m}(t, s) - K_{H_m}(t, u)) e_m - D_u^m X_s^{d,\varepsilon} + \lambda_m K_{H_m}(s, u) e_m \\ &+ \int_s^t \nabla \tilde{b}^{d,\varepsilon}(v, \tilde{X}_v^{d,\varepsilon}) (D_s^m X_v^{d,\varepsilon} - D_u^m X_v^{d,\varepsilon}) dv. \end{aligned}$$

Using iteration we obtain the representation

$$\begin{aligned} D_s^m X_t^{d,\varepsilon} - D_u^m X_t^{d,\varepsilon} &= \lambda_m (K_{H_m}(t, s) - K_{H_m}(t, u)) e_m \\ &+ \lambda_m \sum_{n \geq 1} \int_{\Delta_{s,t}^n} \prod_{j=1}^n \nabla \tilde{b}^{d,\varepsilon}(v_j, \tilde{X}_{v_j}^{d,\varepsilon}) (K_{H_m}(v_1, s) - K_{H_m}(v_1, u)) e_m dv \\ &+ \left(\text{Id} + \sum_{n \geq 1} \int_{\Delta_{s,t}^n} \prod_{j=1}^n \nabla \tilde{b}^{d,\varepsilon}(v_j, \tilde{X}_{v_j}^{d,\varepsilon}) dv \right) (\lambda_m K_{H_m}(s, u) e_m - D_u^m X_s^{d,\varepsilon}), \end{aligned}$$

where by Corollary 4.8

$$\begin{aligned} &(\lambda_m K_{H_m}(s, u) e_m - D_u^m X_s^{d,\varepsilon}) = \\ &- \lambda_m \sum_{n \geq 1} \int_{\Delta_{u,s}^n} K_{H_m}(v_1, u) \sum_{\eta_0, \dots, \eta_{n-1}=1}^d \prod_{j=1}^n \partial_{\eta_j} \tilde{b}_{\eta_{j-1}}^{d,\varepsilon}(v_j, \tilde{X}_{v_j}^{d,\varepsilon}) e_{\eta_0} dv. \end{aligned}$$

Consequently, we get due to Eq. 37 that

$$D_s^m X_t^{d,\varepsilon} - D_u^m X_t^{d,\varepsilon} = \lambda_m (\mathfrak{J}_1 + \mathfrak{J}_2 + \mathfrak{J}_3),$$

where

$$\begin{aligned} \mathfrak{J}_1 &:= (K_{H_m}(t, s) - K_{H_m}(t, u)) e_m, \\ \mathfrak{J}_2 &:= \sum_{n \geq 1} \int_{\Delta_{s,t}^n} (K_{H_m}(v_1, s) - K_{H_m}(v_1, u)) \sum_{\eta_0, \dots, \eta_{n-1}=1}^d \prod_{j=1}^n \partial_{\eta_j} \tilde{b}_{\eta_{j-1}}^{d,\varepsilon}(v_j, \tilde{X}_{v_j}^{d,\varepsilon}) e_{\eta_0} dv, \\ \mathfrak{J}_3 &:= - \left(\text{Id} + \sum_{n \geq 1} \int_{\Delta_{s,t}^n} \sum_{\eta_0, \dots, \eta_{n-1}=1}^d \prod_{j=1}^n \partial_{\eta_j} \tilde{b}_{\eta_{j-1}}^{d,\varepsilon}(v_j, \tilde{X}_{v_j}^{d,\varepsilon}) dv \right) \\ &\times \sum_{n \geq 1} \int_{\Delta_{u,s}^n} K_{H_m}(v_1, u) \sum_{\eta_0, \dots, \eta_{n-1}=1}^d \prod_{j=1}^n \partial_{\eta_j} \tilde{b}_{\eta_{j-1}}^{d,\varepsilon}(v_j, \tilde{X}_{v_j}^{d,\varepsilon}) e_{\eta_0} dv. \end{aligned}$$

In the following we consider each $\mathfrak{J}_i, i = 1, 2, 3$, separately starting with the first. Due to Lemma B.3 there exists $\beta_1 \in (0, \frac{1}{2})$ and a constant $K_1 > 0$ such that

$$\int_0^t \int_0^t \frac{\|\mathfrak{J}_1\|_{L^2(\Omega; \mathcal{H})}^2}{|s - u|^{1+2\beta_1}} ds du = \int_0^t \int_0^t \frac{|K_{H_m}(t, s) - K_{H_m}(t, u)|}{|s - u|^{1+2\beta_1}} ds du \leq K_1 < \infty.$$

Consider now \mathfrak{J}_2 . Define the density \mathcal{E}_t^d by

$$\mathcal{E}_t^d := \exp \left\{ \sum_{k=1}^d \left(\int_0^t K_{H_k}^{-1} \left(\int_0^\cdot b_k^{d,\varepsilon} (u, X_u^{d,\varepsilon}) \lambda_k^{-1} du \right) (s) dW_s^{(k)} - \frac{1}{2} \int_0^t K_{H_k}^{-1} \left(\int_0^\cdot b_k^{d,\varepsilon} (u, X_u^{d,\varepsilon}) \lambda_k^{-1} du \right)^2 (s) ds \right) \right\}.$$

Then applying Girsanov’s Theorem 2.2, monotone convergence and noting that $\sup_{d \geq 1} \sup_{t \in [0, T]} \|\mathcal{E}_t^d\|_{L^4(\Omega)} < \infty$ yields

$$\begin{aligned} & \|\mathfrak{J}_2\|_{L^2(\Omega; \mathcal{H})}^2 \\ & \leq \sum_{n \geq 1} \sum_{\eta_0, \dots, \eta_{n-1}=1}^d \left\| \mathcal{E}_t^d \int_{\Delta_{s,t}^n} (K_{H_m}(v_1, s) - K_{H_m}(v_1, u)) \prod_{j=1}^n \partial_{\eta_j} \tilde{b}_{\eta_{j-1}}^{d,\varepsilon} (v_j, \tau \mathbb{B}_{v_j}^x) dv \right\|_{L^2(\Omega)}^2 \\ & \lesssim \sum_{n \geq 1} \sum_{\eta_0, \dots, \eta_{n-1}=1}^d \left\| \int_{\Delta_{s,t}^n} (K_{H_m}(v_1, s) - K_{H_m}(v_1, u)) \prod_{j=1}^n \partial_{\eta_j} \tilde{b}_{\eta_{j-1}}^{d,\varepsilon} (v_j, \tau \mathbb{B}_{v_j}^x) dv \right\|_{L^4(\Omega)}^2. \end{aligned}$$

Using Eq. 9 yields that

$$|\mathfrak{Q}_2|^2 := \left| \int_{\Delta_{s,t}^n} (K_{H_m}(v_1, s) - K_{H_m}(v_1, u)) \prod_{j=1}^n \partial_{\eta_j} \tilde{b}_{\eta_{j-1}}^{d,\varepsilon} (v_j, \tau \mathbb{B}_{v_j}^x) dv \right|^2$$

can be written as

$$|\mathfrak{Q}_2|^2 = \sum_{\sigma \in \mathcal{S}(n, n)} \int_{\Delta_{s,t}^{2n}} \left(\prod_{j=1}^{2n} g_{[\sigma(j)]} (v_j, \tau \mathbb{B}_{v_j}^x) \right) \left(\prod_{i=0}^1 (K_{H_m}(v_{(in+1)}, s) - K_{H_m}(v_{(in+1)}, u)) \right) dv$$

where for $j = 1, \dots, n$

$$g_j (\cdot, \tau \mathbb{B}^x) = \partial_{\eta_j} \tilde{b}_{\eta_{j-1}}^{d,\varepsilon} (\cdot, \tau \mathbb{B}^x)$$

Repeating the application of Eq. 9 yields

$$\begin{aligned} |\mathfrak{Q}_2|^4 & = \sum_{\sigma \in \mathcal{S}(4; n)} \int_{\Delta_{s,t}^{4n}} \left(\prod_{j=1}^{4n} g_{[\sigma(j)]} (v_j, \tau \mathbb{B}_{v_j}^x) \right) \\ & \times \left(\prod_{i=0}^3 (K_{H_m}(v_{(in+1)}, s) - K_{H_m}(v_{(in+1)}, u)) \right) dv. \end{aligned}$$

Defining $f_j^{d,\varepsilon}(t, \tilde{y}) := \tilde{b}_{\eta_{j-1}}^{d,\varepsilon}(t, \sqrt{Q}\sqrt{K}\tilde{y})$ permits the use of Proposition B.2 with $\sum_{j=1}^{4n} \varepsilon_j = 4, |\alpha_j| = 1$ for all $1 \leq j \leq 4n$ and thus $|\alpha| = 4n$. Consequently, we get using the assumptions on H and b that

$$\begin{aligned} \mathbb{E}[|\mathfrak{A}_2|^4] &= \left\| \int_{\Delta_{s,t}^n} (K_{H_m}(v_1, s) - K_{H_m}(v_1, u)) \prod_{j=1}^n \partial_{\eta_j} b_{\eta_{j-1}}^{d,\varepsilon}(v_j, \tau \mathbb{B}_{v_j}^x) dv \right\|_{L^4(\Omega)}^4 \\ &\leq \#\mathcal{S}(4; n) \frac{K_{d,H}^{4n} \cdot T^{\frac{|\alpha|}{12}}}{\sqrt{2\pi}^{4dn}} \left(C_{H_m,T} \left(\frac{s-u}{su} \right)^{\gamma_m} s^{(H_m - \frac{1}{2} - \gamma_m)} \right)^{\sum_{j=1}^{4n} \varepsilon_j} \\ &\quad \times \prod_{j=1}^n \left\| \tilde{b}_{\eta_{j-1}}^{d,\varepsilon}(\cdot, \sqrt{Q}\sqrt{K}z_j) \right\|_{L^1(\mathbb{R}^d; L^\infty([0,T])}^4 \\ &\quad \times \frac{\left(\prod_{k=1}^d (2|\alpha^{(k)}|)! \right)^{\frac{1}{4}} (t-s)^{-\sum_{k=1}^d H_k(4n+2|\alpha^{(k)}|) + (H_m - \frac{1}{2} - \gamma_m) \sum_{j=1}^{4n} \varepsilon_j + 4n}}{\Gamma(8n - \sum_{k=1}^d H_k(8n+4|\alpha^{(k)}|) + 2(H_m - \frac{1}{2} - \gamma_m) \sum_{j=1}^{4n} \varepsilon_j)^{\frac{1}{2}}} \\ &\leq 2^{8n} \frac{K_{d,H}^{4n} \cdot T^{\frac{n}{3}}}{\sqrt{2\pi}^{4dn}} C_{H_m,T}^4 \prod_{j=1}^n D_{\eta_{j-1}}^4 \lambda_{\eta_{j-1}}^4 \\ &\quad \times \left(\frac{s-u}{su} \right)^{4\gamma_m} s^{4(H_m - \frac{1}{2} - \gamma_m)} (t-s)^{4(H_m - \frac{1}{2} - \gamma_m)} T^{4n} S_n, \end{aligned}$$

where

$$S_n = \sup_n \frac{\left(\prod_{k=1}^d (2|\alpha^{(k)}|)! \right)^{\frac{1}{4}}}{\Gamma\left(8n - \sum_{k=1}^d H_k(8n+4|\alpha^{(k)}|) + 8\left(H_m - \frac{1}{2} - \gamma_m\right)\right)^{\frac{1}{2}}}.$$

For $n \geq 1$ we have due to the assumptions on H that

$$\begin{aligned} A_n &:= 8n - \sum_{k=1}^d H_k(8n+4|\alpha^{(k)}|) + 8\left(H_m - \frac{1}{2} - \gamma_m\right) \\ &\geq 8n - 8n\|H\|_{\ell^1} - 16n \sup_{k \geq 1} |H_k| - 4 > \frac{16}{3}n - 4 > 0. \end{aligned}$$

Thus, we have for n sufficiently large that

$$\Gamma(A_n) \geq \Gamma\left(\frac{16}{3}n - 4\right) \sim \Gamma\left(\frac{16}{3}n + 1\right) \left(\frac{16}{3}n\right)^{-4},$$

and therefore by the approximations in Remark B.7

$$\begin{aligned}
 S_n &\leq \frac{\left(\prod_{k=1}^d (2|\alpha^{(k)}|)\right)^{\frac{1}{4}}}{\Gamma\left(8n - \sum_{k=1}^d H_k (8n + 4|\alpha^{(k)}|) + 8\left(H_m - \frac{1}{2} - \gamma_m\right)\right)^{\frac{1}{2}}} \\
 &\sim \frac{(2\pi)^{\frac{d}{8}} e^{\frac{n}{2}} ((10n)!)^{\frac{1}{4}} \left(\frac{16}{3}n\right)^2}{(20\pi n)^{\frac{1}{8}} \Gamma\left(\frac{16}{3}n + 1\right)^{\frac{1}{2}}} \\
 &\leq C^n \frac{(2\pi)^{\frac{d}{8}} ((10n)!)^{\frac{1}{4}} n^{\frac{15}{8}}}{\Gamma\left(\frac{16}{3}n + 1\right)^{\frac{1}{2}}},
 \end{aligned}$$

where $C > 0$ is a constant which may in the following vary from line to line. Using Stirling’s formula we have moreover that

$$\frac{(10n)!}{\Gamma\left(\frac{16}{3}n + 1\right)^2} \leq \frac{e^{\frac{1}{120n}} \sqrt{20\pi n} \left(\frac{10n}{e}\right)^{10n}}{\frac{32}{3}\pi n \left(\frac{16}{3}n\right)^{\frac{32}{3}n}} \leq \frac{C^n}{\sqrt{\frac{4}{3}n}} \left(\frac{2}{3}n\right)^{-\frac{2}{3}n} \leq \frac{C^n}{\Gamma\left(\frac{2}{3}n + 1\right)}.$$

Consequently, we have for S_n that

$$S_n \sim C^n (2\pi)^{\frac{d}{8}} n^{\frac{15}{8}} \left(\frac{1}{\Gamma\left(\frac{2}{3}n + 1\right)}\right)^{\frac{1}{4}}.$$

Furthermore, using Lemma C.4 we have for every $n \geq 1$ that

$$\sum_{\eta_0, \dots, \eta_{n-1}=1}^d \prod_{j=1}^n D_{\eta_{j-1}}^4 \lambda_{\eta_{j-1}}^4 = \left(\sum_{k=1}^d D_k^4 \lambda_k^4\right)^n.$$

Moreover, due to the assumptions on H there exists a finite constant $K > 0$ which is independent of d and H such that $K_{d,H} \leq K$, cf. Eq. 62. Consequently, there exists a constant $C > 0$ independent of d , ε and n such that for n sufficiently large

$$\begin{aligned}
 \mathcal{D}_n^2 &:= \sum_{\eta_0, \dots, \eta_{n-1}=1}^d 2^{8n} \frac{K_{d,H}^{4n} \cdot T^{\frac{n}{3}}}{\sqrt{2\pi}^{4dn}} \left(\prod_{j=1}^n D_{\eta_{j-1}}^4 \lambda_{\eta_{j-1}}^4\right) T^{4n} S_n \\
 &\sim \left(\frac{n^{\frac{15}{2}} C^n}{\Gamma\left(\frac{2}{3}n + 1\right)}\right)^{\frac{1}{4}}
 \end{aligned}$$

and thus due to the comparison test

$$\sum_{n \geq 1} \mathcal{D}_n < \infty.$$

Hence, there exists a constant $C_2 > 0$ independent of d and ε such that

$$\|\mathfrak{J}_2\|_{L^2(\Omega; \mathcal{H})}^2 \leq C_2 C_{H_m, T}^4 \left(\frac{s-u}{su}\right)^{2\gamma_m} s^{2(H_m - \frac{1}{2} - \gamma_m)} (t-s)^{2(H_m - \frac{1}{2} - \gamma_m)},$$

and thus we can find a $\beta_2 \in \left(0, \frac{1}{2}\right)$ sufficiently small such that

$$\int_0^t \int_0^t \frac{\|\mathfrak{J}_2\|_{L^2(\Omega; \mathcal{H})}^2}{|s-u|^{1+2\beta_2}} dsdu \lesssim C_{H_m, T}^4 < \infty.$$

Equivalently, we can show for \mathfrak{J}_3 that there exists a $\beta_3 \in \left(0, \frac{1}{2}\right)$ such that

$$\int_0^t \int_0^t \frac{\|\mathfrak{J}_3\|_{L^2(\Omega; \mathcal{H})}^2}{|s-u|^{1+2\beta_2}} dsdu \lesssim C_{H_m, T}^4 < \infty,$$

where $C_{H_m, T} = C \cdot c_{H_m}$ due to Lemma B.4. Here, c_{H_m} is the constant in Eq. 14. Thus, we can find a constant $C > 0$ independent of H_m such that $\sup_{H \in (0, \frac{1}{6})} C_{H, T} \leq C < \infty$.

Finally, we get with $\beta_m := \min\{\beta_1, \beta_2, \beta_3\}$ that we can find $\gamma_m, m \geq 1$, such that

$$\begin{aligned} & \sum_{m \geq 1} \frac{1}{(1 - 2^{-2(\beta_m - \alpha_m)})\gamma_m^2} \int_0^t \int_0^t \frac{\|D_s^m X_t^{d, \varepsilon} - D_u^m X_t^{d, \varepsilon}\|_{L^2(\Omega; \mathcal{H})}^2}{|s-u|^{1+2\beta_m}} dsdu \\ & \leq \sum_{m \geq 1} \frac{1}{(1 - 2^{-2(\beta_m - \alpha_m)})\gamma_m^2} \int_0^t \int_0^t \frac{\lambda_m^2 \sum_{l=1}^3 \|\mathfrak{J}_l\|_{L^2(\Omega; \mathcal{H})}^2}{|s-u|^{1+2\beta_m}} dsdu \\ & \lesssim \sum_{m \geq 1} \frac{\lambda_m^2 \tilde{C}^4}{(1 - 2^{-2(\beta_m - \alpha_m)})\gamma_m^2} < \infty, \end{aligned}$$

uniformly in $d \geq 1$ and $\varepsilon > 0$. Similarly, we can show that

$$\sum_{m \geq 1} \gamma_m^{-2} \|D^m X_t^{d, \varepsilon}\|_{L^2(\Omega; L^2([0, 1]; \mathcal{H}))}^2 < \infty \tag{40}$$

uniformly in $d \geq 1$ and $\varepsilon > 0$ and consequently the compactness criterion Theorem A.3 yields the result. \square

4.5 $\mathbb{F}^{\mathbb{B}}$ Adaptedness and Strong Solution

Finally, we can state and prove the main statement of this paper

Theorem 4.11 *Let $b \in \mathfrak{B}([0, T] \times \mathcal{H}; \mathcal{H})$. Then SDE Eq. 3 has a unique Malliavin differentiable strong solution.*

Proof Let $(X_t)_{t \in [0, T]}$ be a weak solution of SDE Eq. 3 which is unique in law due to Proposition 3.5. Due to Lemma 4.9 we know that for every bounded globally Lipschitz continuous function $\phi : \mathcal{H} \rightarrow \mathbb{R}$

$$\phi(X_t^{d, \varepsilon}) \xrightarrow{\varepsilon \rightarrow 0, d \rightarrow \infty} \mathbb{E}\left[\phi(X_t) | \mathcal{F}_t^W\right]$$

weakly in $L^2(\Omega, \mathcal{F}_t^W)$. Furthermore, by Theorem 4.10 there exist subsequences $\{d_k\}_{k \geq 1}$ and $\{\varepsilon_n\}_{n \geq 1}$ such that

$$\phi(X_t^{d_k, \varepsilon_n}) \xrightarrow{n \rightarrow \infty, d \rightarrow \infty} \phi\left(\mathbb{E}\left[X_t | \mathcal{F}_t^W\right]\right)$$

strongly in $L^2(\Omega, \mathcal{F}_t^W)$. Uniqueness of the limit yields that X_t is \mathcal{F}_t^W -measurable for all $t \in [0, T]$. Since $\mathbb{F}^W = \mathbb{F}^{\mathbb{B}}$, we get that $(X_t)_{t \in [0, T]}$ is a unique strong solution of SDE Eq. 3. Malliavin differentiability follows by Eq. 40 and noting that the estimate holds also for $\gamma_m \equiv 1$. □

5 Example

In this section we give an example of a drift function $b \in \mathfrak{B}([0, T] \times \mathcal{H}; \mathcal{H})$ to show that the class does not merely contain the null function.

Let $f_k \in L^1(\ell^2; L^\infty([0, T]; \ell^2))$, $k \geq 1$, i.e. for all $k \geq 1$ we have for all $z \in \ell^2$

$$\sup_{t \in [0, T]} |f_k(t, z)| \leq C_k^f < \infty \sup_{d \geq 1} \int_{\mathbb{R}^d} \sup_{t \in [0, T]} |f_k(t, z)| dz \leq D_k^f < \infty, \tag{41}$$

such that $C^f, D^f \in \ell^1$ and define for every $k \geq 1$ an operator $A_k : \mathcal{H} \rightarrow \mathcal{H}$ which is invertible on $A_k \mathcal{H}$ such that for all $k \geq 1$

$$\det \left(A_k^{-1} \sqrt{Q}^{-1} \sqrt{K}^{-1} \right) \leq \mathcal{D}_k^A < \infty,$$

where $\mathcal{D}^A \in \ell^1$. Then, we define

$$b_k(t, y) := f_k(t, \tau^{-1} A_k y).$$

This yields

$$\begin{aligned} \sup_{t \in [0, T]} |b_k(t, y)| &= \sup_{t \in [0, T]} |f_k(t, \tau^{-1} A_k y)| \leq C_k^f, \\ \int_{\mathcal{H}} \sup_{t \in [0, T]} \left| b_k \left(t, \sqrt{Q} \sqrt{K} y \right) \right| dy &= \int_{\mathcal{H}} \sup_{t \in [0, T]} \left| f_k \left(t, \tau^{-1} A_k \sqrt{Q} \sqrt{K} y \right) \right| dy \\ &= \int_{\tau^{-1} A_k \mathcal{H}} \sup_{t \in [0, T]} |f_k(t, z)| \det \left(A_k^{-1} \sqrt{Q}^{-1} \sqrt{K}^{-1} \right) dz \leq D_k^f \mathcal{D}_k^A. \end{aligned}$$

Due to the definition $C^f \in \ell^1$ and $D^f \cdot \mathcal{D}^A \in \ell^1$ and thus $b \in \mathfrak{B}([0, T] \times \mathcal{H}; \mathcal{H})$.

A possible choice for f is

$$f_k(t, z) = C_k^f \cdot e^{-t} \cdot e^{-D_k^f \frac{|z|}{2}} \left(a \mathbb{1}_{\{z \in A\}} + b \mathbb{1}_{\{z \in A^c\}} \right),$$

where $a, b \in \mathbb{R}$ and $A \subset \mathcal{H}$, which obviously fulfills the assumptions Eq. 41. The operator A_k , $k \geq 1$, can for example be chosen such that there exists a finite subset $N_k \subset \mathbb{N}$ such that for all $k \geq 1$

$$\prod_{n \in N_k} \lambda_k^{-1} \sqrt{\mathfrak{K}_{H_k}}^{-1} \leq C.$$

and we have for every $x \in \mathcal{H}$

$$A_k x = \mathcal{D}_k^A \sum_{n \in N_k} x^{(n)} e_n.$$

Then A_k is invertible on $A_k \mathcal{H}$ for every $k \geq 1$ and

$$\det \left(A_k^{-1} \sqrt{Q}^{-1} \sqrt{K}^{-1} \right) = \mathcal{D}_k^A \prod_{n \in N_k} \lambda_k^{-1} \sqrt{\mathfrak{K}_{H_k}}^{-1} \leq C \mathcal{D}_k^A.$$

Appendix A: Compactness Criterion

The following result which is originally due to [14] in the finite dimensional case and which can be e.g. found in [9], provides a compactness criterion of square integrable cylindrical Wiener processes on a Hilbert space.

Theorem A.1 *Let $(B_t)_{t \in [0, T]}$ be a cylindrical Wiener process on a separable Hilbert space \mathcal{H} with respect to a complete probability space $(\Omega, \mathcal{F}, \mu)$, where \mathcal{F} is generated by $(B_t)_{t \in [0, T]}$. Further, let $\mathcal{L}_{HS}(\mathcal{H}, \mathbb{R})$ be the space of Hilbert-Schmidt operators from \mathcal{H} to \mathbb{R} and let $D : \mathbb{D}^{1,2} \rightarrow L^2(\Omega; L^2([0, T]) \otimes \mathcal{L}_{HS}(\mathcal{H}, \mathbb{R}))$ be the Malliavin derivative in the direction of $(B_t)_{t \in [0, T]}$, where $\mathbb{D}^{1,2}$ is the space of Malliavin differentiable random variables in $L^2(\Omega)$.*

Suppose that C is a self-adjoint compact operator on $L^2([0, T]) \otimes \mathcal{L}_{HS}(\mathcal{H}, \mathbb{R})$ with dense image. Then for any $c > 0$ the set

$$\mathcal{G} = \left\{ G \in \mathbb{D}^{1,2} : \|G\|_{L^2(\Omega)} + \|C^{-1}DG\|_{L^2(\Omega; L^2([0, T]) \otimes \mathcal{L}_{HS}(\mathcal{H}, \mathbb{R}))} \leq c \right\}$$

is relatively compact in $L^2(\Omega)$.

In this paper we aim at using a special case of the previous theorem, which is more suitable for explicit estimations. To this end we need the following auxiliary result from [14].

Lemma A.2 *Denote by $v_s, s \geq 0$, with $v_0 = 1$ the Haar basis of $L^2([0, 1])$. Define for any $0 < \alpha < \frac{1}{2}$ the operator A_α on $L^2([0, 1])$ by*

$$A_\alpha v_s = 2^{i\alpha} v_s, \quad \text{if } s = 2^i + j, \quad i \geq 0, \quad 0 \leq j \leq 2^i,$$

and

$$A_\alpha 1 = 1.$$

Then for $\alpha < \beta < \frac{1}{2}$ we have that

$$\|A_\alpha f\|_{L^2([0, 1])}^2 \leq 2(\|f\|_{L^2([0, 1])}^2 + \frac{1}{1 - 2^{-2(\beta - \alpha)}} \int_0^1 \int_0^1 \frac{|f(t) - f(u)|^2}{|t - u|^{1 + 2\beta}} dt du).$$

Theorem A.3 *Let D^k be the Malliavin derivative in the direction of the k -th component of $(B_t)_{t \in [0, T]}$. In addition, let $0 < \alpha_k < \beta_k < \frac{1}{2}$ and $\gamma_k > 0$ for all $k \geq 1$. Define the sequence $\mu_{s,k} = 2^{-i\alpha_k} \gamma_k$, if $s = 2^i + j, i \geq 0, 0 \leq j \leq 2^i, k \geq 1$. Assume that $\mu_{s,k} \rightarrow 0$ for $s, k \rightarrow \infty$. Let $c > 0$ and \mathcal{G} the collection of all $G \in \mathbb{D}^{1,2}$ such that*

$$\|G\|_{L^2(\Omega)} \leq c,$$

$$\sum_{k \geq 1} \gamma_k^{-2} \|D^k G\|_{L^2(\Omega; L^2([0, 1]))}^2 \leq c,$$

and

$$\sum_{k \geq 1} \frac{1}{(1 - 2^{-2(\beta_k - \alpha_k)}) \gamma_k^2} \int_0^1 \int_0^1 \frac{\|D_t^k G - D_u^k G\|_{L^2(\Omega)}^2}{|t - u|^{1 + 2\beta_k}} dt du \leq c.$$

Then \mathcal{G} is relatively compact in $L^2(\Omega)$.

Proof As before denote by $v_s, s \geq 0$, with $v_0 = 1$ the Haar basis of $L^2([0, 1])$ and by $e_k^* = \langle e_k, \cdot \rangle_H, k \geq 1$, an orthonormal basis of $\mathcal{L}_{HS}(\mathcal{H}, \mathbb{R})$, where $e_k, k \geq 0$, is an orthonormal basis of \mathcal{H} . Define a self-adjoint compact operator C on $L^2([0, 1]) \otimes \mathcal{L}_{HS}(\mathcal{H}, \mathbb{R})$ with dense image by

$$C(v_s \otimes e_k^*) = \mu_{s,k} v_s \otimes e_k^*, \quad s \geq 0, \quad k \geq 1.$$

Then it follows for $G \in \mathbb{D}^{1,2}$ from Lemma A.2 that

$$\begin{aligned} & \left\| C^{-1} DG \right\|_{L^2(\Omega; L^2([0,1]) \otimes \mathcal{L}_{HS}(\mathcal{H}, \mathbb{R}))}^2 \\ &= \sum_{k \geq 1} \sum_{s \geq 0} \mu_{s,k}^{-2} E[\langle DG, v_s \otimes e_k^* \rangle_{L^2([0,1]) \otimes \mathcal{L}_{HS}(\mathcal{H}, \mathbb{R})}^2] \\ &= \sum_{k \geq 1} \gamma_k^{-2} \left\| A_{\alpha_k} D^k G \right\|_{L^2(\Omega; L^2([0,1]))}^2 \\ &\leq 2 \sum_{k \geq 1} \gamma_k^{-2} \left\| D^k G \right\|_{L^2(\Omega; L^2([0,1]))}^2 \\ &\quad + 2 \sum_{k \geq 1} \frac{1}{(1 - 2^{-2(\beta_k - \alpha_k)}) \gamma_k^2} \int_0^1 \int_0^1 \frac{\| D_t^k G - D_u^k G \|_{L^2(\Omega)}^2}{|t - u|^{1+2\beta_k}} dt du \\ &\leq M \end{aligned}$$

for a constant $M < \infty$. So using Theorem A.1 we obtain the result. □

Appendix B: Integration by Parts Formula

In this section we derive an integration by parts formula similar to [6] which is used in the proof of Theorem 4.10 to verify the conditions of the compactness criterion Theorem A.3. Before stating the integration by parts formula, we start by giving some definitions and notations frequently used during the course of this section.

Let n be a given integer. We consider the function $f : [0, T]^n \times (\mathbb{R}^d)^n \rightarrow \mathbb{R}$ of the form

$$f(s, z) = \prod_{j=1}^n f_j(s_j, z_j), \quad s = (s_1, \dots, s_n) \in [0, T]^n, \quad z = (z_1, \dots, z_n) \in (\mathbb{R}^d)^n, \quad (42)$$

where $f_j : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}, j = 1, \dots, n$, are compactly supported smooth functions. Further, we deal with the function $\varkappa : [0, T]^n \rightarrow \mathbb{R}$ which is of the form

$$\varkappa(s) = \prod_{j=1}^n \varkappa_j(s_j), \quad s \in [0, T]^n, \quad (43)$$

with integrable factors $\varkappa_j : [0, T] \rightarrow \mathbb{R}, j = 1, \dots, n$.

Let α_j be a multi-index and D^{α_j} its corresponding differential operator. For $\alpha := (\alpha_1, \dots, \alpha_n) \in \mathbb{N}_0^{d \times n}$ we define the norm $|\alpha| = \sum_{j=1}^n \sum_{k=1}^d \alpha_j^{(k)}$ and write

$$D^\alpha f(s, z) = \prod_{j=1}^n D^{\alpha_j} f_j(s_j, z_j).$$

Let k be an arbitrary integer. Given $(s, z) = (s_1, \dots, s_{kn}, z_1, \dots, z_n) \in [0, T]^{kn} \times (\mathbb{R}^d)^n$ and a shuffle permutation $\sigma \in \mathcal{S}(n, n)$ we define the shuffled functions

$$f_\sigma(s, z) := \prod_{j=1}^{kn} f_{[\sigma(j)]}(s_j, z_{[\sigma(j)]})$$

and

$$z_\sigma(s) := \prod_{j=1}^{kn} z_{[\sigma(j)]}(s_j),$$

where $[j]$ is equal to $(j - in)$ if $(in + 1) \leq j \leq (i + 1)n, i = 0, \dots, (k - 1)$. For a multi-index α , we define

$$\Psi_\alpha^f(\theta, t, z, H, d) := \left(\prod_{k=1}^d \sqrt{(2|\alpha^{(k)}|)!} \right) \sum_{\sigma \in \mathcal{S}(n, n)} \int_{\Delta_{\theta, t}^{2n}} |f_\sigma(s, z)| |\Delta s|^{-H(1+\alpha_{[\sigma(\Delta)]})} ds, \tag{44}$$

and

$$\Psi_\alpha^z(\theta, t, H, d) := \left(\prod_{k=1}^d \sqrt{(2|\alpha^{(k)}|)!} \right) \sum_{\sigma \in \mathcal{S}(n, n)} \int_{\Delta_{\theta, t}^{2n}} |z_\sigma(s)| |\Delta s|^{-H(1+\alpha_{[\sigma(\Delta)]})} ds, \tag{45}$$

where for any $a, b \in \mathbb{R}$

$$|\Delta s|^{H_k(a+b\cdot\alpha_{[\sigma(\Delta)]}^{(k)})} := |s_1|^{H_k(a+b(\alpha_{[\sigma(1)]}^{(k)}+\alpha_{[\sigma(2n)]}^{(k)})} \prod_{j=2}^{2n} |s_j - s_{j-1}|^{H_k(a+b(\alpha_{[\sigma(j)]}^{(k)}+\alpha_{[\sigma(j-1)]}^{(k)})},$$

$$|\Delta s|^{H(a+b\cdot\alpha_{[\sigma(\Delta)]})} := \prod_{k=1}^d |\Delta s|^{H_k(a+b\cdot\alpha_{[\sigma(\Delta)]}^{(k)})}.$$

Theorem B.1 *Suppose the functions $\Psi_\alpha^f(\theta, t, z, H, d)$ and $\Psi_\alpha^z(\theta, t, H, d)$ defined in Eqs. 44 and 45, respectively, are finite. Then,*

$$\Lambda_\alpha^f(\theta, t, z) := (2\pi)^{-dn} \int_{(\mathbb{R}^d)^n} \int_{\Delta_{\theta, t}^n} \prod_{j=1}^n f_j(s_j, z_j) (-iu_j)^{\alpha_j} e^{-i\langle u_j, \widehat{B}_{s_j}^{d, H} - z_j \rangle} ds du, \tag{46}$$

where $\widehat{B}_t^{d,H} := \left(\frac{B_t^{H_1}}{\sqrt{\mathfrak{K}_{H_1}}}, \dots, \frac{B_t^{H_d}}{\sqrt{\mathfrak{K}_{H_d}}} \right)^\top$ and \mathfrak{K}_{H_k} is the constant in Lemma 2.4, is a square integrable random variable in $L^2(\Omega)$ and

$$\mathbb{E} \left[\left| \Lambda_\alpha^f(\theta, t, z) \right|^2 \right] \leq \frac{T^{|\alpha|}}{(2\pi)^{dn}} \Psi_\alpha^f(\theta, t, z, H, d). \tag{47}$$

Furthermore,

$$\mathbb{E} \left[\left| \int_{(\mathbb{R}^d)^n} \Lambda_\alpha^{\mathcal{Z}f}(\theta, t, z) dz \right|^2 \right] \leq \frac{T^{|\alpha|}}{\sqrt{2\pi}^{dn}} (\Psi_\alpha^{\mathcal{Z}f}(\theta, t, H, d))^{\frac{1}{2}} \prod_{j=1}^n \|f_j\|_{L^1(\mathbb{R}^d; L^\infty([0, T]))}. \tag{48}$$

and the integration by parts formula

$$\int_{\Delta_{0,t}^n} D^\alpha f(s, \widehat{B}_s^{d,H}) ds = \int_{(\mathbb{R}^d)^n} \Lambda_\alpha^f(\theta, t, z) dz, \tag{49}$$

holds.

Proof For notational simplicity we consider merely the case $\theta = 0$ and write $\Lambda_\alpha^f(t, z) := \Lambda_\alpha^f(0, t, z)$. For any integrable function $g : (\mathbb{R}^d)^n \rightarrow \mathbb{C}$ we have that

$$\begin{aligned} & \left| \int_{(\mathbb{R}^d)^n} g(u_1, \dots, u_n) du_1 \dots du_n \right|^2 \\ &= \int_{(\mathbb{R}^d)^n} g(u_1, \dots, u_n) du_1 \dots du_n \int_{(\mathbb{R}^d)^n} \overline{g(u_{n+1}, \dots, u_{2n})} du_{n+1} \dots du_{2n} \\ &= \int_{(\mathbb{R}^d)^n} g(u_1, \dots, u_n) du_1 \dots du_n (-1)^{dn} \int_{(\mathbb{R}^d)^n} \overline{g(-u_{n+1}, \dots, -u_{2n})} du_{n+1} \dots du_{2n}, \end{aligned}$$

where the change of variables $(u_{n+1}, \dots, u_{2n}) \mapsto (-u_{n+1}, \dots, -u_{2n})$ was applied in the last equality. Thus,

$$\begin{aligned} \left| \Lambda_\alpha^f(t, z) \right|^2 &= (2\pi)^{-2dn} (-1)^{dn} \int_{(\mathbb{R}^d)^{2n}} \int_{\Delta_{0,t}^n} \prod_{j=1}^n f_j(s_j, z_j) (-iu_j)^{\alpha_j} e^{-i\langle u_j, \widehat{B}_{s_j}^{d,H} - z_j \rangle} ds \\ &\quad \times \int_{\Delta_{0,t}^n} \prod_{j=n+1}^{2n} \overline{f_{[j]}(s_j, z_{[j]})} (-iu_j)^{\alpha_{[j]}} e^{-i\langle u_j, \widehat{B}_{s_j}^{d,H} - z_{[j]} \rangle} ds du \\ &= (2\pi)^{-2dn} (-1)^{dn} i^{|\alpha|} \sum_{\sigma \in \mathcal{S}(n,n)} \int_{(\mathbb{R}^d)^{2n}} \left(\prod_{j=1}^n e^{-i\langle z_j, u_j + u_{j+n} \rangle} \right) \\ &\quad \times \int_{\Delta_{0,t}^{2n}} f_\sigma(s, z) \left(\prod_{j=1}^{2n} u_{\sigma(j)}^{\alpha_{[\sigma(j)]}} \right) \exp \left\{ -i \sum_{j=1}^{2n} \langle u_{\sigma(j)}, \widehat{B}_{s_j}^{d,H} \rangle \right\} ds du, \end{aligned}$$

where we applied shuffling in the sense of Eq. 9. Taking the expectation on both sides together with the independence of the fractional Brownian motions $B^{H_k}, k = 1, \dots, d$, yields that

$$\begin{aligned}
 & \mathbb{E} \left[\left| \Lambda_\alpha^f(t, z) \right|^2 \right] \\
 &= (2\pi)^{-2dn} (-1)^{dn} i^{|\alpha|} \sum_{\sigma \in \mathcal{S}(n, n)} \int_{(\mathbb{R}^d)^{2n}} \left(\prod_{j=1}^n e^{-i \langle z_j, u_j + u_{j+n} \rangle} \right) \\
 & \quad \times \int_{\Delta_{0,t}^{2n}} f_\sigma(s, z) \left(\prod_{j=1}^{2n} u_{\sigma(j)}^{|\alpha_{[\sigma(j)]}|} \right) \exp \left\{ -\frac{1}{2} \text{Var} \left(\sum_{j=1}^{2n} \langle u_{\sigma(j)}, \widehat{B}_{s_j}^{d, H} \rangle \right) \right\} ds du \\
 &= (2\pi)^{-2dn} (-1)^{dn} i^{|\alpha|} \sum_{\sigma \in \mathcal{S}(n, n)} \int_{(\mathbb{R}^d)^{2n}} \left(\prod_{j=1}^n e^{-i \langle z_j, u_j + u_{j+n} \rangle} \right) \\
 & \quad \times \int_{\Delta_{0,t}^{2n}} f_\sigma(s, z) \left(\prod_{j=1}^{2n} u_{\sigma(j)}^{|\alpha_{[\sigma(j)]}|} \right) \exp \left\{ -\frac{1}{2} \sum_{k=1}^d \text{Var} \left(\sum_{j=1}^{2n} u_{\sigma(j)}^{(k)} \frac{B_{s_j}^{H_k}}{\sqrt{\mathfrak{K}_{H_k}}} \right) \right\} ds du \\
 &= (2\pi)^{-2dn} (-1)^{dn} i^{|\alpha|} \sum_{\sigma \in \mathcal{S}(n, n)} \int_{(\mathbb{R}^d)^{2n}} \left(\prod_{j=1}^n e^{-i \langle z_j, u_j + u_{j+n} \rangle} \right) \\
 & \quad \times \int_{\Delta_{0,t}^{2n}} f_\sigma(s, z) \left(\prod_{j=1}^{2n} u_{\sigma(j)}^{|\alpha_{[\sigma(j)]}|} \right) \prod_{k=1}^d \exp \left\{ -\frac{1}{2\mathfrak{K}_{H_k}} (u_\sigma^{(k)})^\top \Sigma_k u_\sigma^{(k)} \right\} ds du, \tag{50}
 \end{aligned}$$

where $u_\sigma^{(k)} = (u_{\sigma(1)}^{(k)}, \dots, u_{\sigma(2n)}^{(k)})^\top$ and

$$\Sigma_k = \Sigma_k(s) := \left(\mathbb{E} \left[B_{s_i}^{H_k} B_{s_j}^{H_k} \right] \right)_{1 \leq i, j \leq 2n}.$$

Moreover, we obtain for every $\sigma \in \mathcal{S}(n, n)$ that

$$\begin{aligned}
 & \int_{\Delta_{0,t}^{2n}} |f_\sigma(s, z)| \int_{(\mathbb{R}^d)^{2n}} \prod_{k=1}^d \left(\left(\prod_{j=1}^{2n} |u_{\sigma(j)}^{(k)}|^{|\alpha_{[\sigma(j)]}|} \right) e^{-\frac{1}{2\mathfrak{K}_{H_k}} (u_\sigma^{(k)})^\top \Sigma_k u_\sigma^{(k)}} \right) duds \\
 &= \int_{\Delta_{0,t}^{2n}} |f_\sigma(s, z)| \prod_{k=1}^d \left(\int_{\mathbb{R}^{2n}} \left(\prod_{j=1}^{2n} |u_j^{(k)}|^{|\alpha_{[\sigma(j)]}|} \right) e^{-\frac{1}{2} \left\langle \frac{\Sigma_k}{\mathfrak{K}_{H_k}} u^{(k)}, u^{(k)} \right\rangle} du^{(k)} \right) ds, \tag{51}
 \end{aligned}$$

where $u^{(k)} := (u_1^{(k)}, \dots, u_{2n}^{(k)})^\top$. For every $1 \leq k \leq d$ we have by using substitution that

$$\begin{aligned}
 & \int_{\mathbb{R}^{2n}} \left(\prod_{j=1}^{2n} |u_j^{(k)}|^{|\alpha_{[\sigma(j)]}|} \right) e^{-\frac{1}{2} \left\langle \frac{\Sigma_k}{\mathfrak{K}_{H_k}} u^{(k)}, u^{(k)} \right\rangle} du^{(k)} \\
 &= \frac{\mathfrak{K}_{H_k}^{2n}}{(\det \Sigma_k)^{1/2}} \int_{\mathbb{R}^{2n}} \left(\prod_{j=1}^{2n} \left| \left\langle \sqrt{\mathfrak{K}_{H_k}} \Sigma_k^{-1/2} u^{(k)}, \tilde{e}_j \right\rangle \right|^{|\alpha_{[\sigma(j)]}|} \right) e^{-\frac{1}{2} \langle u^{(k)}, u^{(k)} \rangle} du^{(k)}. \tag{52}
 \end{aligned}$$

Considering a standard Gaussian random vector $Z \sim \mathcal{N}(0, \text{Id}_{2n})$, we get that

$$\int_{\mathbb{R}^{2n}} \left(\prod_{j=1}^{2n} \left| \left\langle \Sigma_k^{-1/2} u^{(k)}, \tilde{e}_j \right\rangle \right|^{\alpha_{[\sigma(j)]}^{(k)}} \right) e^{-\frac{1}{2} \langle u^{(k)}, u^{(k)} \rangle} du^{(k)} \tag{53}$$

$$= (2\pi)^n \mathbb{E} \left[\prod_{j=1}^{2n} \left| \left\langle \Sigma_k^{-1/2} Z, \tilde{e}_j \right\rangle \right|^{\alpha_{[\sigma(j)]}^{(k)}} \right].$$

Using a Brascamp-Lieb type inequality which is due to Lemma C.1, we further get that

$$\mathbb{E} \left[\prod_{j=1}^{2n} \left| \left\langle \Sigma_k^{-1/2} Z, \tilde{e}_j \right\rangle \right|^{\alpha_{[\sigma(j)]}^{(k)}} \right] \leq \sqrt{\text{perm} A_k} = \sqrt{\sum_{\pi \in S_{2|\alpha^{(k)}}} \prod_{i=1}^{2|\alpha^{(k)}} a_{i,\pi(i)}^{(k)}},$$

where $|\alpha^{(k)}| := \sum_{j=1}^n \alpha_j^{(k)}$ and $\text{perm} A_k$ is the permanent of the covariance matrix $A_k = (a_{i,j}^{(k)})_{1 \leq i,j \leq 2|\alpha^{(k)}|}$ of the Gaussian random vector

$$\left(\underbrace{\left\langle \Sigma_k^{-1/2} Z, \tilde{e}_1 \right\rangle, \dots, \left\langle \Sigma_k^{-1/2} Z, \tilde{e}_1 \right\rangle}_{\alpha_{[\sigma(1)]}^{(k)} \text{ times}}, \dots, \underbrace{\left\langle \Sigma_k^{-1/2} Z, \tilde{e}_{2n} \right\rangle, \dots, \left\langle \Sigma_k^{-1/2} Z, \tilde{e}_{2n} \right\rangle}_{\alpha_{[\sigma(2n)]}^{(k)} \text{ times}} \right),$$

and S_m denotes the permutation group of size m . Using an upper bound for the permanent of positive semidefinite matrices which is due to [3], we find that

$$\text{perm} A_k = \sum_{\pi \in S_{2|\alpha^{(k)}}} \prod_{i=1}^{2|\alpha^{(k)}} a_{i,\pi(i)}^{(k)} \leq (2|\alpha^{(k)}|)! \prod_{i=1}^{2|\alpha^{(k)}} a_{i,i}^{(k)}. \tag{54}$$

Now let $\sum_{l=1}^{j-1} \alpha_{[\sigma(l)]}^{(k)} + 1 \leq i \leq \sum_{l=1}^j \alpha_{[\sigma(l)]}^{(k)}$ for some fixed $j \in \{1, \dots, 2n\}$. Then

$$a_{i,i}^{(k)} = \mathbb{E} \left[\left\langle \Sigma_k^{-1/2} Z, \tilde{e}_j \right\rangle \left\langle \Sigma_k^{-1/2} Z, \tilde{e}_j \right\rangle \right].$$

Substitution gives moreover that

$$\mathbb{E} \left[\left\langle \Sigma_k^{-1/2} Z, \tilde{e}_j \right\rangle \left\langle \Sigma_k^{-1/2} Z, \tilde{e}_j \right\rangle \right] = (\det \Sigma_k)^{1/2} \frac{1}{(2\pi)^n} \int_{\mathbb{R}^{2n}} u_j^2 \exp \left\{ -\frac{1}{2} \langle \Sigma_k u, u \rangle \right\} du. \tag{55}$$

Applying Lemma C.2 we get

$$\int_{\mathbb{R}^{2n}} u_j^2 \exp \left\{ -\frac{1}{2} \langle \Sigma_k u, u \rangle \right\} du = \frac{(2\pi)^{(2n-1)/2}}{(\det \Sigma_k)^{1/2}} \int_{\mathbb{R}} v^2 \exp \left\{ -\frac{1}{2} v^2 \right\} dv \frac{1}{\sigma_j^2}$$

$$= \frac{(2\pi)^n}{(\det \Sigma_k)^{1/2}} \frac{1}{\sigma_j^2}, \tag{56}$$

where $\sigma_j^2 := \text{Var} \left(B_{s_j}^{H_k} \mid B_{s_1}^{H_k}, \dots, B_{s_{2n}}^{H_k} \text{ without } B_{s_j}^{H_k} \right)$.

Subsequently, we aim at the application of the strong local non-determinism property of the fractional Brownian motions, cf. Lemma 2.4, i.e. for all $0 < r < t \leq T$ exists a constant \mathfrak{K}_{H_k} depending on H_k and T such that

$$\text{Var} \left(B_t^{H_k} \mid B_s^{H_k}, |t - s| \geq r \right) \geq \mathfrak{K}_{H_k} r^{2H_k}.$$

Hence, we get due to Lemmas C.5 and C.6 that

$$(\det \Sigma_k(s))^{1/2} \geq \mathfrak{K}_{H_k}^{\frac{(2n-1)}{2}} |s_1|^{H_k} |s_2 - s_1|^{H_k} \dots |s_{2n} - s_{2n-1}|^{H_k}, \tag{57}$$

and

$$\begin{aligned} \sigma_1^2 &\geq \mathfrak{K}_{H_k} |s_2 - s_1|^{2H_k}, \\ \sigma_j^2 &\geq \mathfrak{K}_{H_k} \min \left\{ |s_j - s_{j-1}|^{2H_k}, |s_{j+1} - s_j|^{2H_k} \right\}, \quad 2 \leq j \leq 2n - 1, \\ \sigma_{2n}^2 &\geq \mathfrak{K}_{H_k} |s_{2n} - s_{2n-1}|^{2H_k}. \end{aligned}$$

Thus,

$$\prod_{j=1}^{2n} \sigma_j^{-2\alpha_{[\sigma(j)]}^{(k)}} \leq \mathfrak{K}_{H_k}^{-2|\alpha^{(k)}|} T^{4H_k|\alpha^{(k)}|} |\Delta s|^{-2H_k\alpha_{[\sigma(\Delta)]}^{(k)}}. \tag{58}$$

Concluding from Eqs. 54, 55, 56, and 58 we have that

$$\begin{aligned} \text{perm}(A_k) &\leq \left(2|\alpha^{(k)}|\right)! \prod_{i=1}^{2|\alpha^{(k)}|} a_{i,i}^{(k)} \\ &\leq \left(2|\alpha^{(k)}|\right)! \prod_{j=1}^{2n} \left((\det \Sigma_k)^{1/2} \frac{1}{(2\pi)^n} \frac{(2\pi)^n}{(\det \Sigma_k)^{1/2}} \frac{1}{\sigma_j^2} \right)^{\alpha_{[\sigma(j)]}^{(k)}} \\ &\leq \left(2|\alpha^{(k)}|\right)! \mathfrak{K}_{H_k}^{-2|\alpha^{(k)}|} T^{4H_k|\alpha^{(k)}|} |\Delta s|^{-2H_k\alpha_{[\sigma(\Delta)]}^{(k)}}. \end{aligned}$$

Consequently,

$$\mathbb{E} \left[\prod_{j=1}^{2n} \left| \left\langle \Sigma_k^{-1/2} Z, \tilde{e}_j \right\rangle \right|^{\alpha_{[\sigma(j)]}^{(k)}} \right] \leq \sqrt{(2|\alpha^{(k)}|)!} \mathfrak{K}_{H_k}^{-|\alpha^{(k)}|} T^{2H_k|\alpha^{(k)}|} |\Delta s|^{-H_k\alpha_{[\sigma(\Delta)]}^{(k)}}.$$

Therefore we get from Eqs. 50, 51, 52, 53, and 57 that

$$\begin{aligned} &\mathbb{E} \left[\left| \Lambda_\alpha^f(t, z) \right|^2 \right] \\ &\leq (2\pi)^{-2dn} \sum_{\sigma \in \mathcal{S}(n,n)} \int_{\Delta_{0,t}^{2n}} |f_\sigma(s, z)| \prod_{k=1}^d \left(\int_{\mathbb{R}^{2n}} |u^{(k)}|^{\alpha^{(k)}} e^{-\frac{1}{2\mathfrak{K}_{H_k}} \langle \Sigma_k u^{(k)}, u^{(k)} \rangle} du^{(k)} \right) ds \\ &\leq (2\pi)^{-dn} \sum_{\sigma \in \mathcal{S}(n,n)} \int_{\Delta_{0,t}^{2n}} |f_\sigma(s, z)| \prod_{k=1}^d \left(\frac{\mathfrak{K}_{H_k}^{n+|\alpha^{(k)}|}}{(\det \Sigma_k(s))^{\frac{1}{2}}} \mathbb{E} \left[\prod_{j=1}^{2n} \left| \left\langle \Sigma_k^{-\frac{1}{2}} Z, \tilde{e}_j \right\rangle \right|^{\alpha_{[\sigma(j)]}^{(k)}} \right] \right) ds \\ &\leq (2\pi)^{-dn} \sum_{\sigma \in \mathcal{S}(n,n)} \int_{\Delta_{0,t}^{2n}} |f_\sigma(s, z)| \left(\prod_{k=1}^d |\Delta s|^{-H_k} \mathfrak{K}_{H_k}^{|\alpha^{(k)}| + \frac{1}{2}} \right) \\ &\quad \times \prod_{k=1}^d \left(\sqrt{(2|\alpha^{(k)}|)!} \mathfrak{K}_{H_k}^{-|\alpha^{(k)}|} T^{2H_k|\alpha^{(k)}|} |\Delta s|^{-H_k\alpha_{[\sigma(\Delta)]}^{(k)}} \right) ds \\ &\leq (2\pi)^{-dn} T^{\frac{|\alpha|}{6}} \left(\prod_{k=1}^d \sqrt{\mathfrak{K}_{H_k}} \sqrt{(2|\alpha^{(k)}|)!} \right) \sum_{\sigma \in \mathcal{S}(n,n)} \int_{\Delta_{0,t}^{2n}} |f_\sigma(s, z)| |\Delta s|^{-H(1+\alpha_{[\sigma(\Delta)]})} ds. \end{aligned}$$

Since $\sup_{k \geq 1} \widehat{\mathfrak{K}}_{H_k} \in (0, 1)$, inequality Eq. 47 holds.

Next we prove the estimate Eq. 48. With inequality Eq. 47, we get that

$$\begin{aligned} \mathbb{E} \left[\left| \int_{(\mathbb{R}^d)^n} \Lambda_\alpha^{\mathcal{Z}f}(\theta, t, z) dz \right| \right] &\leq \int_{(\mathbb{R}^d)^n} \mathbb{E} \left[\left| \Lambda_\alpha^{\mathcal{Z}f}(\theta, t, z) \right|^2 \right]^{\frac{1}{2}} dz \\ &\leq \frac{T^{\frac{|\alpha|}{12}}}{\sqrt{2\pi}^{dn}} \int_{(\mathbb{R}^d)^n} (\Psi_\alpha^{\mathcal{Z}f}(\theta, t, z, H, d))^{\frac{1}{2}} dz. \end{aligned}$$

Taking the supremum over $[0, T]$ with respect to each function f_j , i.e.

$$\left| f_{[\sigma(j)]}(s_j, z_{[\sigma(j)]}) \right| \leq \sup_{s_j \in [0, T]} \left| f_{[\sigma(j)]}(s_j, z_{[\sigma(j)]}) \right|, \quad j = 1, \dots, 2n,$$

yields that

$$\begin{aligned} &\mathbb{E} \left[\left| \int_{(\mathbb{R}^d)^n} \Lambda_\alpha^{\mathcal{Z}f}(\theta, t, z) dz \right| \right] \\ &\leq \frac{T^{\frac{|\alpha|}{12}}}{\sqrt{2\pi}^{dn}} \max_{\sigma \in \mathcal{S}(n, n)} \int_{(\mathbb{R}^d)^n} \left(\prod_{j=1}^{2n} \|f_{[\sigma(j)]}(\cdot, z_{[\sigma(j)]})\|_{L^\infty([0, T])} \right)^{\frac{1}{2}} dz \\ &\times \left(\prod_{k=1}^d \sqrt{(2|\alpha^{(k)}|)!} \sum_{\sigma \in \mathcal{S}(n, n)} \int_{\Delta_{\theta, t}^{2n}} |\mathcal{Z}_\sigma(s)| |\Delta s|^{-H(1+\alpha_{[\sigma(\Delta)])}} ds \right)^{\frac{1}{2}} \\ &= \frac{T^{\frac{|\alpha|}{12}}}{\sqrt{2\pi}^{dn}} \max_{\sigma \in \mathcal{S}(n, n)} \int_{(\mathbb{R}^d)^n} \left(\prod_{j=1}^{2n} \|f_{[\sigma(j)]}(\cdot, z_{[\sigma(j)]})\|_{L^\infty([0, T])} \right)^{\frac{1}{2}} dz (\Psi_\alpha^{\mathcal{Z}}(\theta, t, H, d))^{\frac{1}{2}} \\ &= \frac{T^{\frac{|\alpha|}{12}}}{\sqrt{2\pi}^{dn}} \int_{(\mathbb{R}^d)^n} \prod_{j=1}^n \|f_j(\cdot, z_j)\|_{L^\infty([0, T])} dz (\Psi_\alpha^{\mathcal{Z}}(\theta, t, H, d))^{\frac{1}{2}} \\ &= \frac{T^{\frac{|\alpha|}{12}}}{\sqrt{2\pi}^{dn}} \left(\prod_{j=1}^n \|f_j\|_{L^1(\mathbb{R}^d; L^\infty([0, T]))} \right) (\Psi_\alpha^{\mathcal{Z}}(\theta, t, H, d))^{\frac{1}{2}}. \end{aligned}$$

Finally, we show the integration by parts formula Eq. 49. Note that *a priori* one cannot interchange the order of integration in Eq. 46, since e.g. for $m = 1, f \equiv 1$ one gets an integral of the Donsker-Delta function which is not a random variable in the usual sense. Therefore, we define for $R > 0$,

$$\Lambda_{\alpha, R}^f(\theta, t, z) := (2\pi)^{-dn} \int_{B(0, R)} \int_{\Delta_{\theta, t}^n} \prod_{j=1}^n f_j(s_j, z_j) (-iu_j)^{\alpha_j} e^{-i\langle u_j, \widehat{B}_{s_j}^{d, H} - z_j \rangle} ds dv,$$

where $B(0, R) := \{v \in (\mathbb{R}^d)^n : |v| < R\}$. This yields

$$|\Lambda_{\alpha, R}^f(\theta, t, z)| \leq C_R \int_{\Delta_{\theta, t}^n} \prod_{j=1}^n |f_j(s_j, z_j)| ds$$

for a sufficient constant C_R . Under the assumption that the above right-hand side is integrable over $(\mathbb{R}^d)^n$, similar computations as above show that $\Lambda_{\alpha, R}^f(\theta, t, z) \rightarrow \Lambda_\alpha^f(\theta, t, z)$ in

$L^2(\Omega)$ as $R \rightarrow \infty$ for all θ, t and z . By Lebesgue’s dominated convergence theorem and the fact that the Fourier transform is an automorphism on the Schwarz space, we obtain

$$\begin{aligned} \int_{(\mathbb{R}^d)^n} \Lambda_\alpha^f(\theta, t, z) dz &= \lim_{R \rightarrow \infty} \int_{(\mathbb{R}^d)^n} \Lambda_{\alpha, R}^f(\theta, t, z) dx \\ &= \lim_{R \rightarrow \infty} (2\pi)^{-dn} \int_{(\mathbb{R}^d)^n} \int_{B(0, R)} \int_{\Delta_{\theta, t}^n} \prod_{j=1}^n f_j(s_j, z_j) (-iu_j)^{\alpha_j} e^{-i\langle u_j, \widehat{B}_{s_j}^{d, H} - z_j \rangle} dz du ds \\ &= \lim_{R \rightarrow \infty} \int_{\Delta_{\theta, t}^n} \int_{B(0, R)} (2\pi)^{-dn} \int_{(\mathbb{R}^d)^n} \prod_{j=1}^n f_j(s_j, z_j) e^{i\langle u_j, z_j \rangle} dz (-iu_j)^{\alpha_j} e^{-i\langle u_j, \widehat{B}_{s_j}^{d, H} \rangle} du ds \\ &= \lim_{R \rightarrow \infty} \int_{\Delta_{\theta, t}^n} \int_{B(0, R)} \prod_{j=1}^n \widehat{f}_j(s, -u_j) (-iu_j)^{\alpha_j} e^{-i\langle u_j, \widehat{B}_{s_j}^{d, H} \rangle} du ds \\ &= \int_{\Delta_{\theta, t}^n} D^\alpha f\left(s, \widehat{B}_s^{d, H}\right) ds \end{aligned}$$

which is exactly the integration by parts formula Eq. 49. □

Applying Theorem B.1 we obtain the following crucial estimate (compare [1, 2, 6], and [7]):

Proposition B.2 *Let the functions f and \varkappa be defined as in Eqs. 42 and 43, respectively. Further, let $0 \leq \theta' < \theta < t \leq T$ and for some $m \geq 1$*

$$\varkappa_j(s) = (K_{H_m}(s, \theta) - K_{H_m}(s, \theta'))^{\varepsilon_j}, \quad \theta < s < t,$$

for every $j = 1, \dots, n$ with $(\varepsilon_1, \dots, \varepsilon_n) \in \{0, 1\}^n$. Let $\alpha \in (\mathbb{N}_0^d)^n$ be a multi-index. Assume there exists δ such that

$$-\sum_{k=1}^d H_k \left(1 + 2\alpha_j^{(k)}\right) + \left(H_m - \frac{1}{2} - \gamma_m\right) \geq \delta > -1 \tag{59}$$

for all $j = 1, \dots, n$ and $d \geq 1$, where $\gamma_m \in (0, H_m)$ is sufficiently small. Then there exist constants C_T (depending on T) and $K_{d, H}$ (depending on d and H), such that for any $0 \leq \theta < t \leq T$ we have

$$\begin{aligned} &\mathbb{E} \left[\left| \int_{\Delta_{\theta, t}^n} \left(\prod_{j=1}^n D^{\alpha_j} f_j(s_j, \widehat{B}_{s_j}) \varkappa_j(s_j) \right) ds \right| \right] \\ &\leq \frac{K_{d, H}^n \cdot T^{\frac{|\alpha|}{12}}}{\sqrt{2\pi}^{dn}} \left(C_T \left(\frac{\theta - \theta'}{\theta\theta'} \right)^{\gamma_m} \theta^{(H_m - \frac{1}{2} - \gamma_m) \sum_{j=1}^n \varepsilon_j} \prod_{j=1}^n \|f_j(\cdot, z_j)\|_{L^1(\mathbb{R}^d; L^\infty([0, T])} \right) \\ &\quad \times \frac{\left(\prod_{k=1}^d (2|\alpha^{(k)}|)! \right)^{\frac{1}{4}} (t - \theta)^{-\sum_{k=1}^d H_k(n+2|\alpha^{(k)}|) + (H_m - \frac{1}{2} - \gamma_m) \sum_{j=1}^n \varepsilon_j + n}}{\Gamma(2n - \sum_{k=1}^d H_k(2n + 4|\alpha^{(k)}|) + 2(H_m - \frac{1}{2} - \gamma_m) \sum_{j=1}^n \varepsilon_j)^{\frac{1}{2}}}. \end{aligned}$$

In order to prove this result we need the following two auxiliary results.

Lemma B.3 Let $H \in \left(0, \frac{1}{2}\right)$ and $t \in [0, T]$ be fixed. Then, there exists $\beta \in \left(0, \frac{1}{2}\right)$ and a constant $C > 0$ independent of H such that

$$\int_0^t \int_0^t \frac{|K_H(t, \theta') - K_H(t, \theta)|^2}{|\theta' - \theta|^{1+2\beta}} d\theta d\theta' \leq C < \infty.$$

Proof Let $0 \leq \theta' < \theta \leq t$ be fixed. Write

$$K_H(t, \theta) - K_H(t, \theta') = c_H \left[f_t(\theta) - f_t(\theta') + \left(\frac{1}{2} - H\right) (g_t(\theta) - g_t(\theta')) \right],$$

where $f_t(\theta) := \left(\frac{t}{\theta}\right)^{H-\frac{1}{2}} (t - \theta)^{H-\frac{1}{2}}$ and $g_t(\theta) := \int_\theta^t \frac{f_u(\theta)}{u} du$.

We continue with the estimation of $K_H(t, \theta) - K_H(t, \theta')$. First, observe that there exists a constant $0 < C < 1$ such that

$$\frac{y^{-\alpha} - x^{-\alpha}}{(x - y)^\gamma} \leq C y^{-\alpha-\gamma}, \tag{60}$$

for every $0 < y < x < \infty$ and $\alpha := \left(\frac{1}{2} - H\right) \in \left(0, \frac{1}{2}\right)$ as well as $0 < \gamma < \frac{1}{2} - \alpha$. Indeed, rewriting Eq. 60 yields using the substitution $z := \frac{x}{y}$, $z \in (1, \infty)$,

$$\frac{y^{-\alpha} - x^{-\alpha}}{(x - y)^\gamma} y^{\alpha+\gamma} = \frac{1 - z^{-\alpha}}{(z - 1)^\gamma} =: g(z).$$

Furthermore, since $\alpha + \gamma < 1$ we get that

$$\lim_{z \rightarrow 1} g(z) = \lim_{z \rightarrow 1} \frac{1 - z^{-\alpha}}{(z - 1)^\gamma} = \lim_{z \rightarrow 1} \frac{1 + \alpha z^{-\alpha-1}}{\gamma(z - 1)^{\gamma-1}} = 0,$$

and

$$\lim_{z \rightarrow \infty} g(z) = 0.$$

Moreover, for $2 \leq z \leq \infty$ we get the upper bound

$$0 \leq g(z) \leq \frac{1 - z^{-\alpha}}{(z - 1)^\gamma} < \frac{1}{1} = 1,$$

and for $1 < z < 2$ we have that

$$g(z) = \frac{z^\alpha - 1}{(z - 1)^\gamma z^\alpha} < \frac{z - 1}{(z - 1)^\gamma (z - 1)^\alpha} = (z - 1)^{1-\gamma-\alpha} \leq 1.$$

This shows inequality Eq. 60 which then implies for $0 < \gamma < H$ that

$$\begin{aligned} f_t(\theta) - f_t(\theta') &= \left(\frac{t}{\theta}(t - \theta)\right)^{H-\frac{1}{2}} - \left(\frac{t}{\theta'}(t - \theta')\right)^{H-\frac{1}{2}} \\ &\lesssim \left(\frac{t}{\theta}(t - \theta)\right)^{H-\frac{1}{2}-\gamma} t^{2\gamma} \frac{(\theta - \theta')^\gamma}{(\theta\theta')^\gamma} \lesssim (t - \theta)^{H-\frac{1}{2}-\gamma} \frac{(\theta - \theta')^\gamma}{(\theta\theta')^\gamma}. \end{aligned}$$

Further,

$$\begin{aligned}
 g_t(\theta) - g_t(\theta') &= \int_{\theta}^t \frac{f_u(\theta) - f_u(\theta')}{u} du - \int_{\theta'}^{\theta} \frac{f_u(\theta')}{u} du \\
 &\leq \int_{\theta}^t \frac{f_u(\theta) - f_u(\theta')}{u} du \\
 &\lesssim \frac{(\theta - \theta')^{\gamma}}{(\theta\theta')^{\gamma}} \int_{\theta}^t \frac{(u - \theta)^{H - \frac{1}{2} - \gamma}}{u} du \\
 &\leq \frac{(\theta - \theta')^{\gamma}}{(\theta\theta')^{\gamma}} \theta^{H - \frac{1}{2} - \gamma} \int_1^{\infty} \frac{(v - 1)^{H - \frac{1}{2} - \gamma}}{v} dv \\
 &\lesssim \frac{(\theta - \theta')^{\gamma}}{(\theta\theta')^{\gamma}} \theta^{H - \frac{1}{2} - \gamma} \\
 &\lesssim \frac{(\theta - \theta')^{\gamma}}{(\theta\theta')^{\gamma}} \theta^{H - \frac{1}{2} - \gamma} (t - \theta)^{H - \frac{1}{2} - \gamma}.
 \end{aligned}$$

Consequently, we get for $\gamma \in (0, H)$, $0 < \theta' < \theta < t \leq T$, that

$$K_H(t, \theta) - K_H(t, \theta') \leq C \cdot c_H \frac{(\theta - \theta')^{\gamma}}{(\theta\theta')^{\gamma}} \theta^{H - \frac{1}{2} - \gamma} (t - \theta)^{H - \frac{1}{2} - \gamma},$$

where $C > 0$ is a constant merely depending on T . Thus

$$\begin{aligned}
 &\int_0^t \int_0^{\theta} \frac{(K_H(t, \theta) - K_H(t, \theta'))^2}{|\theta - \theta'|^{1+2\beta}} d\theta' d\theta \\
 &\lesssim \int_0^t \int_0^{\theta} \frac{|\theta - \theta'|^{-1-2\beta+2\gamma}}{(\theta\theta')^{2\gamma}} \theta^{2H-1-2\gamma} (t - \theta)^{2H-1-2\gamma} d\theta' d\theta \\
 &= \int_0^t \theta^{2H-1-4\gamma} (t - \theta)^{2H-1-2\gamma} \int_0^{\theta} |\theta - \theta'|^{-1-2\beta+2\gamma} (\theta')^{-2\gamma} d\theta' d\theta \\
 &= \int_0^t \theta^{2H-1-4\gamma-2\beta} (t - \theta)^{2H-1-2\gamma} \frac{\Gamma(-2\beta + 2\gamma)\Gamma(-2\gamma + 1)}{\Gamma(-2\beta + 1)} d\theta \\
 &\lesssim \int_0^t \theta^{2H-1-4\gamma-2\beta} (t - \theta)^{2H-1-2\gamma} d\theta \\
 &= \frac{\Gamma(2H - 2\gamma)\Gamma(2H - 4\gamma - 2\beta)}{\Gamma(4H - 6\gamma - 2\beta)} t^{4H-6\gamma-2\beta-1} < \infty,
 \end{aligned}$$

for sufficiently small γ and β . On the other hand, we have that

$$\begin{aligned}
 &\int_0^t \int_{\theta}^t \frac{(K_H(t, \theta) - K_H(t, \theta'))^2}{|\theta - \theta'|^{1+2\beta}} d\theta' d\theta \\
 &\lesssim \int_0^t \theta^{2H-1-4\gamma} (t - \theta)^{2H-1-2\gamma} \int_{\theta}^t \frac{|\theta - \theta'|^{-1-2\beta+2\gamma}}{(\theta')^{2\gamma}} d\theta' d\theta \\
 &\leq \int_0^t \theta^{2H-1-6\gamma} (t - \theta)^{2H-1-2\gamma} \int_{\theta}^t |\theta - \theta'|^{-1-2\beta+2\gamma} d\theta' d\theta \\
 &\lesssim \int_0^t \theta^{2H-1-6\gamma} (t - \theta)^{2H-1-2\beta} d\theta \lesssim t^{4H-6\gamma-2\beta-1}.
 \end{aligned}$$

Therefore,

$$\int_0^t \int_0^t \frac{(K_H(t, \theta) - K_H(t, \theta'))^2}{|\theta - \theta'|^{1+2\beta}} d\theta' d\theta < \infty.$$

□

Lemma B.4 *Let $H \in (0, \frac{1}{2})$, $0 \leq \theta < t \leq T$ and $(\varepsilon_1, \dots, \varepsilon_n) \in \{0, 1\}^n$ be fixed. Assume $w_j + (H - \frac{1}{2} - \gamma) \varepsilon_j > -1$ for all $j = 1, \dots, n$. Then there exists a finite constant $C_{H,T} > 0$ depending only on H and T such that for $\gamma \in (0, H)$*

$$\begin{aligned} & \int_{\Delta_{\theta,t}^n} \prod_{j=1}^n (K_H(s_j, \theta) - K_H(s_j, \theta'))^{\varepsilon_j} |s_j - s_{j-1}|^{w_j} ds \\ & \leq \left(C_{H,T} \left(\frac{\theta - \theta'}{\theta \theta'} \right)^\gamma \theta^{(H-\frac{1}{2}-\gamma)} \right)^{\sum_{j=1}^n \varepsilon_j} \Pi_\gamma(n) (t - \theta)^{\sum_{j=1}^n (w_j + (H-\frac{1}{2}-\gamma)\varepsilon_j) + n}, \end{aligned}$$

where

$$\Pi_\gamma(m) := \frac{\prod_{j=1}^m \Gamma(w_j + 1)}{\Gamma\left(\sum_{j=1}^m w_j + \left(H - \frac{1}{2} - \gamma\right) \sum_{j=1}^m \varepsilon_j + n\right)}. \tag{61}$$

Proof Recall, that for given exponents $a, b > -1$ and some fixed $s_{j+1} > s_j$ we have

$$\int_\theta^{s_{j+1}} (s_{j+1} - s_j)^a (s_j - \theta)^b ds_j = \frac{\Gamma(a + 1) \Gamma(b + 1)}{\Gamma(a + b + 2)} (s_{j+1} - \theta)^{a+b+1}.$$

Due to Lemma B.3 we have that for every $\gamma \in (0, H)$, $0 < \theta' < \theta < s_j \leq T$,

$$K_H(s_j, \theta) - K_H(s_j, \theta') \leq C_{H,T} \frac{(\theta - \theta')^\gamma}{(\theta \theta')^\gamma} \theta^{H-\frac{1}{2}-\gamma} (s_j - \theta)^{H-\frac{1}{2}-\gamma},$$

for $C_{H,T} := C \cdot c_H$, where c_H is the constant in Eq. 14 and $C > 0$ is some constant merely depending on T . Consequently, we get that

$$\begin{aligned} & \int_\theta^{s_2} |K_H(s_1, \theta) - K_H(s_1, \theta')|^{\varepsilon_1} |s_2 - s_1|^{w_2} |s_1 - \theta|^{w_1} ds_1 \\ & \leq C_{H,T}^{\varepsilon_1} \frac{(\theta - \theta')^{\gamma \varepsilon_1}}{(\theta \theta')^{\gamma \varepsilon_1}} \theta^{(H-\frac{1}{2}-\gamma)\varepsilon_1} \int_\theta^{s_2} |s_2 - s_1|^{w_2} |s_1 - \theta|^{w_1 + (H-\frac{1}{2}-\gamma)\varepsilon_1} ds_1 \\ & = C_{H,T}^{\varepsilon_1} \frac{(\theta - \theta')^{\gamma \varepsilon_1}}{(\theta \theta')^{\gamma \varepsilon_1}} \theta^{(H-\frac{1}{2}-\gamma)\varepsilon_1} \frac{\Gamma(\hat{w}_1) \Gamma(\hat{w}_2)}{\Gamma(\hat{w}_1 + \hat{w}_2)} (s_2 - \theta)^{w_1 + w_2 + (H-\frac{1}{2}-\gamma)\varepsilon_1 + 1}, \end{aligned}$$

where

$$\hat{w}_1 := w_1 + \left(H - \frac{1}{2} - \gamma\right) \varepsilon_1 + 1, \quad \hat{w}_2 := w_2 + 1.$$

Noting that

$$\prod_{j=1}^{n-1} \frac{\Gamma\left(\sum_{l=1}^j w_l + \left(H - \frac{1}{2} - \gamma\right) \sum_{l=1}^j \varepsilon_l + j\right) \Gamma(w_{j+1} + 1)}{\Gamma\left(\sum_{l=1}^{j+1} w_l + \left(H - \frac{1}{2} - \gamma\right) \sum_{l=1}^j \varepsilon_l + j + 1\right)} \leq \Pi_\gamma(n).$$

and iterative integration yields the desired formula. □

Finally, we are able to give the proof of Proposition B.2.

Proof of Proposition B.2 The integration by parts formula Eq. 49 yields that

$$\int_{\Delta_{\theta,t}^n} \left(\prod_{j=1}^n D^{\alpha_j} f_j(s_j, \widehat{B}_{s_j}) \varkappa_j(s_j) \right) ds = \int_{\mathbb{R}^{dn}} \Lambda_{\alpha}^{\varkappa f}(\theta, t, z) dz.$$

Taking the expectation and applying Theorem B.1 we get that

$$\begin{aligned} & \mathbb{E} \left[\left| \int_{\Delta_{\theta,t}^n} \left(\prod_{j=1}^n D^{\alpha_j} f_j(s_j, \widehat{B}_{s_j}) \varkappa_j(s_j) \right) ds \right| \right] \\ & \leq \frac{T^{\frac{|\alpha|}{2}}}{\sqrt{2\pi}^{dn}} (\Psi_{\alpha}^{\varkappa}(\theta, t, H, d))^{\frac{1}{2}} \prod_{j=1}^n \|f_j\|_{L^1(\mathbb{R}^d; L^{\infty}([0, T]))}, \end{aligned}$$

where

$$\begin{aligned} \Psi_{\alpha}^{\varkappa}(\theta, t, H, d) & := \left(\prod_{k=1}^d \sqrt{(2|\alpha^{(k)}|)!} \right) \\ & \times \sum_{\sigma \in \mathcal{S}(n,n)} \int_{\Delta_{0,t}^{2n}} |\Delta s|^{-H(1+\alpha_{[\sigma(\Delta)]})} \prod_{j=1}^{2n} (K_{H_m}(s_j, \theta) - K_{H_m}(s_j, \theta'))^{\varepsilon_{[\sigma(j)]}} ds. \end{aligned}$$

Under the assumption $-\sum_{k=1}^d H_k(1 + \alpha_{[\sigma(j)]}^{(k)} + \alpha_{[\sigma(j-1)]}^{(k)}) + (H_m - \frac{1}{2} - \gamma_m)\varepsilon_{[\sigma(j)]} > -1$ for all $j = 1, \dots, 2n$, we can apply Lemma B.4 and thus get

$$\begin{aligned} & \Psi_{\alpha}^{\varkappa}(\theta, t, H, d) \\ & \leq \sum_{\sigma \in \mathcal{S}(n,n)} \left(C_T \left(\frac{\theta - \theta'}{\theta\theta'} \right)^{\gamma_m} \theta^{(H_m - \frac{1}{2} - \gamma_m) \sum_{j=1}^{2n} \varepsilon_{[\sigma(j)]}} \Pi_{\gamma}(2n) \right) \\ & \times \left(\prod_{k=1}^d \sqrt{(2|\alpha^{(k)}|)!} \right) (t - \theta)^{-\sum_{k=1}^d H_k(2n+4|\alpha^{(k)}|) + (H_m - \frac{1}{2} - \gamma_m) \sum_{j=1}^{2n} \varepsilon_{[\sigma(j)]} + 2n}, \end{aligned}$$

where $\Pi_{\gamma}(2n)$ is defined as in Eq. 61. We define the constant $K_{d,H}$ by

$$K_{d,H} := 2 \sup_{j=1, \dots, 2n} \Gamma \left(1 - \sum_{k=1}^d H_k \left(1 + \alpha_{[\sigma(j)]}^{(k)} + \alpha_{[\sigma(j-1)]}^{(k)} \right) \right) \tag{62}$$

and thus an upper bound of $\Pi_{\gamma}(2n)$ is given by

$$\Pi_{\gamma}(2n) \leq \frac{K_{d,H}^{2n}}{2^{2n} \Gamma \left(-\sum_{k=1}^d H_k (2n + 4|\alpha^{(k)}|) + \left(H_m - \frac{1}{2} - \gamma_m \right) \sum_{j=1}^{2n} \varepsilon_{[\sigma(j)]} + 2n \right)}.$$

Note that $\sum_{j=1}^{2n} \varepsilon_{[\sigma(j)]} = 2 \sum_{j=1}^n \varepsilon_j$ and

$$\#\mathcal{S}(n, n) = \binom{2n}{n} = \frac{2^{2n}}{\sqrt{\pi}} \frac{\Gamma \left(n + \frac{1}{2} \right)}{\Gamma(n+1)} \leq 2^{2n}.$$

Hence, it follows that

$$\begin{aligned}
 & (\Psi_k^\varkappa(\theta, t, H, d))^{\frac{1}{2}} \\
 & \leq K_{d,H}^n \left(C_T \left(\frac{\theta - \theta'}{\theta\theta'} \right)^{\gamma_m} \theta^{(H_m - \frac{1}{2} - \gamma_m)} \right)^{\sum_{j=1}^n \varepsilon_j} \\
 & \quad \times \frac{\left(\prod_{k=1}^d (2|\alpha^{(k)}|)! \right)^{\frac{1}{4}} (t - \theta)^{-\sum_{k=1}^d H_k(n+2|\alpha^{(k)}|) + (H_m - \frac{1}{2} - \gamma_m)\sum_{j=1}^n \varepsilon_j + n}}{\Gamma\left(2n - \sum_{k=1}^d H_k(2n + 4|\alpha^{(k)}|) + 2\left(H_m - \frac{1}{2} - \gamma_m\right)\sum_{j=1}^n \varepsilon_j\right)^{\frac{1}{2}}},
 \end{aligned}$$

□

Proposition B.5 *Let the functions f and \varkappa be defined as in Eqs. 42 and 43, respectively. Let $0 \leq \theta < t \leq T$ and*

$$\varkappa_j(s) = (K_{H_m}(s, \theta))^{\varepsilon_j}, \theta < s < t,$$

for every $j = 1, \dots, n$ with $(\varepsilon_1, \dots, \varepsilon_n) \in \{0, 1\}^n$. Let $\alpha \in (\mathbb{N}_0^d)^n$ be a multi-index and suppose that there exists δ such that

$$-\sum_{k=1}^d H_k \left(1 + 2\alpha_j^{(k)}\right) + \left(H_m - \frac{1}{2}\right) \geq \delta > -1$$

for all $j = 1, \dots, n$ and $d \geq 1$. Then there exist constants C_T (depending on T) and $K_{d,H}$ (depending on d and H) such that for any $0 \leq \theta < t \leq T$ we have

$$\begin{aligned}
 & \mathbb{E} \left[\left| \int_{\Delta_{\theta,t}^n} \left(\prod_{j=1}^n D^{\alpha_j} f_j(s_j, \widehat{B}_{s_j}) \varkappa_j(s_j) \right) ds \right| \right] \\
 & \leq \frac{K_{d,H}^n \cdot T^{\frac{|\alpha|}{2}}}{\sqrt{2\pi}^{dn}} \left(C_T \theta^{(H_m - \frac{1}{2})} \right)^{\sum_{j=1}^n \varepsilon_j} \prod_{j=1}^n \|f_j(\cdot, z_j)\|_{L^1(\mathbb{R}^d; L^\infty([0,T])} \\
 & \quad \times \frac{\left(\prod_{k=1}^d (2|\alpha^{(k)}|)! \right)^{\frac{1}{4}} (t - \theta)^{-\sum_{k=1}^d H_k(n+2|\alpha^{(k)}|) + (H_m - \frac{1}{2})\sum_{j=1}^n \varepsilon_j + n}}{\Gamma\left(2n - \sum_{k=1}^d H_k(2n + 4|\alpha^{(k)}|) + 2\left(H_m - \frac{1}{2}\right)\sum_{j=1}^n \varepsilon_j\right)^{\frac{1}{2}}}.
 \end{aligned}$$

The proof of Proposition B.5 is similar to the one of Proposition B.2 by using the subsequent lemma instead of Lemma B.4 and thus it is omitted in this manuscript.

Lemma B.6 *Let $H \in \left(0, \frac{1}{2}\right)$, $0 \leq \theta < t \leq T$ and $(\varepsilon_1, \dots, \varepsilon_n) \in \{0, 1\}^n$ be fixed. Assume $w_j + \left(H - \frac{1}{2}\right) \varepsilon_j > -1$ for all $j = 1, \dots, n$. Then there exists a finite constant $C_{H,T} > 0$ depending only on H and T such that*

$$\begin{aligned}
 & \int_{\Delta_{\theta,t}^n} \prod_{j=1}^n (K_H(s_j, \theta))^{\varepsilon_j} |s_j - s_{j-1}|^{w_j} ds \\
 & \leq \left(C_{H,T} \theta^{(H - \frac{1}{2})} \right)^{\sum_{j=1}^n \varepsilon_j} \Pi_0(n) (t - \theta)^{\sum_{j=1}^n (w_j + (H - \frac{1}{2}) \varepsilon_j) + n},
 \end{aligned}$$

where Π_0 is defined in Eq. 61.

Proof Using similar arguments as in the proof of Lemma B.3 we get the following estimate

$$|K_H(s_j, \theta)| \leq C_{H,T} |s_j - \theta|^{H-\frac{1}{2}} \theta^{H-\frac{1}{2}}$$

for every $0 < \theta < s_j < T$ and $C_{H,T} := C \cdot c_H$, where c_H is the constant in Eq. 14 and $C > 0$ is some constant merely depending on T . Thus,

$$\begin{aligned} & \int_{\theta}^{s_2} (K_H(s_1, \theta))^{\varepsilon_1} |s_2 - s_1|^{w_2} |s_1 - \theta|^{w_1} ds_1 \\ & \leq C_{H,T}^{\varepsilon_1} \theta^{(H-\frac{1}{2})\varepsilon_1} \int_{\theta}^{s_2} |s_2 - s_1|^{w_2} |s_1 - \theta|^{w_1 + (H-\frac{1}{2})\varepsilon_1} ds_1 \\ & = C_{H,T}^{\varepsilon_1} \theta^{(H-\frac{1}{2})\varepsilon_1} \frac{\Gamma(w_1 + (H - \frac{1}{2})\varepsilon_1 + 1) \Gamma(w_2 + 1)}{\Gamma(w_1 + w_2 + (H - \frac{1}{2})\varepsilon_1 + 1)} (s_2 - \theta)^{w_1 + w_2 + (H-\frac{1}{2})\varepsilon_1 + 1}. \end{aligned}$$

Proceeding similar to the proof of Lemma B.4 yields the desired estimate. □

Remark B.7 Note that

$$\prod_{k=1}^d \left(2|\alpha^{(k)}|\right)! \leq \sqrt{2\pi}^d e^{\frac{|\alpha|}{2}} \frac{\Gamma\left(\frac{5}{2}|\alpha| + 1\right)}{\sqrt{5\pi}|\alpha|}.$$

Indeed, since for $n \geq 1$ sufficiently large we have by Stirling’s formula that

$$\sqrt{2\pi n} \left(\frac{n}{e}\right)^n \leq n! \leq e^{\frac{1}{12n}} \sqrt{2\pi n} \left(\frac{n}{e}\right)^n,$$

we get by assuming without loss of generality that $|\alpha^{(k)}| \geq 1$ for all $1 \leq k \leq d$, that

$$\begin{aligned} \prod_{k=1}^d \left(2|\alpha^{(k)}|\right)! & \leq \prod_{k=1}^d e^{\frac{1}{24|\alpha^{(k)}|}} \sqrt{4\pi|\alpha^{(k)}|} \left(\frac{2|\alpha^{(k)}|}{e}\right)^{2|\alpha^{(k)}|} \\ & \leq e^{\frac{d}{24}} \sqrt{\frac{8}{5}\pi}^d \prod_{k=1}^d \left(\frac{5}{2}|\alpha^{(k)}|\right)^{\frac{|\alpha^{(k)}|}{2}} \left(\frac{5}{2}|\alpha^{(k)}|\right)^{2|\alpha^{(k)}|} \\ & \leq \sqrt{2\pi}^d \prod_{k=1}^d \left(\frac{5}{2}|\alpha|\right)^{\frac{5}{2}|\alpha^{(k)}|} e^{\frac{|\alpha^{(k)}|}{2}} \\ & \leq \sqrt{2\pi}^d e^{\frac{|\alpha|}{2}} \left(\frac{5}{2}|\alpha|\right)^{\frac{5}{2}|\alpha|} \leq \sqrt{2\pi}^d e^{\frac{|\alpha|}{2}} \frac{\Gamma\left(\frac{5}{2}|\alpha| + 1\right)}{\sqrt{5\pi}|\alpha|}. \end{aligned}$$

Appendix C: Technical Results

The following technical result can be found in [26].

Lemma C.1 *Assume that X_1, \dots, X_n are real centered jointly Gaussian random variables, and $\Sigma = (\mathbb{E}[X_j X_k])_{1 \leq j, k \leq n}$ is the covariance matrix, then*

$$\mathbb{E}[|X_1| \dots |X_n|] \leq \sqrt{\text{perm}(\Sigma)},$$

where $\text{perm}(A)$ is the permanent of a matrix $A = (a_{ij})_{1 \leq i, j \leq n}$ defined by

$$\text{perm}(A) = \sum_{\pi \in \mathcal{S}_n} \prod_{j=1}^n a_{j, \pi(j)}$$

for the symmetric group \mathcal{S}_n .

The next lemma corresponds to [12, Lemma 2]:

Lemma C.2 *Let Z_1, \dots, Z_n be mean zero Gaussian random variables which are linearly independent. Then for any measurable function $g : \mathbb{R} \rightarrow \mathbb{R}_+$ we have that*

$$\int_{\mathbb{R}^n} g(v_1) e^{-\frac{1}{2} \text{Var} \sum_{j=1}^n v_j Z_j} dv_1 \dots dv_n = \frac{(2\pi)^{\frac{n-1}{2}}}{(\det \text{Cov} Z_1, \dots, Z_n)^{\frac{1}{2}}} \int_{\mathbb{R}} g\left(\frac{v}{\sigma_1}\right) e^{-\frac{v^2}{2}} dv,$$

where $\sigma_1^2 := \text{Var} Z_1 | Z_2, \dots, Z_n$.

Remark C.3 Note that here linearly independence is meant in the sense that $\det \text{Cov} Z_1, \dots, Z_n \neq 0$.

Lemma C.4 *Let $a \in \ell^p$, $1 \leq p < \infty$. Then, for every $n \geq 1$ and $d \geq 1$*

$$\sum_{k_1, \dots, k_n=1}^d \prod_{j=1}^n a_{k_j} = \left(\sum_{k=1}^d a_k \right)^n, \tag{63}$$

and

$$\lim_{d \rightarrow \infty} \sum_{k_1, \dots, k_n=1}^d \prod_{j=1}^n |a_{k_j}|^p = (\|a\|_{\ell^p})^n. \tag{64}$$

Proof We proof Eq. 63 by induction. For $n = 1$ the result holds. Therefore we assume that Eq. 63 holds for n and we show that it also holds for $n + 1$. Thus, we get by the induction hypothesis that

$$\begin{aligned} \sum_{k_1, \dots, k_{n+1}=1}^d \prod_{j=1}^{n+1} a_{k_j} &= \sum_{k_{n+1}=1}^d a_{k_{n+1}} \left(\sum_{k_1, \dots, k_n=1}^d \prod_{j=1}^n a_{k_j} \right) \\ &= \sum_{k_{n+1}=1}^d a_{k_{n+1}} \left(\sum_{k=1}^d a_k \right)^n = \left(\sum_{k=1}^d a_k \right)^{n+1}. \end{aligned}$$

Equation 64 is an immediate consequence of Eq. 63 and the continuity of the function $f(x) = x^n$ for fixed $n \geq 1$. □

The subsequent lemmas are due to [4].

Lemma C.5 *Let (X_1, \dots, X_n) be a mean-zero Gaussian random vector. Then,*

$$\det (\text{Cov} (X_1, \dots, X_n)) = \text{Var} (X_1) \text{Var} (X_2 | X_1) \cdots \text{Var} (X_n | X_{n-1}, \dots, X_1).$$

Lemma C.6 *For any square integrable random variable X and σ -algebras $\mathcal{G}_1 \subset \mathcal{G}_2$*

$$\text{Var} (X | \mathcal{G}_1) \geq \text{Var} (X | \mathcal{G}_2).$$

Funding Open access funding provided by University of Oslo (incl Oslo University Hospital).

Data Availability Data sharing not applicable to this article as no datasets were generated or analysed during the current study.

Declarations

Conflict of Interests No potential conflict of interest was reported by the authors.

Open Access This article is licensed under a Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other third party material in this article are included in the article's Creative Commons licence, unless indicated otherwise in a credit line to the material. If material is not included in the article's Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit <http://creativecommons.org/licenses/by/4.0/>.

References

1. Amine, O., Baños, D., Proske, F.: Regularity properties of the stochastic flow of a skew fractional brownian motion. arXiv:1805.04889 (2018)
2. Amine, O., Coffie, E., Harang, F., Proske, F.: A bismut-elworthy-li formula for singular SDE's driven by a fractional brownian motion and applications to rough volatility modeling. arXiv preprint arXiv:1805.11435 (2018)
3. Anari, N., Gurvits, L., Gharan, S., Saberi, A.: Simply exponential approximation of the permanent of positive semidefinite matrices. In: 2017 IEEE 58th Annual Symposium on Foundations of Computer Science (FOCS), pp. 914–925. IEEE (2017)
4. Anderson, T.W.: An introduction to multivariate statistical analysis. Technical report, Wiley New York (1962)
5. Baños, D., Haferkorn, H., Proske, F.: Strong uniqueness of singular stochastic delay equations. arXiv:1707.02271 (2017)
6. Baños, D., Nilssen, T., Proske, F.: Strong existence and higher order fréchet differentiability of stochastic flows of fractional Brownian motion driven SDE's with singular drift. arXiv:1511.02717v2 (2018)
7. Baños, D., Ortiz-Latorre, S., Pilipenko, A., Proske, F.: Strong solutions of SDE's with generalized drift and multidimensional fractional Brownian initial noise. arXiv:1705.01616 (2017)
8. Bauer, M., Meyer-Brandis, T., Proske, F.: Strong solutions of mean-field stochastic differential equations with irregular drift. *Electron. J. Probab.*, vol. 23 (2018)
9. Bogachev, V.: Differentiable measures, and the Malliavin calculus. Number 164 in mathematical surveys and monographs AMS (2010)
10. Borovkov, K., Mishura, Y., Novikov, A., Zhitlukhin, M.: Bounds for expected maxima of Gaussian processes and their discrete approximations. *Stochastics* **89**(1), 21–37 (2017)
11. Catellier, R., Gubinelli, M.: Averaging along irregular curves and regularisation of ODEs. *Stoch. Process. Appl.* **126**(8), 2323–2366 (2016)
12. Cuzick, J., DuPreez, J.: Joint continuity of Gaussian local times. *Annals Probab.*, pp. 810–817 (1982)
13. Da Prato, G., Flandoli, F., Priola, E., Röckner, M.: Strong uniqueness for stochastic evolution equations in hilbert spaces perturbed by a bounded measurable drift. *Annals Probab.* **41**(5), 3306–3344 (2013)
14. Da Prato, G., Malliavin, P., Nualart, D.: Compact families of Wiener functionals. *Comptes Rendus De l'Académie Des Sciences Série 1, Mathématique* **315**(12), 1287–1291 (1992)
15. Davie, A.: Uniqueness of solutions of stochastic differential equations. *Int. Math. Res. Notices* (2007)
16. Decreusefond, L.: Stochastic analysis of the fractional Brownian motion. *Potential Anal.* **10**(2), 177–214 (1999)
17. Engelbert, H.: On the theorem of T. Yamada and S Watanabe. *Stochastics Int. J. Probab. Stochastic Process.* **36**(3–4), 205–216 (1991)
18. Fang, S., Zhang, T.: Stochastic differential equations with non-lipschitz coefficients: I. Pathwise uniqueness and large deviation. *C.R. Acad. Sci. Paris Ser. I* **337**, 737–740 (2003)
19. Flandoli, F.: Random perturbation of PDEs and fluid dynamic models. In: *École d'Été de Probabilités de Saint-Flour XL–2010*, vol 2015. Springer (2011)

20. Flandoli, F., Nilssen, T., Proske, F.: Malliavin differentiability and strong solutions for a class of SDE in Hilbert spaces. Preprint series: pure mathematics (2013)
21. Gyöngy, I., Krylov, N.: Existence of strong solutions for Itô's stochastic equations via approximations. *Probab. Theory Related Fields* **105**(2), 143–158 (1996)
22. Gyöngy, I., Martínez, T.: On stochastic differential equations with locally unbounded drift. *Czechoslov. Math. J.* **51**(4), 763–783 (2001)
23. Haadem, S., Proske, F.: On the construction and Malliavin differentiability of solutions of Lévy noise driven SDE's with singular coefficients. *J. Functional Anal.* **266**(8), 5321–5359 (2014)
24. Krylov, N., Röckner, M.: Strong solutions of stochastic equations with singular time dependent drift. *Probab. Theory Related Fields* **131**(2), 154–196 (2005)
25. Leha, G., Ritter, G.: On solutions to stochastic differential equations with discontinuous drift in Hilbert space. *Math. Ann.* **270**(1), 109–123 (1985)
26. Li, W., Wei, A.: A Gaussian inequality for expected absolute products. *J. Theor. Probab.* **25**(1), 92–99 (2012)
27. Menoukeu-Pamen, O., Meyer-Brandis, T., Nilssen, T., Proske, F., Zhang, T.: A variational approach to the construction and Malliavin differentiability of strong solutions of SDE's. *Math. Ann.* **357**(2), 761–799 (2013)
28. Meyer-Brandis, T., Proske, F.: On the existence and explicit representability of strong solutions of Lévy noise driven SDE's with irregular coefficients. *Commun. Math. Sci.* **4**(1), 129–154 (2006)
29. Meyer-Brandis, T., Proske, F.: Construction of strong solutions of SDE's via Malliavin calculus. *J. Funct. Anal.* **258**(11), 3922–3953 (2010)
30. Mohammed, S., Nilssen, T., Proske, F.: Sobolev differentiable stochastic flows for SDEs with singular coefficients: applications to the transport equation. *Annals Probab.* **43**(3), 1535–1576 (2015)
31. Moser, J.: A rapidly convergent iteration method and nonlinear differential equations. *Uspekhi Matematicheskikh Nauk* **23**(4), 179–238 (1968)
32. Nualart, D.: The Malliavin calculus and related topics. Probability and its applications. Springer second edn. (2006)
33. Nualart, D., Ouknine, Y.: Regularization of differential equations by fractional noise. *Stoch. Process. Appl.* **102**(1), 103–116 (2002)
34. Oldham, K., Spanier, J.: The fractional calculus theory and applications of differentiation and integration to arbitrary order, vol. 111. Elsevier (1974)
35. Pitt, L.D.: Local times for Gaussian vector fields. *Indiana University Math. J.* **27**(2), 309–330 (1978)
36. Pylypenko, A., Tantsyura, M.: Limit theorem for countable systems of stochastic differential equations. *Ukr. Math. J.* **68**(10), 1591–1619 (2017)
37. Samko, S., Kilbas, A., Marichev, O.: Fractional integrals and derivatives: theory and applications Gordo and breach science publishers (1993)
38. Sznitman, A.-S.: Topics in propagation of chaos. In: *Ecole D'Été De Probabilité De Saint-Flour XIX — 1989*, vol. 1464 of Lecture Notes in Mathematics, Chapter 3, pp. 165–251. Springer (1991)
39. Veretennikov, A.: On the strong solutions of stochastic differential equations. *Theory Probab. Appl.* **24**(2), 354 (1979)
40. Yamada, T., Watanabe, S.: On the uniqueness of solutions of stochastic differential equations. *J. Math. Kyoto University* **11**(1), 155–167 (1971)
41. Zvonkin, A.: A transformation of the phase space of a diffusion process that removes the drift. *Math. USSR-Sb.* **22**(1), 129 (1974)